An observer-oriented approach to topological data analysis Part 1: From comparing subsets of  $\mathbb{R}^n$  to studying metric spaces of functions

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# Outline



Our basic questions

Assumptions in our model

Mathematical setting and theoretical results

Experiments



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We are interested in these questions:

- Is there a general metric model to compare data in TDA?
- What is the role of the observer in this comparison?
- How could we approximate the observer's judgement by means of a computable metric?



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# Assumptions in our model



Truth often depends on the observer's perspective:



Multiple perspectives are unavoidable! ( $\rightarrow$  Sergio's talk)

# Assumptions in our model



We will make these assumptions:

- 1. No object can be studied directly. Any object is knowable just through acts of measurement made by an observer.
- 2. Any act of measurement can be represented as a function defined on a topological space.
- 3. The observer usually acquires measurement data by applying operators to the functions describing them.



# An example of operator





### Choice of the operators



- The observer cannot usually choose the functions representing the measurement data, but can often choose the operators that will be applied to those functions.
- The choice of the operators <u>reflects the invariances</u> that are relevant for the observer.
- In some sense we could state that the observer can be represented as a collection of (suitable) operators, endowed with the invariance he/she has chosen.

In this talk we will confine ourselves to examine the case of operators that act on a space  $\Phi$  of continuous functions and take  $\Phi$  to itself.

# From comparing sets in $\mathbb{R}^n$ to comparing functions $\mathbf{V}^*$

Instead of directly focusing on the objects we are interested in, we focus on the filtering functions describing the measurements we make on them, and on the "glasses" that we use "to observe" the filtering functions. In our approach, these "glasses" are G-operators which act on the filtering functions.

These operators represent the observer's perspective.

In some sense, the family of operators defines the observer.





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# Natural pseudo-distance associated with a group $G\mathbf{V}$

First of all we need a definition allowing us to formalize the comparison of data in our model.

#### Definition

Let X be a compact space. Let G be a subgroup of the group Homeo(X) of all homeomorphisms  $f: X \to X$ . The pseudo-distance  $d_G: C^0(X, \mathbb{R}) \times C^0(X, \mathbb{R}) \to \mathbb{R}$  defined by setting

$$d_G(\varphi, \psi) = \inf_{g \in G} \max_{x \in X} |\varphi(x) - \psi(g(x))|$$

is called the natural pseudo-distance associated with the group G.

In plain words, the definition of  $d_G$  is based on the attempt of finding the best correspondence between the functions  $\varphi, \psi$  by means of homeomorphisms in G.

# G-invariant non-expansive operators



### The natural pseudo-distance $d_G$ represents our ground truth.

Unfortunately,  $d_G$  is difficult to compute. This is also a consequence of the fact that we can easily find subgroups G of Homeo(X) that cannot be approximated with arbitrary precision by smaller finite subgroups of G (i.e. G = group of rigid motions of  $X = \mathbb{R}^3$ ).

Nevertheless, in this talk we will show that  $d_G$  can be approximated with arbitrary precision by means of a **DUAL** approach based on persistent homology and *G*-invariant non-expansive operators.

This research is based on an ongoing joint research project with Grzegorz Jabłoński (Jagiellonian University - Poland)

# G-invariant non-expansive operators



Let us consider the following objects:

- A triangulable space X with nontrivial homology in degree k.
- A set Φ of continuous functions from X to ℝ, that contains the set of all constant functions.
- A topological subgroup G of Homeo(X) that acts on Φ by composition on the right.
- A subset *F* of the set *F*<sup>all</sup>(Φ, G) of all non-expansive G-operators from Φ to Φ.

