



# Stabilization of second order evolution equations with unbounded feedback with delay

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# Outline of the talk

- The Problem
- Well-posedness
- Energy
  - Energy decay
  - Energy decay to 0
- Exponential stability
- Polynomial stability
- Some examples

# The abstract problem

Let  $H$  be a real Hilbert space with norm and i. p.  $\|\cdot\|$  and  $(\cdot, \cdot)$ ;  $A : D(A) \rightarrow H$  a self-adjoint positive op. with a compact inverse in  $H$ ;  $V := D(A^{\frac{1}{2}})$ . For  $i = 1, 2$ , let  $U_i$  be a real Hilbert space (identified to its dual space) with norm and i. p.  $\|\cdot\|_{U_i}$  and  $(\cdot, \cdot)_{U_i}$  and let  $B_i \in \mathcal{L}(U_i, V')$ .

We consider the closed loop system

$$\begin{cases} \ddot{\omega}(t) + A\omega(t) + B_1 B_1^* \dot{\omega}(t) + B_2 B_2^* \dot{\omega}(t - \tau) = 0, & t > 0 \\ \omega(0) = \omega_0, \dot{\omega}(0) = \omega_1, B_2^* \dot{\omega}(t - \tau) = f^0(t - \tau), & 0 < t < \tau. \end{cases} \quad (1)$$

where  $\tau$  is a positive constant which represents the delay,  $\omega : [0, \infty) \rightarrow H$  is the state of the system.

# Example

The wave equation with internal feedbacks

$$\begin{cases} \frac{\partial^2 \omega}{\partial t^2} - \frac{\partial^2 \omega}{\partial x^2} + \alpha_1 \frac{\partial \omega}{\partial t}(\xi, t) \delta_\xi + \alpha_2 \frac{\partial \omega}{\partial t}(\xi, t - \tau) \delta_\xi = 0, & 0 < x < 1, \\ \omega(0, t) = \omega(1, t) = 0, & t > 0 \\ I.C. \end{cases}$$

where  $\xi \in (0, 1)$ ,  $\alpha_1, \alpha_2 > 0$  and  $\tau > 0$ .

$$H = L^2(0, 1), A : H^2(0, 1) \cap H_0^1(0, 1) \rightarrow H : \varphi \mapsto -\frac{d^2}{dx^2} \varphi$$

$$V = H_0^1(0, 1); U_1 = U_2 = \mathbb{R},$$

$$B_i : \mathbb{R} \rightarrow V' : k \mapsto \sqrt{\alpha_i} k \delta_\xi, i = 1, 2.$$



# Some instabilities

If  $\alpha_1 = 0$ , the previous system is unstable, cfr.

[Datko-Lagnese-Polis 1986].

If  $\alpha_2 > \alpha_1$ , the previous system may be unstable, cfr.

[N.-Pignotti 2006, N.-Valein 2007].

Hence some conditions between  $B_1$  and  $B_2$  have to be imposed to get stability.

# Well-posedness (1)

Let us set  $z(\rho, t) = B_2^* \dot{\omega}(t - \tau\rho)$  for  $\rho \in (0, 1)$  and  $t > 0$ .  
Then (1) is equivalent to

$$\left\{ \begin{array}{l} \ddot{\omega}(t) + A\omega(t) + B_1 B_1^* \dot{\omega}(t) + B_2 z(1, t) = 0, t > 0 \\ \tau \frac{\partial z}{\partial t} + \frac{\partial z}{\partial \rho} = 0, t > 0, 0 < \rho < 1 \\ \omega(0) = \omega_0, \dot{\omega}(0) = \omega_1, z(\rho, 0) = f^0(-\tau\rho), 0 < \rho < 1 \\ z(0, t) = B_2^* \dot{\omega}(t), t > 0. \end{array} \right. \quad (2)$$

