

Distance to curves and surfaces in the Heisenberg group

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- Fausto Ferrari, N.A. *Metric normal and distance function in the Heisenberg group*, Math.Z. 2007.
- Fausto Ferrari, N.A. *The Hessian of the distance from a surface in the Heisenberg group*, Ann. Acad. Fenn. 2008.
- Annalisa Baldi, N.A. *From Gruschin to Heisenberg via an isoperimetric problem*, JMAA 2008.
- N.A., Fausto Ferrari, Francescopaolo Montefalcone *CC-distance and metric normal of smooth hypersurfaces in sub-Riemannian Carnot groups*, preprint 2009.
- N.A. *Distance to a curve in the Heisenberg group*, in preparation 2012.
- Fausto Ferrari, N.A. *A variational approximation of the perimeter with second order penalization in the Heisenberg group*, in preparation 2012.

Heisenberg group and CC geometry

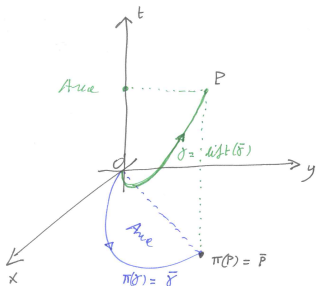
- Group: $\mathbb{H} = \mathbb{R}^3 \ni (x, y, t)$,
 $(x_1, y_1, t_1) \cdot (x_2, y_2, t_2) = (x_1 + x_2, y_1 + y_2, t_1 + t_2 + 1/2(x_1y_2 - y_1x_2))$.
- Lie algebra: $X = \partial_x - \frac{y}{2}\partial_t$, $Y = \partial_y + \frac{x}{2}\partial_t$, $T = [X, Y] = \partial_t$:
 $\mathfrak{h} = \text{span}\{X, Y, T\}$.
- Stratification: $H = V_1 = \{X, Y\}$, $V = V_2 = [V_1, V_2] = \text{span}\{T\}$.
- The CC length of a curve: $\gamma : [a, b] \rightarrow \mathbb{H}$, $\dot{\gamma} = \alpha X + \beta Y + mT$ is

CC length

$$\text{length}(\gamma) = \int_a^b \sqrt{\alpha(\tau)^2 + \beta(\tau)^2 + \infty^2 \cdot m(\tau^2)} d\tau.$$

- γ is *horizontal* if $m \equiv 0$ (iff $\text{length}(\gamma) < \infty$, iff $\dot{\gamma} \in H$).
- $d(P, Q) = \inf \{\text{length}(\gamma) : \gamma(a) = P, \gamma(b) = Q\}$.
- d is a distance on \mathbb{H} , realized by the length of *geodesics*.
- $d(O, (x, y, t)) \approx ((x^2 + y^2)^2 + t^2)^{1/2}$.
- $\gamma = (x, y, t)$ is horizontal iff $dt = \frac{xdy - ydx}{2}$: we can give an interpretation of length in terms of areas.

$$\Delta t = \int_{\pi(\gamma)} \frac{xdy - ydx}{2} = \iint_{\text{int}(\pi(\gamma))} dx dx = \text{Area}(\text{int}(\pi(\gamma))).$$



$$\text{length}(\delta) = \text{Euc-length}(\pi(\delta))$$

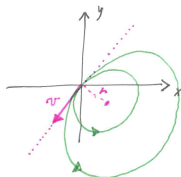
geodesic between O and P :

given A_{area} and $O\tilde{P}$
 find $\tilde{\gamma}$ in \mathbb{R}^2 joining O and \tilde{P}
 making an area A_{area} with $O\tilde{P}$,
shortest with the above;

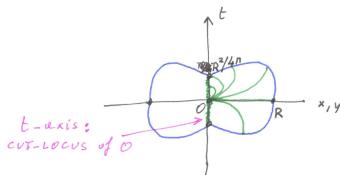
DIDO's problem.

Geodesics:

- They are horizontal curves projecting to circles;
- They are length minimizing along the length of the circle.



Ball of radius R in \mathbb{H}^1



- For each horizontal v at P there are ∞^1 geodesics η leaving P such that $\dot{\eta}(0) = v$.
- For each $\epsilon > 0$ there is a geodesic leaving O which is length minimizing for a time $< \epsilon$.
- If $\eta(0) = P$, $\dot{\eta}(0) = v$ and η projects to a circle having radius $r > 0$ we write $\eta = \eta_{P,v,1/r}$.

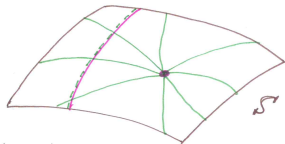
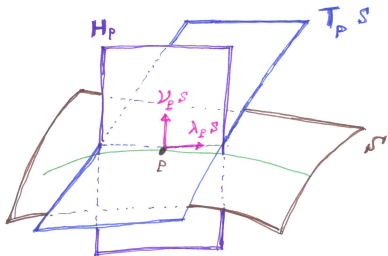
Metric \rightarrow Hausdorff measures \mathcal{H}^a ($a > 0$) and dimensions $\dim_{\mathcal{H}}$.