# The operator space $\mathscr{F}^{all}(\Phi, G)$



In plain words,  $F \in \mathscr{F}^{\mathrm{all}}(\Phi,G)$  means that

1.  $F: \Phi \rightarrow \Phi$ 

- 2.  $F(\phi \circ g) = F(\phi) \circ g$ . (F is a G-operator)
- 3.  $\|F(\varphi_1) F(\varphi_2)\|_{\infty} \le \|\varphi_1 \varphi_2\|_{\infty}$ . (*F* is non-expansive)

### The operator F is not required to be linear.

Some simple examples of F, taking  $\Phi$  equal to the set of all continuous functions  $\varphi : \mathbf{S}^1 \to \mathbb{R}$  and G equal to the group of all rotations of  $\mathbf{S}^1$ :

- $F(\phi) :=$  the constant function  $\psi : \mathbf{S}^1 \to \mathbb{R}$  taking the value max $\phi$ ;
- $F(\varphi)$  defined by setting  $F(\varphi)(x) := \max\left\{\varphi\left(x \frac{\pi}{8}\right), \varphi\left(x + \frac{\pi}{8}\right)\right\};$
- $F(\varphi)$  defined by setting  $F(\varphi)(x) := \frac{1}{2} \left( \varphi \left( x \frac{\pi}{8} \right) + \varphi \left( x + \frac{\pi}{8} \right) \right).$



# The pseudo-metric $D_{\text{match}}^{\mathscr{F}}$

For every  $arphi_1, arphi_2 \in \Phi$  we set

 $D^{\mathscr{F}}_{\mathrm{match}}(\varphi_1,\varphi_2) := \sup_{F \in \mathscr{F}} d_{match}(\rho_k(F(\varphi_1)),\rho_k(F(\varphi_2)))$ 

where  $\rho_k(\psi)$  denotes the persistent Betti number function (i.e. the rank invariant) of  $\psi$  in degree k, while  $d_{match}$  denotes the usual bottleneck distance that is used to compare the persistence diagrams associated with  $\rho_k(F(\varphi_1))$  and  $\rho_k(F(\varphi_2))$ .

#### Proposition

 $D^{\mathscr{F}}_{match}$  is a G-invariant and stable pseudo-metric on  $\Phi$ .

The *G*-invariance of  $D^{\mathscr{F}}_{match}$  means that for every  $\varphi_1, \varphi_2 \in \Phi$  and every  $g \in G$  the equality  $D^{\mathscr{F}}_{match}(\varphi_1, \varphi_2 \circ g) = D^{\mathscr{F}}_{match}(\varphi_1, \varphi_2)$  holds.



We observe that the pseudo-distance  $D_{\text{match}}^{\mathscr{F}}$  and the natural pseudo-distance  $d_G$  are defined in quite different ways.

In particular, the definition of  $D_{\text{match}}^{\mathscr{F}}$  is based on persistent homology, while the natural pseudo-distance  $d_G$  is based on the group of homeomorphisms G.

In spite of this, the following statement holds:

Theorem

If  $\mathscr{F} = \mathscr{F}^{all}(\Phi, G)$ , then the pseudo-distance  $D^{\mathscr{F}}_{match}$  coincides with the natural pseudo-distance  $d_G$  on  $\Phi$ .

# Our main idea



The previous theorem suggests to study  $D_{\text{match}}^{\mathscr{F}}$  instead of  $d_G$ .

To this end, let us choose a finite subset  $\mathscr{F}^*$  of  $\mathscr{F},$  and consider the pseudo-metric

$$D^{\mathscr{F}^*}_{\mathrm{match}}(\varphi_1,\varphi_2):=\max_{F\in\mathscr{F}^*}d_{\mathrm{match}}(
ho_k(F(\varphi_1)),
ho_k(F(\varphi_2)))$$

for every  $\varphi_1, \varphi_2 \in \Phi$ .

Obviously,  $D_{\text{match}}^{\mathscr{F}^*} \leq D_{\text{match}}^{\mathscr{F}}$ .

Furthermore, if  $\mathscr{F}^*$  is dense enough in  $\mathscr{F}$ , then the new pseudo-distance  $D_{\mathrm{match}}^{\mathscr{F}^*}$  is close to  $D_{\mathrm{match}}^{\mathscr{F}}$ .