# Well-posedness (2)

Therefore the problem can be rewritten as

$$\begin{cases} U' = \mathcal{A}U \\ U(0) = (\omega_0, \omega_1, f^0(-\tau.)), \end{cases} \quad (3)$$

where the operator  $\mathcal{A}$  is defined by

$$\mathcal{A} \begin{pmatrix} \omega \\ u \\ z \end{pmatrix} = \begin{pmatrix} u \\ -A\omega - B_1 B_1^* u - B_2 z(1) \\ -\frac{1}{\tau} \frac{\partial z}{\partial \rho} \end{pmatrix},$$

$$D(\mathcal{A}) := \{(\omega, u, z) \in V \times V \times H^1((0, 1), U_2); z(0) = B_2^* u, \\ A\omega + B_1 B_1^* u + B_2 z(1) \in H\}.$$

# Well-posedness (3)

Denote by  $\mathcal{H}$  the Hilbert space  $\mathcal{H} = V \times H \times L^2((0, 1), U_2)$ .  
Let us now suppose that

$$\exists 0 < \alpha \leq 1, \forall u \in V, \|B_2^* u\|_{U_2}^2 \leq \alpha \|B_1^* u\|_{U_1}^2. \quad (4)$$

We fix a positive real number  $\xi$  such that

$$1 \leq \xi \leq \frac{2}{\alpha} - 1. \quad (5)$$

We now introduce the following inner product on  $\mathcal{H}$ :

$$\left\langle \begin{pmatrix} \omega \\ u \\ z \end{pmatrix}, \begin{pmatrix} \tilde{\omega} \\ \tilde{u} \\ \tilde{z} \end{pmatrix} \right\rangle = (A^{\frac{1}{2}}\omega, A^{\frac{1}{2}}\tilde{\omega}) + (u, \tilde{u}) + \tau\xi \int_0^1 (z(\rho), \tilde{z}(\rho))_{U_2} d\rho$$



# Well-posedness (4)

We show that  $\mathcal{A}$  generates a  $C_0$  semigroup on  $\mathcal{H}$ , by showing that  $\mathcal{A}$  is dissipative in  $\mathcal{H}$  for the above inner product and that  $\lambda I - \mathcal{A}$  is surjective for any  $\lambda > 0$ . By **Lumer-Phillips** Theorem  $\Rightarrow$

**Thm 1.** *Under the assumption (4), for an initial datum  $U_0 \in \mathcal{H}$ , there exists a unique solution  $U \in C([0, +\infty), \mathcal{H})$  to system (3). Moreover, if  $U_0 \in D(\mathcal{A})$ , then*

$$U \in C([0, +\infty), D(\mathcal{A})) \cap C^1([0, +\infty), \mathcal{H}).$$

**Ex. (4)**  $\Leftrightarrow \alpha_2 \leq \alpha_1$ .

# Energy decay

We restrict the ass. (4) to obtain the decay of the energy:

$$\exists 0 < \alpha < 1, \forall u \in V, \|B_2^* u\|_{U_2}^2 \leq \alpha \|B_1^* u\|_{U_1}^2 \quad (6)$$

We define the energy as

$$E(t) := \frac{1}{2} \left( \|A^{\frac{1}{2}} \omega\|_H^2 + \|\dot{\omega}\|_H^2 + \tau \xi \int_0^1 \|B_2^* \dot{\omega}(t - \tau \rho)\|_{U_2}^2 d\rho \right),$$

where  $\xi$  is a positive constant satisfying  $1 < \xi < \frac{2}{\alpha} - 1$ .

**Prop 1.** *For any regular sol. of (1), the energy is non increasing and*

$$E'(t) \sim - \left( \|B_1^* \dot{\omega}(t)\|_{U_1}^2 + \|B_2^* \dot{\omega}(t - \tau)\|_{U_2}^2 \right). \quad (7)$$

**Ex. (6)**  $\Leftrightarrow \alpha_2 < \alpha_1$ .

# Energy decay to 0

**Prop 2.** Assume that (6) holds. Then, for all initial data in  $\mathcal{H}$ ,  
 $\lim_{t \rightarrow \infty} E(t) = 0$  iff

$$\forall (\text{non zero}) \text{ eigenvector } \varphi \in D(A) : B_1^* \varphi \neq 0. \quad (8)$$

