

Functions of matrices with Kronecker sum structure: decay properties and computation

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Joint work with Michele Benzi, Emory University (USA)

The inverse of the 2D Laplace matrix on the unit square

$$\mathcal{A} := M \otimes I_n + I_n \otimes M, \qquad M = \operatorname{tridiag}(-1, 2, -1)$$

Sparsity pattern:



 $\mathsf{Matrix}\ \mathcal{A}$



 $\mathbf{2}$

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The exponential decay

The classical bound (Demko, Moss & Smith):

If M spd is banded with bandwidth $\beta,$ then

$$|(M^{-1})_{ij}| \le \gamma q^{\frac{|i-j|}{\beta}}$$

where
$$q := \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} < 1$$
 ($\kappa = \operatorname{cond}(M)$) $\gamma := \max\left\{\frac{1}{\lambda_{\min}(M)}, \frac{(1 + \sqrt{\kappa})^2}{2\lambda_{\max}(M)}\right\}$

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If f analytic in region containing spec(M): $|f(M)_{ij}| \leq Cq^{\frac{i-j}{\beta}}$

with C, q depending on $\operatorname{spec}(M)$ and f ($Benzi \ \ Golub, 1999$) Many contributions: Bebendorf, Hackbusch, Benzi, Boito, Razouk, Golub, Tuma, Concus, Meurant, Mastronardi, Ng, Tyrtyshnikov, Nabben, ... Decay bounds for Cauchy-Stieltjes (or Markov-type) functions

$$f(M) = \int_{-\infty}^{0} (M - \omega I)^{-1} \mathrm{d}\gamma(\omega), \quad x \in \mathbb{C} \setminus (-\infty, 0]$$
$$f(x) = z^{-\frac{1}{2}}, f(x) = \frac{\mathrm{e}^{-t\sqrt{x}} - 1}{x}, f(x) = \frac{\log(1+x)}{x}, \dots$$

* Demko etal bound to estimate $|f(M)|_{kt}$ for M spd and β -banded:

$$|M_{kt}^{-\frac{1}{2}}| \le C \left(\frac{\sqrt{\lambda_{\max}} - \sqrt{\lambda_{\min}}}{\sqrt{\lambda_{\max}} + \sqrt{\lambda_{\min}}}\right)^{\frac{|k-t|}{\beta}}$$

(C depends on spec(M))



Estimates for $|M^{-1/2}|_{:,t}$, t = 127, n = 200 (log-scale)

Typical decay plot for $f(\mathcal{A})$

 \mathcal{A} : Laplace operator as before



Much richer structure

In general, $\mathcal{A} = M_1 \oplus M_2 := M_1 \otimes I + I \otimes M_2$, M_1, M_2 banded spd

Decay bounds for the exponential function

Keynote formula : $\exp(M_1 \oplus M_2) = \exp(M_1) \otimes \exp(M_2)$

Let M be spsd, β -banded; $\operatorname{spec}(M) \subset [0, 4\rho]$, $\mathcal{A} = I \otimes M + M \otimes I$. Then $(\exp(-\tau \mathcal{A}))_{kt} = (\exp(-\tau M))_{k_1 t_1} (\exp(-\tau M))_{k_2 t_2}$ for all $t = (t_1, t_2)$ and $k = (k_1, k_2)$ For $\min\{|t_1 - k_1|, |t_2 - k_2|\} \ge \sqrt{4\rho\tau\beta}$ i) For $\rho\tau \ge 1$ and $\sqrt{4\rho\tau} \le |k_j - t_j|/\beta \le 2\rho\tau$, $|(\exp(-\tau M))_{k_j t_j}| \le 10 \exp\left(-\frac{(|k_j - t_j|/\beta)^2}{5\rho\tau}\right)$; ii) For $|k_j - t_j|/\beta \ge 2\rho\tau$,

$$|(\exp(-\tau M))_{k_j t_j}| \le 10 \frac{\exp(-\rho \tau)}{\rho \tau} \left(\frac{e\rho \tau}{\frac{|k_j - t_j|}{\beta}}\right)^{\frac{|k_j - t_j|}{\beta}}$$