In order to make this point clear, we need the next theoretical result.

# Compactness of $\mathscr{F}^{all}(\Phi, G)$



The following result holds:

#### Theorem

If  $\Phi$  is a compact metric space with respect to the sup-norm, then  $\mathscr{F}^{all}(\Phi,G)$  is a compact metric space with respect to the distance d defined by setting

$$d(F_1,F_2) := \max_{\varphi \in \Phi} \|F_1(\varphi) - F_2(\varphi)\|_{\infty}$$

for every  $F_1, F_2 \in \mathscr{F}$ .

# Approximation of $\mathscr{F}^{all}(\Phi, G)$



This statement follows:

### Corollary

Assume that the metric space  $\Phi$  is compact with respect to the sup-norm. Let  $\mathscr{F}$  be a subset of  $\mathscr{F}^{all}(\Phi, G)$ . For every  $\varepsilon > 0$ , a finite subset  $\mathscr{F}^*$  of  $\mathscr{F}$  exists, such that

$$\left|D_{match}^{\mathscr{F}^*}(arphi_1,arphi_2)\!-\!D_{match}^{\mathscr{F}}(arphi_1,arphi_2)
ight|\leq arepsilon$$

for every  $\varphi_1, \varphi_2 \in \Phi$ .

This corollary implies that the pseudo-distance  $D^{\mathscr{F}}_{match}$  can be approximated computationally, at least in the compact case.



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Let us check what happens in practice



# A RETRIEVAL EXPERIMENT ON A DATASET OF CURVES

# Let us check what happens in practice



We have considered

- 1. a dataset of 10000 functions from  $S^1$  to  $\mathbb{R}$ , depending on five random parameters (#);
- 2. these three invariance groups:
  - the group Homeo( $S^1$ ) of all self-homeomorphisms of  $S^1$ ;
  - the group  $R(S^1)$  of all rotations of  $S^1$ ;
  - the trivial group  $I(S^1) = \{id\}$ , containing just the identity of  $S^1$ .

Obviously,

Homeo(
$$S^1$$
)  $\supset R(S^1) \supset I(S^1)$ .

(#) For  $1 \le i \le 10000$  we have set  $\bar{\varphi}_i(x) = r_1 \sin(3x) + r_2 \cos(3x) + r_3 \sin(4x) + r_4 \cos(4x)$ , with  $r_1, ..., r_4$  randomly chosen in the interval [-2, 2]; the *i*-th function in our dataset is the function  $\varphi_i := \bar{\varphi}_i \circ \gamma_i$ , where  $\gamma_i(x) := 2\pi (\frac{x}{2\pi})^{r_5}$  and  $r_5$  is randomly chosen in the interval  $[\frac{1}{2}, 2]$ .



The choice of  $Homeo(S^1)$  as an invariance group implies that the following two functions are considered equivalent. Their graphs are obtained from each other by applying a horizontal stretching. Also shifts are accepted as legitimate transformations.





The choice of  $R(S^1)$  as an invariance group implies that the following two functions are considered equivalent. Their graphs are obtained from each other by applying a rotation of  $S^1$ . Stretching is not accepted as a legitimate transformation.



Finally, the choice of  $\mathbf{I}(\mathbf{S}^1) = \{id\}$  as an invariance group means that two functions are considered equivalent if and only if they coincide everywhere.

What happens if we decide to assume

that the invariance group is the group  $Homeo(S^1)$ 

of all self-homeomorphisms of  $S^{1?}$ 

If we choose  $G = \text{Homeo}(S^1)$ , to proceed we need to choose a finite set of non-expansive Homeo $(S^1)$ -operators. In our experiment we have considered these three non-expansive Homeo $(S^1)$ -operators:

• 
$$F_0 := id$$
 (i.e.,  $F_0(\phi) := \phi$ );

• 
$$F_1 := -id$$
 (i.e.,  $F_0(\phi) := -\phi$ );

•  $F_2(\varphi) :=$  the constant function  $\psi : \mathbf{S}^1 \to \mathbb{R}$  taking the value  $\frac{1}{5} \cdot \sup\{-\varphi(x_1) + \varphi(x_2) - \frac{1}{2}\varphi(x_3) + \frac{1}{2}\varphi(x_4) - \varphi(x_5) + \varphi(x_6)\},\$  $(x_1, \dots, x_6)$  varying among all the counterclockwise 6-tuples on  $\mathbf{S}^1$ .