**Pf.**  $\Leftarrow$  We closely follow [\[Tucsnak-Weiss 03\]](#).

$\Rightarrow$  We use a contradiction argument. ■

**Rk** This NSC is the same than without delay; therefore, (1) with delay is st. stable (i.e. the energy tends to zero) iff the system without delay (i.e. for  $B_2 = 0$ ) is st. stable. ■

**Ex.**  $\varphi_k = \sin(k\pi \cdot) \forall k \in \mathbb{N}^*$ :

$$(8) \Leftrightarrow \sin(k\pi\xi) \neq 0 \forall k \in \mathbb{N}^* \Leftrightarrow \xi \notin \mathbb{Q}.$$

# Cons. syst. (1)

The stability of (1) is based on some observability estimates for the associated conservative system: We split up  $\omega$  sol of (1) in the form

$$\omega = \phi + \psi,$$

where  $\phi$  is solution of the problem without damping

$$\begin{cases} \ddot{\phi}(t) + A\phi(t) = 0 \\ \phi(0) = \omega_0, \dot{\phi}(0) = \omega_1. \end{cases} \quad (9)$$

and  $\psi$  satisfies

$$\begin{cases} \ddot{\psi}(t) + A\psi(t) = -B_1 B_1^* \dot{\omega}(t) - B_2 B_2^* \dot{\omega}(t - \tau) \\ \psi(0) = 0, \dot{\psi}(0) = 0. \end{cases} \quad (10)$$

# Cons. syst. (2)

By setting  $B = (B_1 \ B_2) \in \mathcal{L}(U, V')$  where  $U = U_1 \times U_2$ ,  $\psi$  is solution of

$$\begin{cases} \ddot{\psi}(t) + A\psi(t) = Bv(t) \\ \psi(0) = 0, \dot{\psi}(0) = 0, \end{cases} \quad v(t) = (-B_1^* \dot{\omega}(t), -B_2^* \dot{\omega}(t - \tau))^{\top}. \quad (11)$$

[Ammari-Tucsnak 01]  $\Rightarrow$  if  $B$  satisfies:  $\exists \beta > 0$  :

$$\lambda \in \{\mu \in \mathbb{C} \mid \Re \mu = \beta\} \rightarrow H(\lambda) = \lambda B^* (\lambda^2 I + A)^{-1} B \in \mathcal{L}(U) \text{ is bd,} \quad (12)$$

then  $\psi$  satisfies

$$\int_0^T \sum_{i=1,2} \|(B_i^* \psi)'\|_{U_i}^2 dt \leq C e^{2\beta T} \int_0^T (\|B_1^* \dot{\omega}(t)\|_{U_1}^2 + \|B_2^* \dot{\omega}(t - \tau)\|_{U_2}^2) dt.$$

**Le 1.** Suppose that the assumption (12) is satisfied. Then the solutions  $\omega$  of (1) and  $\phi$  of (9) satisfy

$$\int_0^T \sum_{i=1,2} \|(B_i^* \phi)'\|_{U_i}^2 dt \leq C e^{2\beta T} \int_0^T (\|B_1^* \dot{\omega}(t)\|_{U_1}^2 + \|B_2^* \dot{\omega}(t - \tau)\|_{U_2}^2) dt,$$

with  $C > 0$  independent of  $T$ .

# Exp. stab. (1)

**Thm 2.** Assume that (6) and (12) are satisfied. If  $\exists T > \tau > 0$  and a constant  $C > 0$  ind. of  $\tau$  s. t. the observability estimate

$$\left\| A^{\frac{1}{2}} \omega_0 \right\|_H^2 + \|\omega_1\|_H^2 \leq C \int_0^T \left\| B_1^* \dot{\phi}(t) \right\|_{U_1}^2 dt \quad (13)$$

holds, where  $\phi$  is solution of (9), then the system (1) is exp. stable. in energy space.

