



Spectral Properties
of Saddle Point Linear Systems
and Relations to Iterative Solvers
Part II: Iterative solvers

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Outline of the 3-hour Presentation

- Schematic presentation of certain algebraic preconditioners
(Yesterday)
- **Iterative solvers. Some (hopefully) helpful considerations...**
(Today)
- Spectral analysis of nonsymmetric preconditioners
(Tomorrow)

The standard solvers

Krylov subspace iterative solvers for $\mathcal{M}x = b$:

- \mathcal{M} symmetric and positive definite \Rightarrow (P)CG
- \mathcal{M} symmetric indefinite \Rightarrow (P)MINRES, (P)SYMLQ
- \mathcal{M} nonsymmetric \Rightarrow (P)GMRES, (P)BiCGSTAB(ℓ)

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More specific issues:

- ★ Convergence and clustering
- ★ Stagnation
- ★ Symmetry wrto H -inner product (H spd)
- ★ Symmetry wrto J -inner product (J **not** spd)

Convergence... CG

CG: minimum error method (in energy norm). For \mathcal{M} spd ($x_0 = 0$)

$$\min_{x \in K_k(\mathcal{M}, b)} \|x_\star - x\|_{\mathcal{M}} \leq 2 \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^k \|x_\star\|_{\mathcal{M}}$$

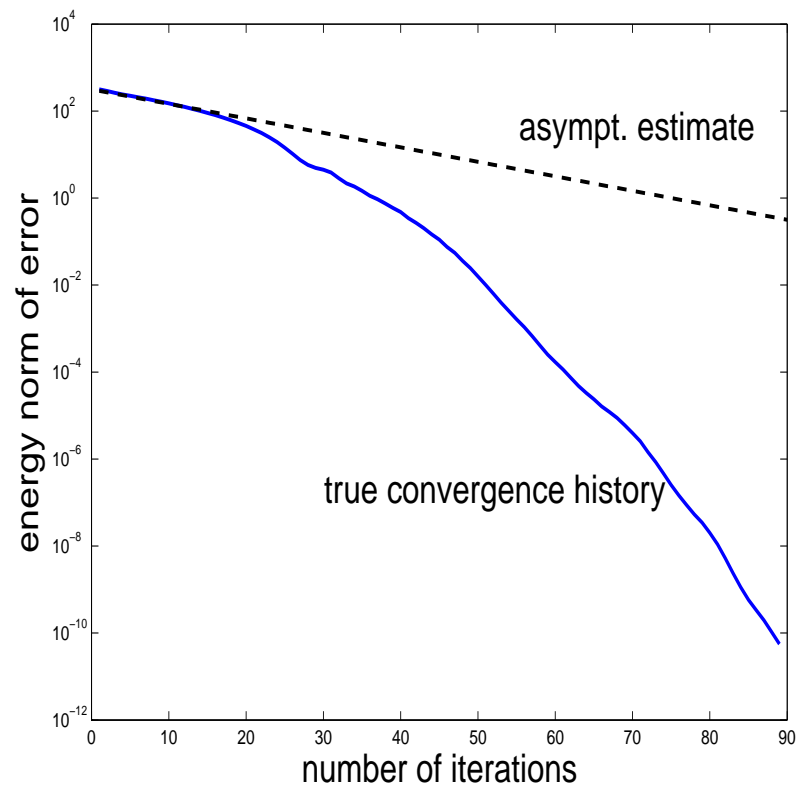
with $\kappa = \lambda_{\max}(\mathcal{M}) / \lambda_{\min}(\mathcal{M})$

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Convergence...

GMRES: minimum residual method

$$\min_{x \in K_k(\mathcal{M}, b)} \|b - \mathcal{M}x\|, \quad (x_0 = 0)$$

x_k minimizer.

For $w \in K_k(\mathcal{M}, v)$, $w = q_{k-1}(\mathcal{M})b$. Then

$$r_k = b - \mathcal{M}x_k = b - \mathcal{M}q_{k-1}(\mathcal{M})b = p_k(\mathcal{M})b$$

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Some “intuitive” consequences:

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Some “intuitive” consequences:

- \mathcal{M} (diag.ble) has **few** distinct eigs \Rightarrow fast convergence
(minimal polynomial of \mathcal{M} wrto b has low degree)
- Spectral clustering is beneficial \Rightarrow select appropriate preconditioner

...and clustering

Will any spectral clustering do the job ?