This choice produces the Homeo $(S^1)$ -invariant pseudo-distance

$$D^{\mathscr{F}^*}_{match}(\varphi_1,\varphi_2) := \max_{0 \leq i \leq 2} d_{match}(
ho_k(F_i(\varphi_1)),
ho_k(F_i(\varphi_2))).$$

### An important remark



It is important to use several operators. The use of just one operator still produces a pseudo-distance  $D_{match}^{\mathscr{F}^*}$  that is invariant under the action of the group G, but this choice is far from guaranteeing a good approximation of the natural pseudo-distance  $d_G$ .

As an example in the case  $G = \text{Homeo}(\mathbf{S}^1)$ , if we use just the identity operator (i.e., we just apply classical persistent homology), we cannot distinguish these two functions  $\varphi_1, \varphi_2 : \mathbf{S}^1 \to \mathbb{R}$ , despite the fact that they are different for  $d_G$ :



Here is a query (in **blue**), and the first four retrieved functions (in **black**):







(b) φ<sub>381</sub>, dist: 0.0541687



(c) φ<sub>7776</sub>, dist: 0.0984192

(d) φ<sub>6214</sub>, dist: 0.10376

Let's have a closer look at the query and at the first retrieved function:

Here is the query:



Here is the first retrieved function with respect to  $D_{match}^{\mathscr{F}^*}$ :



Here is the query function after aligning it to the first retrieved function by means of a shift (in **red**).

The first retrieved function is represented in **black**.

The figure shows that the retrieved function is approximately equivalent to the query function, by applying a shift and a stretching.



Here is the query function after aligning it to the first four retrieved functions by means of a shift (in **red**).

The first four retrieved functions are represented in **black**.







(b)  $\varphi_{381}$ , dist: 0.0541687







(d) φ<sub>6214</sub>, dist: 0.10376



If we choose  $G = R(\mathbf{S}^1)$ , in order to proceed we need to choose a finite set of non-expansive  $R(\mathbf{S}^1)$ -operators. Obviously, since  $F_0$ ,  $F_1$  and  $F_2$  are Homeo( $\mathbf{S}^1$ )-invariant, they are also  $R(\mathbf{S}^1)$ -invariant. In our experiment we have added these five non-expansive  $R(\mathbf{S}^1)$ -operators (which are not Homeo( $\mathbf{S}^1$ )-invariant) to  $F_0$ ,  $F_1$  and  $F_2$ :

• 
$$F_3(\varphi)(x) := \max\{\varphi(x), \varphi(x+\pi)\}$$

• 
$$F_4(\varphi)(x) := \frac{1}{2} \cdot \left(\varphi(x) + \varphi(x + \frac{\pi}{4})\right)$$

• 
$$F_5(\varphi)(x) := \max\{\varphi(x), \varphi(x+\pi/10), \varphi(x+\frac{2\pi}{10}), \varphi(x+\frac{3\pi}{10})\}$$

• 
$$F_6(\varphi)(x) := \frac{1}{3} \cdot (\varphi(x) + \varphi(x + \frac{\pi}{3}) + \varphi(x + \frac{\pi}{4}))$$
  
•  $F_7(\varphi)(x) := \frac{1}{3} \cdot (\varphi(x) + \varphi(x + \frac{\pi}{3}) + \varphi(x + \frac{2\pi}{3}))$ 