- $\dim_{\mathcal{H}}(\mathbb{H}) = 4$ and $d\mathbb{H}^4 = dx dy dt$ is the Haar measure of \mathbb{H} .
- $\dim_{\mathcal{H}}(t\text{-axis}) = 2$ and $d\mathbb{H}_{t\text{-axis}}^2 = dt$ is the Haar measure of the t -axis.
- $\dim_{\mathcal{H}}(x\text{-axis}) = 1$ and $d\mathbb{H}_{x\text{-axis}}^1 = dx$ is the Haar measure of the x -axis.
- $\dim_{\mathcal{H}}(x, t\text{-plane}) = 3$ and $d\mathbb{H}_{x,t\text{-plane}}^3 = dx dt$ is the Haar measure of the x, t -plane.
- $\dim_{\mathcal{H}}(x, y\text{-plane}) = 3$ and $d\mathbb{H}_{x,y\text{-plane}}^3 = \sqrt{x^2 + y^2} dx dy$.
- Explanation: $\lambda \cdot (x, y, t) = (\lambda x, \lambda y, \lambda^2 t)$ defines the right dilations (length-areas, stratification...).

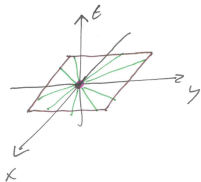
S a smooth orientable surface in \mathbb{H} ; $H_P = \text{span}\{X_P, Y_P\}$; $T_P S$: the plane tangent to S at P .

- $C \in S$ is *characteristic* iff $H_C = T_C S$.
- Characteristic points form a small set ($\dim_{\mathcal{H}}(\text{Characteristic set}(S)) \leq 2$).
- Simply connected compact S 's have characteristic points.
- If $P \notin \text{Characteristic set}(S)$ then $\dim(H_P \cap T_P S) = 1$, hence
- $S \setminus \text{Characteristic set}(S)$ is foliated by horizontal curves.
- $H_P \ominus (H_P \cap T_P S)$ is the *direction normal* to S at P .
- If $\langle \cdot, \cdot \rangle$ makes X, Y into a orthonormal system for H , $H_P \ominus (H_P \cap T_P S) = \text{span}\{\nu_P\}$ with $\langle \nu_P, \nu_P \rangle = 1$.
- $\pm \nu_P$ is the *horizontal vector normal* to S at its *noncharacteristic point* P .
- Choose ν_P together with an orientation of S .

Surfaces in \mathbb{H}



S is ruled by horizontal curves but for its (small) characteristic set



- S : a smooth surface in \mathbb{H} , $S = \partial\Omega$, Ω open and bounded, ν inward horizontal normal.
- $d_S(P) : \inf\{d(P, Q) : Q \in S\}$.
- **Problem I:** smoothness properties of d_S ?
- **Problem II:** given Q in S , what can we say about the set $\mathcal{N}_Q S = \{P \in \mathbb{H} : d_S(P) = d(P, Q)\}$?
- $\mathcal{N}_Q S$ is the *metric normal to S at Q* .

The quest for the metric normal

Metric normal in

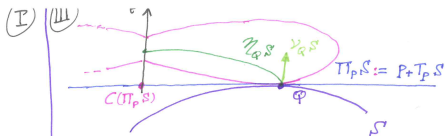
- Riemannian geometry:



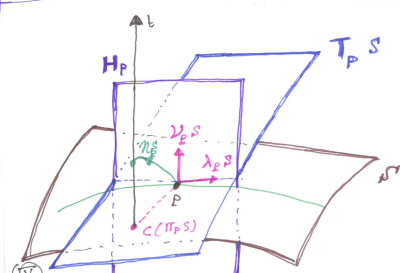
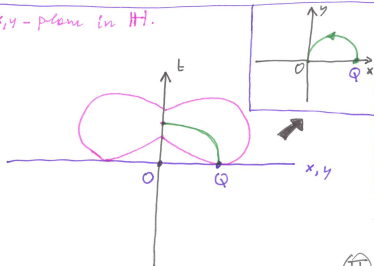
- Sub-Riemannian geometry:



How do we find the right one?



x, y -plane in \mathbb{H}^2 .



Metric normal to a smooth surface

Theorem (A., F. Ferrari)

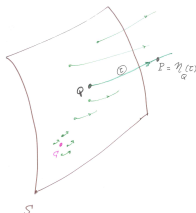
S a C^1 surface in \mathbb{H} and $Q \in S$. Then

$\mathcal{N}_Q S \subseteq \eta_{Q, \nu_Q S, 2/d(Q, C(\Pi_Q S))}$ is a subarc containing Q .

