A subriemannian model of visual perception

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- contrast perception
- completion of boundaries
- pop up of the triangle

Contrast perception - retinex model



[Land, '71, '77], [J. M. McCann et al. 2002], [R. Kimmel, M. Elad, D. Shaked, R. Keshet, I. Sobel, 2003], [J-M Morel, A. Beln Petro, C. Sbert, 2010],

Models of the visual cortex with differential instruments



[Hubel Wiesel] [W.C. Hoffmann '89] [Petitot and Tondut '99], [Petitot '03] [S. Zucker ' 05]

[C.- Sarti] [Sarti, C- Petitot '08][Hladky and Pauls '08].[Duits, van Almsick, Franken, ter Haar Romeny '05, '08]

The receptive field of a cortical neuron is the portion of the retina which the neuron reacts to, retinal and receptive profile ψ models the activation. Over each retinal point there is a whole fiber of In presence of a visual stimulus *I*, output of the cells is an integral

$$O(x,y)_{LGN} = \int \phi_{xy}(\xi,\eta) \log I(\xi,\eta) d\xi d\eta \approx \Delta \log I(x,y).$$



The input is propagated via the lateral connectivity.

 $A = \Gamma * O(x, y)_{LGN}$



The output of LGN cells is propagated via The total activity contribution will be modelled as

$$u = \Gamma * \Delta \log(I)$$

We do not recover the initial image, but $u - \log(I)$ is harmonic. Euler Lagrange equation of the functional

$$F_1(u) = \int |\nabla u(\xi,\eta) - \nabla \log(I(\xi,\eta))|^2 d\xi d\eta.$$
(1)





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Simple cells of the visual cortex V1

Simple cells of V1 are strongly oriented cells. They can be represented as a first derivative of a Gaussian bell.

$$\psi_0(\xi,\eta) = \partial_\eta G(\xi,\eta)$$

Over each point (x, y) there is a whole fiber of cells each one sensible to a direction θ . Each cell is identified by 3 parameters The set of cells is obtained by rotation and translation from a fixed one

$$\psi_{(x,y,\theta)}(\xi,\eta) = R_{\theta}T_{x,y}\psi_0(\xi,\eta) = \psi_{\theta}(x-\xi,y-\eta)$$

The action of simple cells and non maxima suppression

In presence of visual signal, the whole ipercolumn fires, the cell sensible to the perceived feature has the highest response.

$$O_{V1}(x,y,\theta) = \int \psi_{x,y,\theta}(\xi,\eta) f(\xi,\eta) d\xi d\eta.$$

lateral connectivity induced

 $X_1 = \cos(\theta)\partial_x + \sin(\theta)\partial_y$ $X_2 = \partial_\theta$



Curves on the LGN plane are lifted to 3D curves. The tangent vector to any lifted curve lies on the plane generated by

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Definition of distance



$$X_1 = \cos(heta)\partial_x + \sin(heta)\partial_y, \quad X_2 = \partial_ heta$$

admissible curves: $\gamma' = \sum_{i=1}^{2} \alpha_i X_i(\gamma)$, metric $||a_1 X_1 + a_2 X_2|| = \sqrt{a_1^2 + a_2^2}$ length $l(\gamma) = \int ||\gamma'(t)|| dt$, $d(\xi, \eta) = inf\{l(\gamma) : \gamma \text{ connects } \xi, \eta\}$.

 $\begin{aligned} X_3 &= [X_1, \partial_{\theta}] = \sin(\theta) \partial_x - \cos(\theta) \partial_y, \\ \text{[Bony], [A.Nagel, E.M.Stein, S.Wainger '85]} \end{aligned}$

Theorem: Chow

 X_1, \dots, X_m are called bracket generating if the generated Lie algebra has dimension n at every point. In this case each couple of points can be connected with integral curves of the vector fields.