Residual: $r_k = p_k(\mathcal{M})b$ with $r_0 = b \Rightarrow p_k(0) = 1$

\Rightarrow Spectrum away from zero

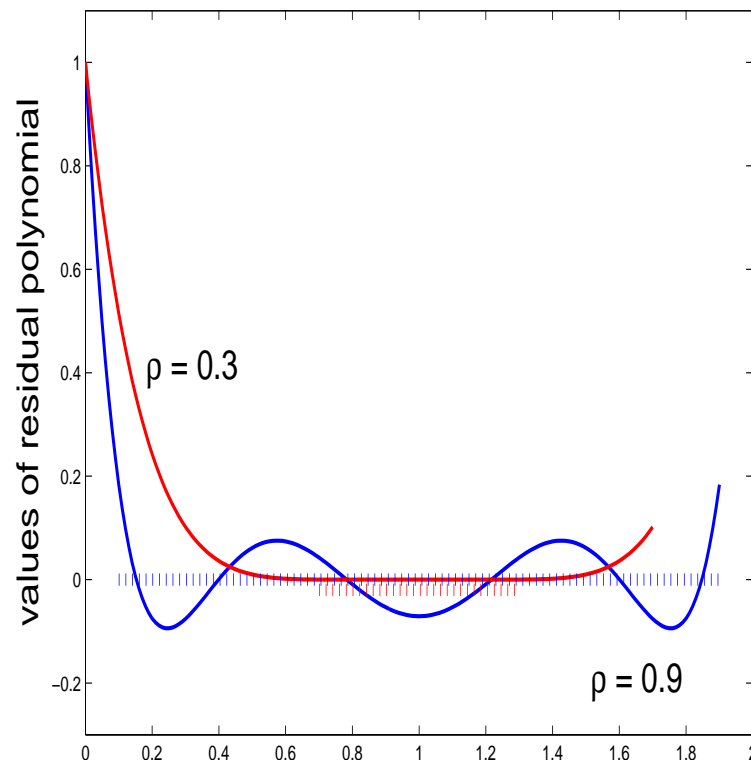
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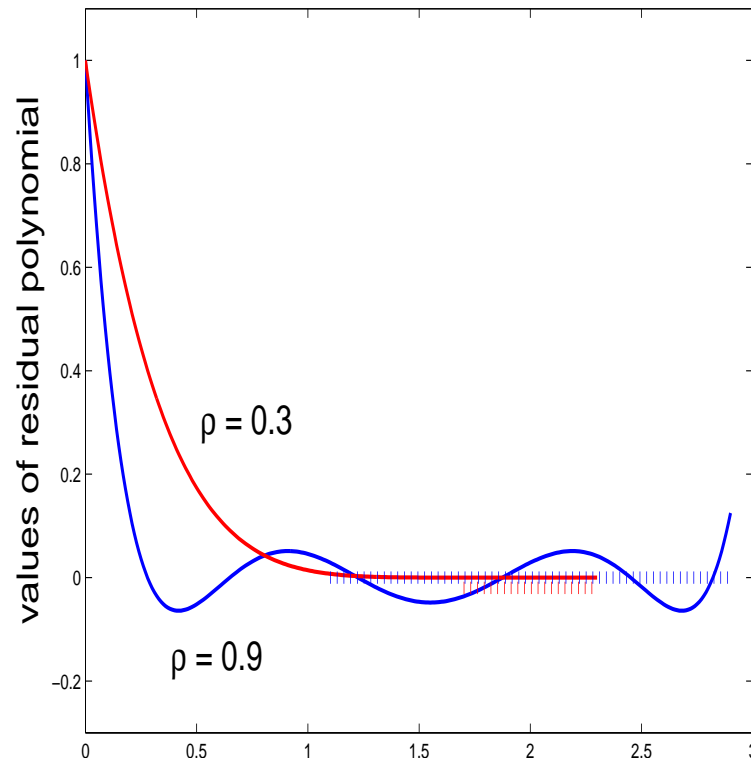
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\Rightarrow Spectrum away from zero