If S is $C^{1,1}$ and Q in noncharacteristic, the Q in the interior of the arc.
If Q is characteristic, then $\mathcal{N}_Q S = \{Q\}$.

The *imaginary curvature* of S at Q is $\kappa_S(Q) = 2/d(Q, C(\Pi_Q S))$: the curvature of the geodesic metrically normal to S at Q .

The *cut-locus* of S contains the endpoints of the geodesics' arcs $\mathcal{N}_Q S$ as Q varies on S .



$$\mathcal{E}xp_S : S \times \mathbb{R} \rightarrow \mathbb{H}, (Q, \tau) \mapsto (\mathcal{N}_S Q)(\tau) = P.$$

- $d_S(P) = |\tau|$.

- Signed distance from S : $\delta_S(P) = \tau := \begin{cases} d_S(P) & \text{if } P \in \Omega \\ -d_S(P) & \text{if } P \notin \Omega \end{cases}$

Theorem (A., F. Ferrari)

- There \mathcal{U} open in $(S \setminus \{\text{characteristic set}\}) \times \mathbb{R}$ such that $\mathcal{E}xp_S : \mathcal{U} \rightarrow \mathbb{H}$ is a diffeomorphism (if S is $C^{1,1}$).
- If $P \rightarrow [\mathcal{E}xp_S]^{-1}(P) = (Q, \tau)$, $\tau = \delta_S(P)$ and $\nabla_H \delta_S \in C(\mathcal{U})$.

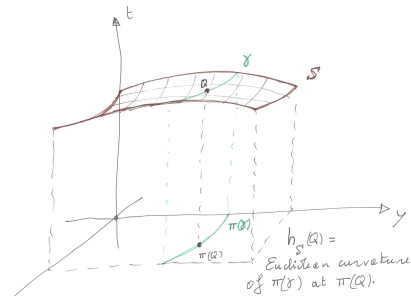
$\nabla_H f = Xf \cdot X + Yf \cdot Y$ is the horizontal gradient.

The horizontal Hessian of δ_S

- The *mean curvature* of S at Q is $h_S(Q) = \Delta_h \delta_S(Q)$, where $\Delta_h = XX + YY$.
- The horizontal Hessian of $f: \mathbb{H} \rightarrow \mathbb{R}$ is $\text{Hess}_h f = \begin{pmatrix} XXf & YXf \\ XYf & YYf \end{pmatrix}$.
- Consider the matrices $I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and $J = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$.

Theorem (A., F. Ferrari)

$$\text{Hess}_h \delta_S = \lambda_S \otimes \lambda_S \cdot (h_S I + \kappa_S J).$$



- $\gamma : I = (a, b) \rightarrow \mathbb{H}, \dot{\gamma} = \alpha X + \beta Y + mT$
- $d_\gamma(P) = \inf\{d(P, Q) : Q \in \gamma(I)\}$.
- **Problem I:** smoothness properties of d_γ ?
- **Problem II:** given Q in $\gamma(I)$, what can we say about the set $\mathcal{N}_Q\gamma = \{P \in \mathbb{H} : d_\gamma(P) = d(P, Q)\}$?

Straight lines.

Suppose γ is a straight line (i.e. a coset of a one-parameter subgroup of \mathbb{H}).

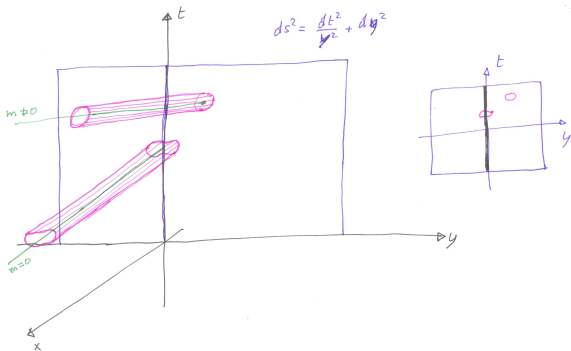
Horizontal and non-horizontal lines behave much differently.

- ℓ_m : straight line through O with $\dot{\ell} = X + mT$.
- For P_1, P_2 in \mathbb{H} : $\ell_m \cdot P_1$ and $\ell_m \cdot P_2$ are metrically parallel: $d(Q_1, \ell_m \cdot P_2)$ is independent of $Q_1 \in \ell_m \cdot P_1$.
- Quotient metric on \mathbb{H}/ℓ_m : $(\ell_m \cdot P_1, \ell_m \cdot P_1) \mapsto d(\ell_m \cdot P_1, \ell_m \cdot P_1)$.