(generalization to $\mathcal{A} = I \otimes M_1 + M_2 \otimes I$)

Decay bounds for the exponential function



Left: whole pattern of $\exp(-\mathcal{A})$ Right: Row 56 of $\exp(-\mathcal{A})$ $|\exp(-\mathcal{A})|_{kt}$ with $k = 56 \Rightarrow k = (k_1, k_2) = (6, 5)$ For $t = 50 \Rightarrow t = (t_1, t_2) = (10, 4)$ so that $|k_1 - t_1| \gg 0$ For $t = 45 \Rightarrow t = (t_1, t_2) = (5, 4)$ so that $|k_1 - t_1| \gg 0$ Decay bounds for Laplace-Stieltjes function

$$f(M) = \int_0^\infty e^{-\tau M} \mathrm{d}\alpha(\tau)$$

e.g., $f(x) = x^{-\sigma}$ ($\sigma > 0$), $f(x) = e^{-x}$, $f(x) = e^{1/x}$, $f(x) = (1 - e^{-x})/x$, $f(x) = \log(1 + 1/x)$, ...

• For M spd and $\beta\text{-banded},\ \widehat{M}=M-\lambda_{\min}I$

$$|f(M)|_{k,t} \le \int_0^\infty \exp(-\lambda_{\min}\tau) |(\exp(-\tau\widehat{M}))_{k,t}| \mathrm{d}\alpha(\tau)$$

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$$|f(M)|_{k,t} \le \int_0^\infty \exp(-\lambda_{\min}\tau) |(\exp(-\tau\widehat{M}))_{k,t}| \mathrm{d}\alpha(\tau)$$

• For $\mathcal{A} = M \otimes I + I \otimes M$

$$(f(\mathcal{A}))_{kt} = \int_0^\infty (\exp(-\tau M))_{k_1 t_1} (\exp(-\tau M))_{t_2 k_2} \mathrm{d}\alpha(\tau)$$

then, more precise bounds for specific choices of $d\alpha(\tau)$

An example:
$$f(x) = \frac{1 - e^{-x}}{x}$$

M = tridiag(-1, 4, -1), n = 200



Cauchy-Stieltjes functions of Kronecker sum: $f(\mathcal{A}) = \int_{\Gamma} (\mathcal{A} - \omega I)^{-1} d\gamma(\omega)$

$$e_k^T f(\mathcal{A}) e_t = \int_{\Gamma} e_k^T (\mathcal{A} - \omega I)^{-1} e_t \mathrm{d}\gamma(\omega),$$

where we can write $\mathcal{A}-\omega I=M\otimes I+I\otimes (M-\omega I)$

• For each t, $x_t := (\mathcal{A} - \omega I)^{-1} e_t$, so that $X_t = X_t(\omega) \in \mathbb{C}^{n \times n}$ solution to

 $MX_t + X_t(M - \omega I) = E_t, \qquad x_t = \operatorname{vec}(X_t), \quad e_t = \operatorname{vec}(E_t)$

Then (e.g., Lancaster 1970)

$$X_t = -\int_0^\infty \exp(-\tau M) E_t \exp(-\tau (M - \omega I)) d\tau$$

so that (with $k = (k_1, k_2), t = (t, t_2)$)

 $e_k^T (\omega I - \mathcal{A})^{-1} e_t = e_{k_1}^T X_t e_{k_2} = -\int_0^\infty |\exp(-\tau M)|_{k_1, t_1} |\exp(-\tau (M - \omega I))|_{t_2, k_2} d\tau$

then, more precise bounds for specific choices of f...

Computational strategies

 $f(\mathcal{A})b, \qquad \mathcal{A} = M_1 \otimes I + I \otimes M_2$

Projection strategy for large A: given approximation space range(V),

$$f(\mathcal{A})b \approx \mathcal{V}f(H)(\mathcal{V}^T b), \qquad H = \mathcal{V}^T \mathcal{A}\mathcal{V}$$

• Typical choices: $K_m(\mathcal{A}, b)$, $EK_m(\mathcal{A}, b)$, $RK_m(\mathcal{A}, b)$

(standard, extended, rational Krylov subspaces, and their variants)

Structure not exploited!