**Pf.** Le 1  $\Rightarrow E(0) - E(T) \geq CE(T) \geq CE(0) + \text{inv. by translation} \Rightarrow \text{exp. stab.}$

**Rk.** Notice that the SC (13) is the same than the case without delay [Ammari-Tucsnak 01]. Therefore, if (12) holds, then (1) is exp. stable if the dissipative system without delay (i.e. with  $B_2 = 0$ ) is exp. stable. ■

# Exp. stab. (2)

Ingham's  $\Leftrightarrow$

**Prop 3.** *Assume that the eigenvalues  $\lambda_k, k \in \mathbb{N}^*$  are simple and that the standard gap condition*

$$\exists \gamma_0 > 0, \forall k \geq 1, \lambda_{k+1} - \lambda_k \geq \gamma_0$$

*holds. Then (13) holds iff*

$$\exists \alpha > 0, \forall k \geq 1, \|B_1^* \varphi_k\|_{U_1} \geq \alpha.$$

**Ex.** Not exp. stable for any  $\xi \in (0, 1)$  because

$$\nexists \alpha > 0 : |\sin(k\pi\xi)| \geq \alpha \quad \forall k.$$

# Pol. stab. (1)

$(\omega_0, \omega_1, f^0(-\tau.)) \in D(\mathcal{A}) \not\Rightarrow \omega_0 \in D(A)$ , we can not use standard interpolation inequalities.

Therefore we need to make the following hypo.:

$\exists m, C > 0 \forall (\omega_0, \omega_1, z) \in D(\mathcal{A}) :$

$$\|\omega_0\|_V^{m+1} \leq C \|(\omega_0, \omega_1, z)\|_{D(\mathcal{A})}^m \|\omega_0\|_{D(A^{\frac{1-m}{2}})} . \quad (14)$$



# Pol. stab. (2)

**Thm 3.** *Let  $\omega$  sol. of (1) with  $(\omega_0, \omega_1, f^0(-\tau \cdot)) \in D(\mathcal{A})$ . Assume that (6), (12) and (14) are verified. If  $\exists m > 0$ , a time  $T > 0$  and  $C > 0$  ind. of  $\tau$  s. t.*

$$\int_0^T \|(B_1^* \phi)'(t)\|_{U_1}^2 dt \geq C(\|\omega_0\|_{D(A^{\frac{1-m}{2}})}^2 + \|\omega_1\|_{D(A^{-\frac{m}{2}})}^2) \quad (15)$$

*holds where  $\phi$  is sol. of (9), then the energy decays polynomially, i.e.,  $\exists C > 0$  depending on  $m$  and  $\tau$  s. t.*

$$E(t) \leq \frac{C}{(1+t)^{\frac{1}{m}}} \left\| (\omega_0, \omega_1, f^0(-\tau \cdot)) \right\|_{D(\mathcal{A})}^2, \forall t > 0.$$

# Pol. stab. (3)

Ingham's  $\Leftrightarrow$

**Prop 4.** *Assume that the eigenvalues  $\lambda_k, k \in \mathbb{N}^*$  are simple and that the standard gap condition*

$$\exists \gamma_0 > 0, \forall k \geq 1, \lambda_{k+1} - \lambda_k \geq \gamma_0$$

*holds. Then (15) holds iff*

$$\exists \alpha > 0, \forall k \geq 1, \|B_1^* \varphi_k\|_{U_1} \geq \frac{\alpha}{\lambda_k^m}.$$

**Ex.** If  $\xi \in S$  (containing the quadratic irrational numbers), then energy decays as  $t^{-1}$ , because  $\exists \alpha > 0 : |\sin(k\pi\xi)| \geq \frac{\alpha}{k} \quad \forall k.$

# Ex 1: Distributed dampings

$$\left\{ \begin{array}{l} \frac{\partial^2 \omega}{\partial t^2} - \frac{\partial^2 \omega}{\partial x^2} + \alpha_1 \frac{\partial \omega}{\partial t}(x, t) \chi_{|I_1} \\ + \alpha_2 \frac{\partial \omega}{\partial t}(x, t - \tau) \chi_{|I_2} = 0 \quad \text{in } (0, 1) \times (0, \infty) \\ \omega(0, t) = \omega(1, t) = 0 \quad t > 0 \\ \omega(x, 0) = \omega_0(x), \quad \frac{\partial \omega}{\partial t}(x, 0) = \omega_1(x) \quad \text{in } (0, 1) \\ \frac{\partial \omega}{\partial t}(x, t - \tau) = f^0(x, t - \tau) \quad \text{in } I_2 \times (0, \tau), \end{array} \right.$$

where  $\chi_{|I} =$  characteristic fct of  $I$ .