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Connectivity kernel and sub-Laplacian operator

A 2D gradient can be defined $\nabla_{V1}f = (X_1, X_2)f$ $f \in C_{V1}^1$ if $\nabla_{V1} = (X_1, X_2)$ is continuous $f \in C_{V1}^2$ if $X_j X_j$ exists and are continous

A Laplace operator is well defined

$$\Delta_{V1} = X_1^2 + X_2^2$$

It has a fundamental solution Γ_{V1}

If u is a solution of $X_1^2 u + X_2^2 u = f \in C^\infty(R^2 \times S^1)$ then $u \in C^\infty$

(SanchezCalle '84, Folland-Stein, Rothschild-Stein '87)

Note that if u is a solution of $\partial_1^2 u + \partial_2^2 u = 0 \in C^{\infty}(\mathbb{R}^3)$ u is not regular along x_3

We are interested in is the geometry induced on the retinal plane by the geometry of V1 in presence of a visual stimulus. The stimulus induces two functions $\rho(x, y)$ and $\theta : \mathbb{R}^2 \to S^1$

Theorem: [Ambrosio Serracassano Vittone], [C- Manfredini]

If the function $f(x, y, s) = s - \theta(x, y)$ is of class C_{V1}^1 then θ is C^1 with respect to the vector field $X_{1,\theta(x,y)}$.

This defines a differential structure on R^2 . Associated differential equation in more general setting: [Capogna, Citti, Manfredini] [Serracassano Vittone] The two output functions define a vector

$$\vec{A}(x,y) =
ho(x,y)(\cos(\theta(x,y)),\sin(\theta(x,y)))$$

The intrinsic gradient is

 $X_{1,\theta}\vec{A}(x,y)$

The associated propagation of the \vec{A} along the connectivity is

$$F_{2} = \int |X_{1,\theta(x,y)}A(\vec{x,y})|^{2} dx dy.$$
⁽²⁾

The first term is

$$\mathcal{L}_1 = \int |\nabla u(x, y) - \nabla Log(I(x, y))|^2 dx dy$$
(3)

and is directly inspired by the Retinex model. The field term is

$$\tilde{\mathcal{L}}_2 = \int |X_{1,\theta(x,y)}A(\vec{x,y})|^2 dx dy.$$

The last term describes the interaction between the particle u(x, y) and the field A(x, y).

$$\mathcal{L}_3 = \int |\nabla u(x,y) - A(x,y)|^2 dx dy.$$
(4)

$$\mathcal{L} = \int |\nabla u - \nabla \log(I)|^2 dx dy + \int |\nabla u - A|^2 dx dy + \int |X_{1\theta} \vec{A}|^2 dx dy \quad (5)$$

Theorem

The functional $\mathcal{L}(u, A)$, is weakly lower semi-continuous in suitable Sobolev spaces. Hence it has a minimum.

The Euler Lagrange Equations are

$$\begin{cases} \Delta u = \frac{1}{2} (\Delta \log(I) + \operatorname{div}_{\theta}(A)) \\ \Delta_{\theta} A = -\nabla u + A. \end{cases}$$
(6)

completion

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$$\begin{cases} \Delta_A A = -\nabla u\\ \Delta u = \frac{1}{2} (\Delta \log(I) + \operatorname{div}_{\theta}(A)) \end{cases}$$
(7)









Multilayer extension of the model

- other features: scale, color, movement
- the invariance of images characterize the space of cells
- the receptive fields and connectivity kernels have the sane invariance properties

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Thank you for your attention

fundamental solution and grouping

Ermentraut-Cowan, Bressloff-Cowan field population model,

$$\frac{\mathrm{d}\boldsymbol{a}}{\mathrm{d}\boldsymbol{t}} = -\lambda\boldsymbol{a} + \sigma \Big(\boldsymbol{\Gamma}_{V1} \ast \boldsymbol{a} - \chi_{\mathcal{O}_{V1} > 0} \Big)$$
(8)

 σ is the transfer function of the population with sigmoidal behavior. Calling to the set Ω where O_{V1} does not vanish,

$$\frac{\mathrm{d}\mathbf{a}(x, y, \theta, t)}{\mathrm{d}t} = -\lambda \mathbf{a}(x, y, \theta, t) + \sigma(\Gamma * \mathbf{a} - 1) \in \Omega$$
(9)

Linearizing the perturbation around a stationary solution:

$$-\lambda a_1(x, y, \theta, t) + \Gamma * a_1 = 0$$

Eigenvalues on the set Ω

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