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Structure not exploited!

• If $B = b_1 b_2^T$, then structure-aware choice:

$$\mathsf{range}(\mathcal{V}) = K_m(M_1, b_2) \otimes K_m(M_2, b_2)$$
 (or their variants)

that is, $\mathcal{V} = P_m \otimes Q_m$, so that

$$f(\mathcal{A})b \approx x_m^{\otimes} := (P_m \otimes Q_m)z, \qquad z = f(\mathcal{T}_m)(P_m \otimes Q_m)^T b$$

with $\mathcal{T}_m = T_2 \otimes I_m + I_m \otimes T_1$, $T_1 = Q_m^T M_1 Q_m$, $T_2 = P_m^T M_2 P_m$

Advantages of the structured approximation

 $f(\mathcal{A})b \approx x_m^{\otimes} := (P_m \otimes Q_m)z, \quad z = f(\mathcal{T}_m)(P_m \otimes Q_m)^T b$

• No need to explicitly compute $P_m \otimes Q_m$, as

$$(P_m \otimes Q_m)z = \operatorname{vec}(Q_m Z P_m^T)$$

- No need to explicitly compute \mathcal{T}_m if eigencomposition of T_1, T_2 is reliable
- Memory requirements drastically reduced from mn^2 to 2mn
- Accurate approximate solution obtained with much smaller space dimension
- M_1, M_2 not necessarily symmetric

An example from Frommer, Güttel, Schweitzer, 2014

 $f(z) = (e^{10^{-3}\sqrt{z}} - 1)/z$, M = tridiag(-1, 2, -1), b = 1, n = 50

m	$\ f(\mathcal{A})b - x_m\ $	$\ f(\mathcal{A})b - x_m^{\otimes}\ $	$\frac{\ x_m\!-\!x_{m,old}\ }{\ x_m\ }$	$\frac{\ x_m^{\otimes}\!-\!x_{m,old}^{\otimes}\ }{\ x_m^{\otimes}\ }$
4	4.2422e-01	3.9723e-01	1.0000e+00	1.0000e+00
8	2.6959e-01	2.1025e-01	2.2710e-01	2.5313e-01
12	1.7072e-01	1.0365e-01	1.3066e-01	1.2971e-01
16	1.0324e-01	4.2407e-02	8.3444e-02	6.9960e-02
20	5.7342e-02	1.1176e-02	5.4224e-02	3.3969e-02
24	2.7550e-02	4.8230e-04	3.4054e-02	1.0935e-02
28	1.0351e-02	2.8883e-12	1.9296e-02	4.8230e-04
32	3.4273e-03	2.8496e-12	8.3585e-03	1.1366e-13
36	2.2906e-03	2.9006e-12	1.7514e-03	1.4799e-13
	÷			
48	1.8744e-04	2.8235e-12	3.0332e-04	2.5965e-13

An example from Frommer, Güttel, Schweitzer, 2014 $f(z) = (e^{10^{-3}\sqrt{z}} - 1)/z, M = \text{tridiag}(-1, 2, -1), b = 1, n = 100$

m	$\frac{\ x_m - x_{m,old}\ }{\ x_m\ }$	$\frac{\ x_m^{\otimes}\!-\!x_{m,old}^{\otimes}\ }{\ x_m^{\otimes}\ }$
4	1.0000e+00	1.0000e+00
8	2.3942e-01	2.7720e-01
12	1.5010e-01	1.6289e-01
16	1.0716e-01	1.0966e-01
20	8.1062e-02	7.8150e-02
28	5.0347e-02	4.1674e-02
36	3.2507e-02	2.0802e-02
44	2.0667e-02	7.5529e-03
52	1.2194e-02	3.1470e-04
56	8.8234e-03	1.1354e-12
60	5.9194e-03	3.4639e-13