We assume that  $0 < \alpha_2 < \alpha_1, \tau > 0$  and

$$I_2 \subset I_1 \subset [0, 1], \quad \exists \delta \in [0, 1], \epsilon > 0 : [\delta, \delta + \epsilon] \subset I_1.$$

# Ex 1 continued

$$\begin{aligned} H &= L^2(0, 1), V = H_0^1(0, 1), D(A) = \\ &H_0^1(0, 1) \cap H^2(0, 1), A : D(A) \rightarrow H : \varphi \mapsto -\frac{d^2}{dx^2}\varphi \\ U_i &= L^2(I_i), B_i : U_i \rightarrow H \subset V' : k \mapsto \sqrt{\alpha_i} \tilde{k} \chi_{|I_i}. \\ B_i^*(\varphi) &= \sqrt{\alpha_i} \varphi|_{I_i} \Rightarrow B_i B_i^*(\varphi) = \alpha_i \varphi \chi_{|I_i} \forall \varphi \in V. \end{aligned}$$

The problem is exponentially stable since  
 $\|B_1^* \sin(k\pi \cdot)\|_{U_1} \geq \alpha_1 \frac{\epsilon}{2}$ , for  $k \gg \gg$ .

# Ex 2: Distributed dampings

Let  $\Omega \subset \mathbb{R}^n$ ,  $n \geq 1$ , with a  $C^2$  bdy  $\Gamma$ . We assume that  $\Gamma = \Gamma_D \cup \Gamma_N$ , with  $\bar{\Gamma}_D \cap \bar{\Gamma}_N = \emptyset$  and  $\Gamma_D \neq \emptyset$ .  $\exists x_0 \in \mathbb{R}^n$  is s. t.  $(x - x_0) \cdot \nu(x) \leq 0$ ,  $\forall x \in \Gamma_D$ .  
Let  $O_2 \subset O_1 \subset \Omega$  s. t.  $\Gamma_N \subset \partial O_1$ .

$$\left\{ \begin{array}{l} \frac{\partial^2 \omega}{\partial t^2} - \Delta \omega + \alpha_1 \frac{\partial \omega}{\partial t}(x, t) \chi_{|O_1} \\ + \alpha_2 \frac{\partial \omega}{\partial t}(x, t - \tau) \chi_{|O_2} = 0 \quad \text{in } \Omega \times (0, \infty), \\ \omega(x, t) = 0 \quad \text{on } \Gamma_D \times (0, \infty), \\ \frac{\partial \omega}{\partial \nu}(x, t) = 0 \quad \text{on } \Gamma_N \times (0, \infty), \\ I.C., \end{array} \right.$$

$$0 < \alpha_2 < \alpha_1, \tau > 0.$$

# Ex 2 continued

$$H = L^2(\Omega), V = H_{\Gamma_D}^1(\Omega),$$

$$A : D(A) \rightarrow H : \varphi \mapsto -\Delta\varphi$$

$$U_i = L^2(O_i), B_i : U_i \rightarrow H \subset V' : k \mapsto \sqrt{\alpha_i} \tilde{k} \chi_{|O_i}.$$

$$B_i^*(\varphi) = \sqrt{\alpha_i} \varphi|_{O_i}.$$

The obs. est. (13) was proved in  
[Lasiacka-Triggiani-Yao 99]  $\Rightarrow$  the pb is  
exponentially stable.

**Rk.** Generalization of [N.-Pignotti 2006] where  
 $O_2 = O_1$ .