Projecting Heisenberg onto Grushin

Theorem (A., A. Baldi)

- 1 $(\mathbb{H}/\ell_m, d)$ is isometric to the *Grushin plane* (\mathbb{R}^2, ds^2) ,
 $ds^2 = du^2 \frac{dv^2}{u^2}$.
- 2 ℓ_m projects to a point of the critical line $u = 0$ iff it is horizontal (iff $m = 0$).



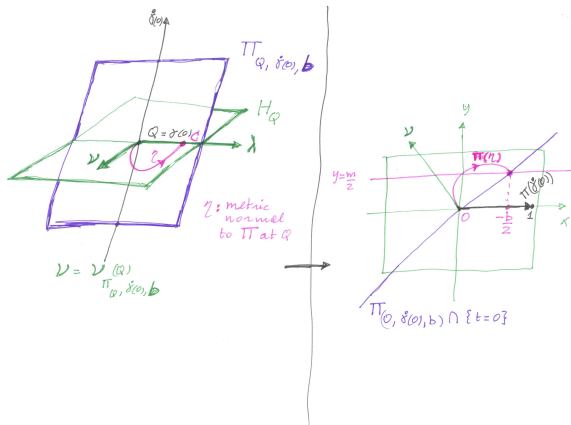
Corollary

- If ℓ_m is not horizontal, then d_{ℓ_m} is smooth in a neighborhood of ℓ_m .
- If ℓ_m is horizontal, then d_{ℓ_m} is not smooth in any neighborhood of ℓ_m .

This leaves open the problem of understanding $\mathcal{N}_{\ell_m} Q$: the surface metrically normal to ℓ_m at Q .

The quest for the surface metrically normal to a curve: non-horizontal case.

$\gamma : I = (a, b) \rightarrow \mathbb{H}, \dot{\gamma} = \alpha X + \beta Y + mT, m \neq 0$ pointwise, $\alpha^2 + \beta^2 \equiv 1$.



$\eta = \eta_{Q, b}, b \in \mathbb{T}$.

Regularity of the distance function.

The above construction allows one to construct a *metric exponential map*

Exponential

$$\mathcal{E}xp_\gamma : \gamma(I) \times \mathbb{T} \times \mathbb{R}^+ \rightarrow \mathbb{H}, \mathcal{E}xp_\gamma(Q, b, \tau) = \eta_{Q,b}(\tau).$$

Theorem

- The map $\mathcal{E}xp_\gamma$ is invertible near $\gamma(I)$ and $d_\gamma(\mathcal{E}xp_\gamma(Q, b, \tau)) = \tau$ for small τ .
- d_γ is smooth (C^1 if γ is C^2) near $\gamma(I)$.

The case of horizontal curves is quite the opposite.

Theorem

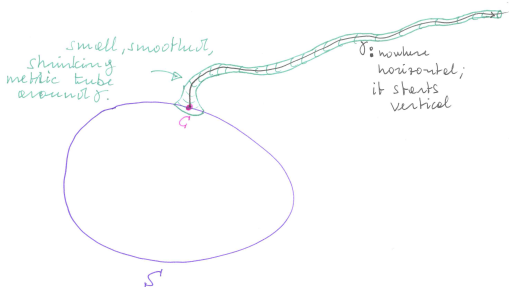
If γ is a horizontal curve, then for all Q in $\gamma(I)$ and $\epsilon > 0$ there is P such that $d(Q, P) < \epsilon$, but d_γ is not differentiable (in the Euclidean case) at P .

An application of the positive result.

Theorem

Let $S = \partial\Omega$ be a compact C^2 surface in \mathbb{H} and fix $\epsilon > 0$. Then there exists a C^2 surface $S_\epsilon = \text{partial}\Omega_\epsilon$ **without characteristic points** such that:

- $\mathcal{H}^4(\Omega_\epsilon \Delta \Omega) < \epsilon$;
- $|\mathcal{H}^3(S_\epsilon) - \mathcal{H}^3(S)| < \epsilon$.



An application of the negative result's proof.

Theorem

Let $E \subset \mathbb{H}$ be a closed subset and let $\text{Cut-locus}(E)$ be its cut-locus. Then for all open metric balls B in \mathbb{H} , $B \cap \text{Cut-locus}(E)$ **is not** an arc of a horizontal curve.

Since the cut-locus can not either have isolated points, we have the following guess.

Conjecture

For each metric open ball B in \mathbb{H} intersecting the cut-locus of E it must be $\mathcal{H}^2(B \cap \text{Cut-locus}(E)) \geq 0$.

- Initial motivation: extending a result of Fonseca e Mantegazza from \mathbb{R}^n to \mathbb{H} (Bruno Franchi's question).
- Some of the above is proved for more general Carnot groups in joint work with Ferrari e Montefalcone.
- A more general study of the cut-locus might be interesting.
- Ferrari e Valdinoci have interesting applications of some of the above to some nonlinear PDE's.
- Most results await sharp regularity versions of themselves.

Happy birthday Gianni!