This choice produces the 
$$R(S^1)$$
-invariant pseudo-distance

$$D_{match}^{\mathscr{F}^*}(\varphi_1,\varphi_2) := \max_{0 \le i \le 7} d_{match}(\rho_k(F_i(\varphi_1)),\rho_k(F_i(\varphi_2))).$$

The results of an experiment: the group  $R(\mathbf{S}^1)$ 







(a) φ<sub>5566</sub>, dist: 0.333405





(b) φ<sub>8454</sub>, dist: 0.422668



(d) φ<sub>4426</sub>, dist: 0.46463


Here is the query:



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Here is the first retrieved function with respect to  $D_{match}^{\mathscr{F}^*}$ :





Here is the query function after aligning it to the first retrieved function by means of a shift (in **red**).

The first retrieved function is represented in **black**.

The figure shows that the retrieved function is approximately equivalent to the query function, via a shift.



Here is the query function after aligning it to the first four retrieved functions by means of a shift (in **red**).

The first four retrieved functions are represented in **black**.





<sup>(</sup>b)  $\varphi_{8454}$ , dist: 0.422668





(d) φ<sub>4426</sub>, dist: 0.46463

Finally, what happens if we decide to assume that the invariance group is the group  $I(S^1) = \{id\}$ containing only the identity of  $S^{1}$ ? This means that the "perfect" retrieved function should coincide with our query.

If we choose  $G = I(S^1) = \{id\}$ , in order to proceed we need to choose a finite set of non-expansive operators (obviously, every operator is an  $I(S^1)$ -operator).

In our experiment we have considered these three non-expansive operators (which are not  $R(S^1)$ -operators):

- $F_8(\varphi)(x) := \sin(x)\varphi(x)$
- $F_9(\varphi)(x) := \frac{\sqrt{2}}{2}\sin(x)\varphi(x) + \frac{\sqrt{2}}{2}\cos(x)\varphi(x+\frac{\pi}{2})$
- $F_{10}(\varphi)(x) := \sin(2x)\varphi(x)$

We have added  $F_8$ ,  $F_9$ ,  $F_{10}$  to  $F_1, \ldots, F_7$ .

This choice produces the pseudo-distance

$$D_{match}^{\mathscr{F}^*}(\varphi_1,\varphi_2):=\max_{0\leq i\leq 10}d_{match}(\rho_k(F_i(\varphi_1)),\rho_k(F_i(\varphi_2))).$$

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Here is a query (in **blue**), and the first four retrieved functions (in **black**):





(c) φ389, dist: 0.617218



(b)  $\varphi_{7001}$ , dist: 0.598145



(d) φ<sub>5723</sub>, dist: 0.617981

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Let's have a closer look at the query and at the first retrieved function:

Here is the query:



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Here is the first retrieved function with respect to  $D_{match}^{\mathscr{F}}$ :





The first retrieved function is represented in **black**.

As expected, no aligning shift is necessary here.

The figure shows that the retrieved function is approximately equal to the query function.





The figure shows that the retrieved functions are approximately coinciding with the query function.



## An open problem



We have proven that if  $\Phi$  is compact, then  $D^{\mathscr{F}}_{match}$  can be approximated computationally.

However, this result does not say which set of operators allows for both a good approximation of  $D^{\mathscr{F}}_{match}$  and a fast computation.

Further research is needed in this direction.

## Conclusions



In this talk we have supported these statements:

- Shape comparison is based on acts of measurement made by an observer. The acts of measurement can be represented as a function defined on a topological space X. The observer can be seen as a collection of *G*-invariant operators, applied to the functions describing the data.
- These functions can be compared by means of the natural pseudo-distance associated with any subgroup G of Homeo(X).
- Persistent homology can be used to approximate the natural pseudo-metric  $d_G$ . This can be done by means of a method that is based on non-expansive *G*-operators. This method is stable with respect to noise.

For more information about the approach described in these slides use the following link: <u>http://arxiv.org/pdf/1312.7219v3.pdf</u>.