A second example: $\sigma(\mathcal{M}) \subset [2 - \rho, 2 + \rho]$ $p_k(\lambda) :$



...and a good clustering

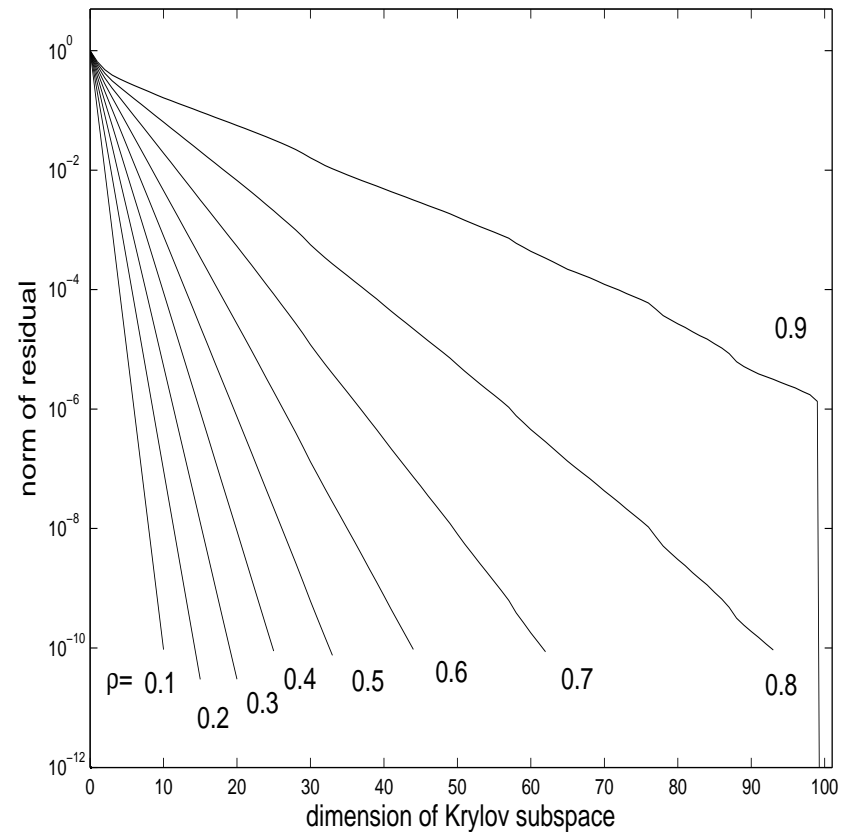
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GMRES rate: ρ^k