The matrix exponential: $\exp(\mathcal{A})b$

$$\begin{aligned} x_m^{\otimes} &= (P_m \otimes Q_m) \exp(T_2 \otimes I_m + I_m \otimes T_1) (P_m \otimes Q_m)^T b \\ &= (P_m \otimes Q_m) (\exp(T_2) \otimes \exp(T_1)) (P_m \otimes Q_m)^T b \\ &= \operatorname{vec}((Q_m \exp(T_1) Q_m^T b_1) (b_2^T P_m \exp(T_2)^T P_m^T)) \\ &=: \operatorname{vec}(x_m^{(1)} (x_m^{(2)})^T) \end{aligned}$$

Convergence driven by the most slowly converging between $\boldsymbol{x}_m^{(1)}$, $\boldsymbol{x}_m^{(2)}$

An example from graph and network analysis

Graphs: $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ Cartesian product^a: $\mathcal{G} = G_1 \Box G_2$ \Rightarrow Adjacency matrix \mathcal{A} of \mathcal{G} is Kronecker sum of adjacency matrices of G_1 and G_2 Of interest, Total Communicability of \mathcal{G} : $e^{\mathcal{A}}\mathbf{1}$

^a The vertex set of \mathcal{G} is $V_1 \times V_2$; there is an edge between vertices (u_1, u_2) and (v_1, v_2) of \mathcal{G} if either $u_1 = v_1$ and $(u_2, v_2) \in E_2$, or $u_2 = v_2$ and $(u_1, v_1) \in E_1$

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EXAMPLE: Consider $\mathcal{G}_i = G_i \Box G_i$, with each G_i being a Barabasi-Albert graph constructed using the preferential attachment model (pref in Matlab toolbox CONTEST)

number of nodes: $n = 1000, 2000, \dots, 5000$

 \Rightarrow the adjacency matrices of the corresponding Cartesian product graphs G_i have dimension ranging between one and twenty-five millions

 \Rightarrow All the resulting matrices are symmetric indefinite

^a The vertex set of \mathcal{G} is $V_1 \times V_2$; there is an edge between vertices (u_1, u_2) and (v_1, v_2) of \mathcal{G} if either $u_1 = v_1$ and $(u_2, v_2) \in E_2$, or $u_2 = v_2$ and $(u_1, v_1) \in E_1$

An example from graph and network analysis. Cont'd

CPU time to construct an approximation space of dimension m = 30:

n	CPU Time	CPU Time
	$K_m(M_1, b_1)$	$K_m(\mathcal{A}, b)$
1000	0.02662	29.996
2000	0.04480	189.991
3000	0.06545	_
4000	0.90677	_
5000	0.99206	_

An example from graph and network analysis. Cont'd

Convergence history to $\exp(\mathcal{A})b$



Left: case n = 1000

Right: convergence history for all five cases

Convergence for standard Krylov approximation. $\mathcal{A} = M \otimes I + I \otimes M$ λ_{\min} , λ_{\max} extreme eigenvalues of M, and $\hat{\kappa} = \frac{\lambda_{\max} + \lambda_{\min}}{\lambda_{\min} + \lambda_{\min}}$ \star For Cauchy-Stieltjes functions

$$||f(\mathcal{A})v - x_m^{\otimes}|| = \mathcal{O}\left(\exp\left(-\frac{2m}{\sqrt{\widehat{\kappa}}}\right)\right)$$

for m and $\hat{\kappa}$ large enough

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$$\|f(\mathcal{A})v - x_m^{\otimes}\| \le C\left(\frac{\sqrt{\widehat{\kappa}} - 1}{\sqrt{\widehat{\kappa}} + 1}\right)^m$$

with C computable and depending on f and M.

(for $\hat{\kappa}$ large the two bounds are equivalent)

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Faster rate of convergence than for f(A)b and $f(M)b_1$ More bounds for extended and rational Krylov approximation spaces

Conclusions and outlook

- Exploring/Exploiting structure is beneficial
- Generalization to *d*-Kronecker sum is possible, e.g.,

 $\mathcal{A} = M \otimes I \otimes I + I \otimes M \otimes I + I \otimes I \otimes M$

• Possibility of using quasi-sparsity information in applications ? (already done for $f(x) = x^{-1}$)

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