For CG, rate: $\left(\frac{\rho}{1 + \sqrt{1 - \rho^2}} \right)^k$

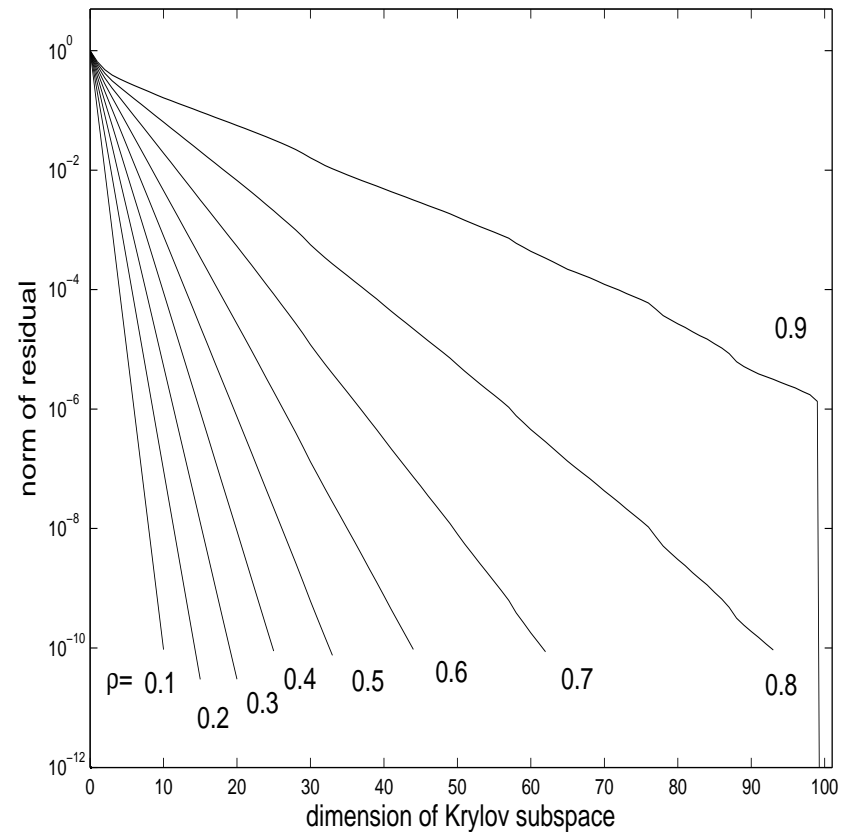


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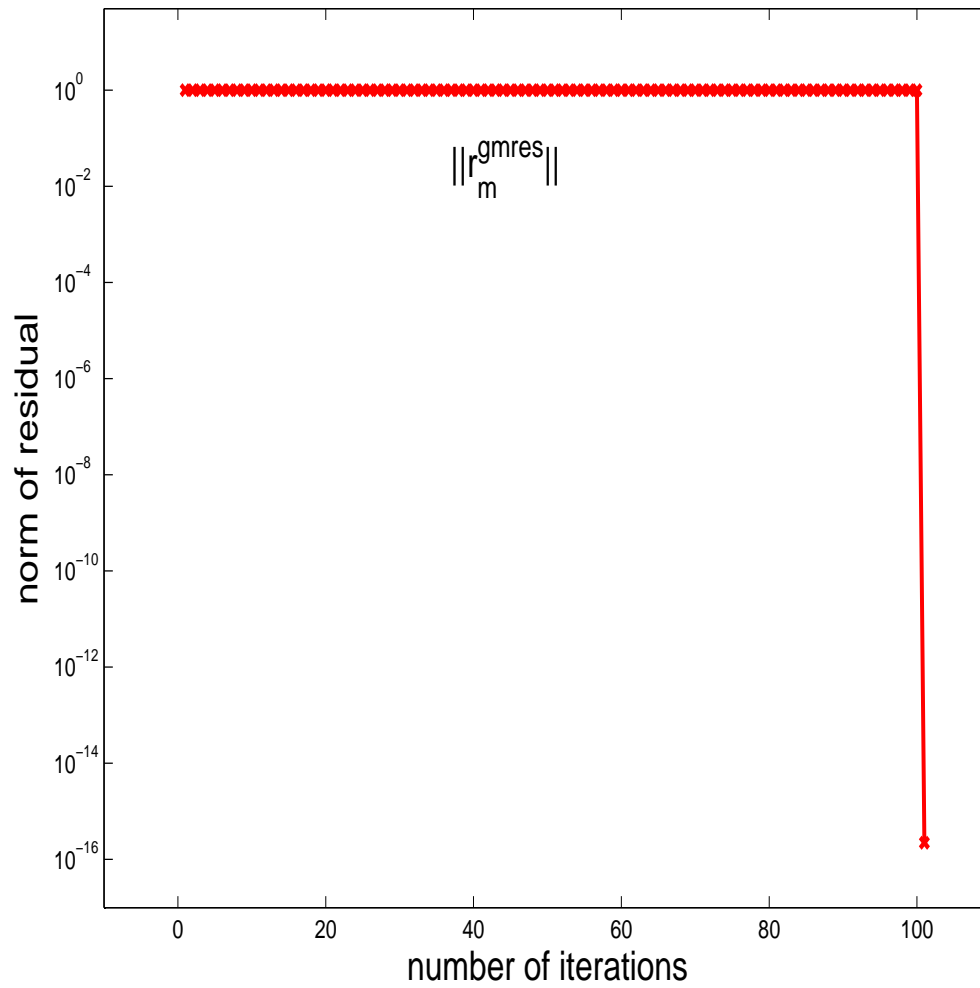
For CG, rate: $\left(\frac{\rho}{1 + \sqrt{1 - \rho^2}} \right)^k$



If $\sigma(\mathcal{M}) \subset D(2, \rho)$, GMRES has rate $\left(\frac{\rho}{2} \right)^k$

Stagnation of GMRES

A is 100×100



Conditions for non-Stagnation of GMRES

If $\alpha = \lambda_{\min}(\frac{1}{2}(\mathcal{M} + \mathcal{M}^T)) > 0$, then

$$\|r_k\| \leq \left(1 - \frac{\alpha^2}{\|\mathcal{M}\|^2}\right)^{\frac{k}{2}} \|b\| < \|b\|$$

Note: \mathcal{M} must be positive real

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Note: \mathcal{M} must be positive real

New condition: Let $H = \frac{1}{2}(\mathcal{M} + \mathcal{M}^T)$, $S = \frac{1}{2}(\mathcal{M} - \mathcal{M}^T)$

If H is nonsingular and $\|SH^{-1}\| < 1$ then there exists (computable) c with $0 < c < 1$ s.t.

$$\|r_2\| \leq c\|b\| < \|b\|$$

(same result for S nonsingular and $\|HS^{-1}\| < 1$)

An additional result

With the same tools:

If $H^2 + S^2$ nonsingular and $\|(HS + SH)(H^2 + S^2)^{-1}\| < 1$ (*)
then there exists c with $0 < c < 1$ s.t.

$$\|r_4\| \leq c\|b\| < \|b\|$$

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An example

$$\mathcal{M} = \begin{bmatrix} A & B^T \\ -B & 0 \end{bmatrix} \quad \begin{array}{l} A \text{ symmetric} \\ B \text{ full rank} \end{array}$$

Note: $H = \frac{1}{2}(\mathcal{M} + \mathcal{M}^T)$ and $S = \frac{1}{2}(\mathcal{M} - \mathcal{M}^T)$ are singular

Assume $A = \mu I$. If μ s.t. (*) holds, then no full stagnation

Changing the inner product. Occurrence

- Minimize quantity in a different inner product
- Monitor convergence in agreement with the continuous problem
- Exploit “non-canonical” symmetries of the coeff. matrix

Symmetry wrto Euclidean inner product

$$\mathcal{M}x = b, \quad \mathcal{M} \text{ spd}$$

Classical CG: $(u, v) = u^T v$

Given x_0

$$r_0 = b - \mathcal{M}x_0, \quad p_0 = r_0$$

for $i = 0, 1, \dots$

$$\alpha_i = \frac{(r_i, r_i)}{(p_i, \mathcal{M}p_i)}$$

$$x_{i+1} = x_i + p_i \alpha_i$$

$$r_{i+1} = r_i - \mathcal{M}p_i \alpha_i$$

$$\beta_{i+1} = \frac{(r_{i+1}, \mathcal{M}p_i)}{(p_i, \mathcal{M}p_i)}$$

$$p_{i+1} = r_i + p_i \beta_{i+1}$$

Symmetry wrto H -inner product (H spd)

$$\mathcal{M}x = b$$

Assume there exists H **spd** such that $H\mathcal{M}$ is also **spd**

H-sym CG: $(u, v)_H = u^T H v$

Given x_0

$$r_0 = b - \mathcal{M}x_0, p_0 = r_0$$

for $i = 0, 1, \dots$

$$\alpha_i = \frac{(r_i, r_i)_H}{(p_i, \mathcal{M}p_i)_H}$$

$$x_{i+1} = x_i + p_i \alpha_i$$

$$r_{i+1} = r_i - \mathcal{M}p_i \alpha_i$$

$$\beta_{i+1} = \frac{(r_{i+1}, \mathcal{M}p_i)_H}{(p_i, \mathcal{M}p_i)_H}$$

$$p_{i+1} = r_i + p_i \beta_{i+1}$$

Application to Saddle-point systems. The “minus-signed” matrix

$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & O \end{bmatrix}$$

★ \mathcal{M}_- is $\mathcal{H}(\gamma)$ -symmetric, with

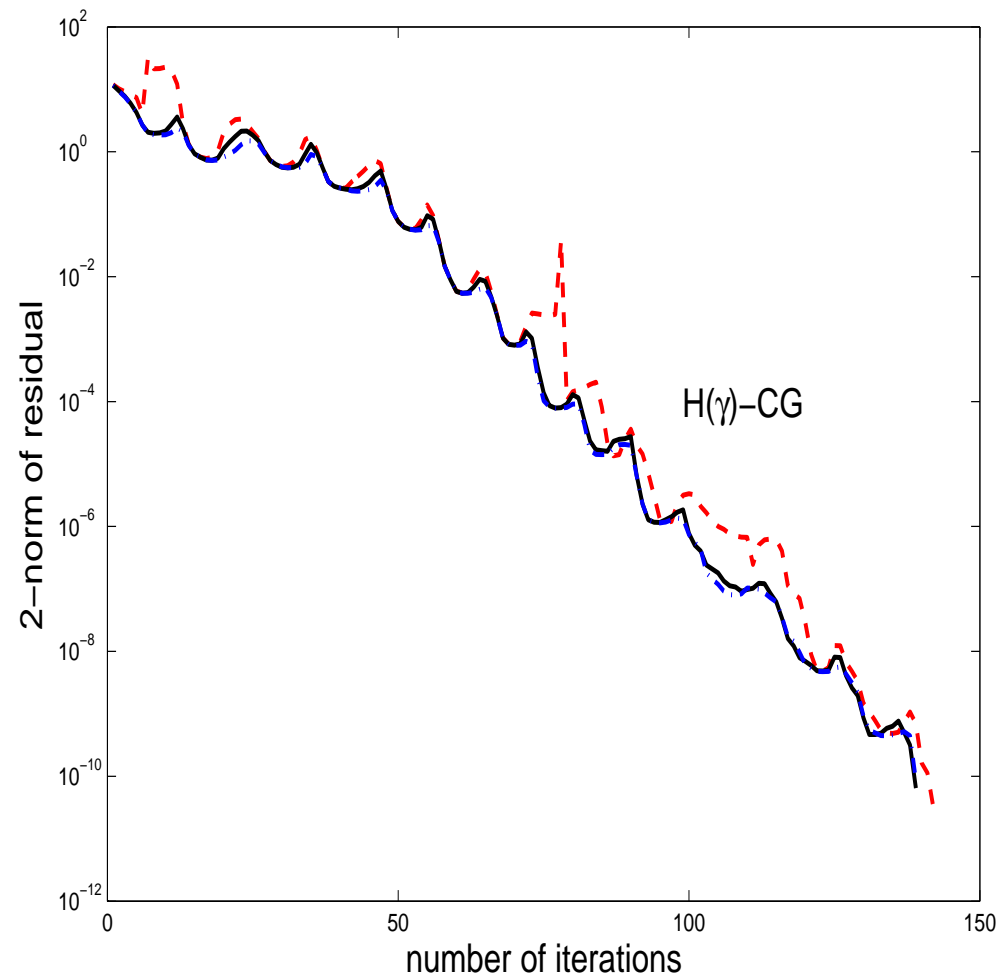
$$\mathcal{H}(\gamma) = \begin{bmatrix} A - \gamma I & B^T \\ B & \gamma I \end{bmatrix}$$

★ Let $\gamma_\star = \frac{1}{2} \lambda_{\min}(A)$.

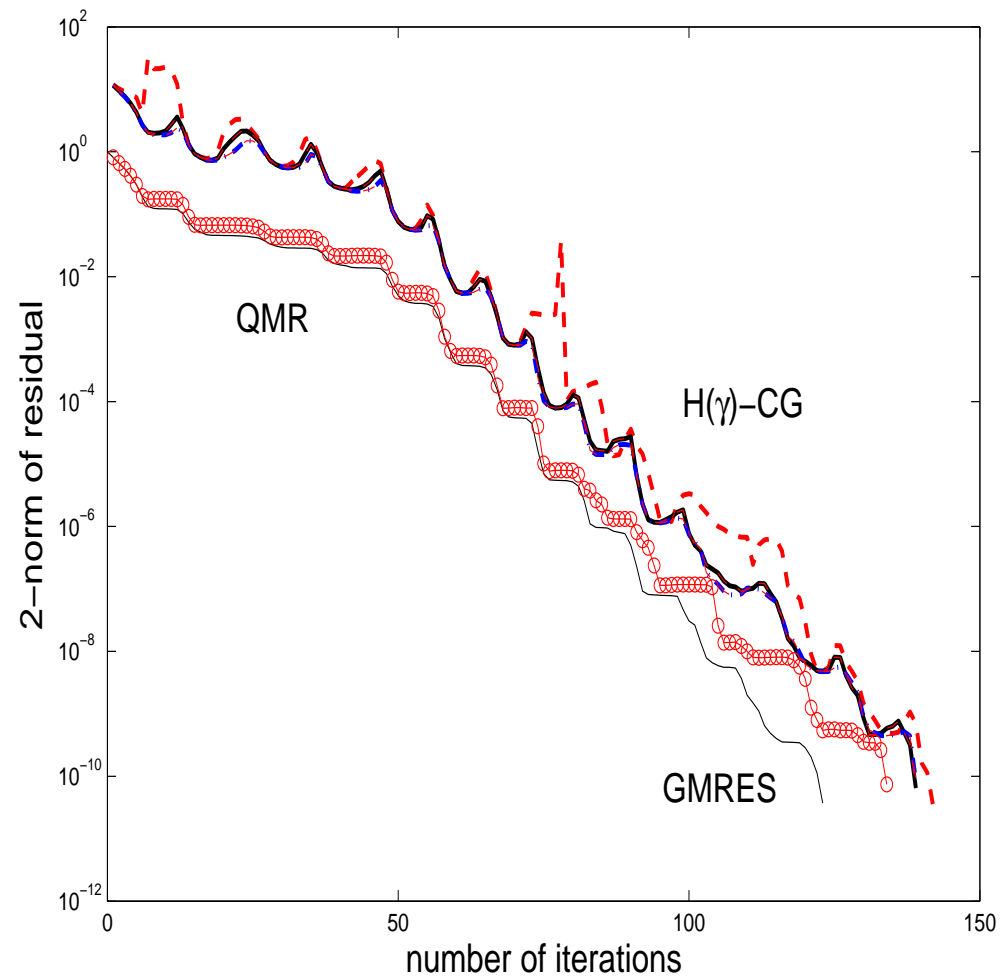
If $\lambda_{\min}(A) > 4\lambda_{\max}(B^T A^{-1} B)$ then $\mathcal{H}(\gamma_\star)$ is spd

★ ...and $\mathcal{H}(\gamma_\star)\mathcal{M}$ is also spd

An example. Stokes with mixed b.c. on the unit square



An example. Stokes with mixed b.c. on the unit square



Symmetry wrto an indefinite inner product

Given J symmetric nonsing, \mathcal{M} is J -symmetric if

$$\mathcal{M}^T J = J \mathcal{M}$$

J -inner product: $(x, y)_J = x^T J y$

Example:

$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & O \end{bmatrix}, \quad J = \begin{bmatrix} I & O^T \\ O & -I \end{bmatrix},$$

Simplification of Lanczos-type procedure (e.g. QMR):

only one matrix-vector product (by \mathcal{M}) per iteration

Another example: Indefinite (Constraint) Preconditioner

$$\mathcal{M} = \begin{bmatrix} A & B^T \\ B & O \end{bmatrix}, \quad \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ B & O \end{bmatrix}$$

- ★ $\mathcal{M}\mathcal{P}^{-1}$ nonsym (nondiagonalizable!)
- ★ $\mathcal{M}\mathcal{P}^{-1}$ is \mathcal{P}^{-1} -symmetric \Rightarrow **Simplified Lanczos**
- ★ Applying \mathcal{P}^{-1} may be expensive... Inexact preconditioning
- ★ Case $C \neq O$ more challenging \Rightarrow Class of preconditioners

Comparing $H(\gamma)$ -CG and Simplified Lanczos

- $H(\gamma)$ -CG involves reality condition
- $H(\gamma)$ -CG involves estimating γ
- $H(\gamma)$ -CG not clear how to precondition
- $H(\gamma)$ -CG convergence clear (exact arithm)