

Deep learning and group equivariant (non-expansive) operators - Theory.

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(Joint work with D. Giorgi (ISTI-CNR) and N. Quercioli (Univ. of Bologna))

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Outline

A mathematical framework for data comparison

The natural pseudo-distance d_G

Group equivariant non-expansive operators

Persistent homology

The link between the natural pseudo-distance and persistent homology via GNEOs

Building new GNEOs

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The content of this talk

In this talk we will illustrate the topological theory introduced in this paper:

Mattia G. Bergomi, Patrizio Frosini, Daniela Giorgi, Nicola Quercioli, *Towards a topological-geometrical theory of group equivariant non-expansive operators for data analysis and machine learning*, Nature Machine Intelligence, vol. 1, n. 9, pages 423–433 (2 September 2019).

Full-text access to a view-only version of this paper is available at the link <https://rdcu.be/bP6HV>.

The role of equivariant operators in machine learning

- As pointed out by several authors (Mallat, Poggio, Rosasco...) the role of equivariant operators in machine learning is getting more and more important.
- Data comparison is almost never a direct process: it is usually mediated by the comparison of new data produced by agents/observers, i.e. by the comparison of the action of agents on the original data.
- Equivariant operators (and networks of equivariant operators) can model agents acting on data.

At the very beginning, data are usually given by *measurements*.

What does MEASUREMENT mean?

Before proceeding, we have to determine what measurements are in our mathematical model.

Measurement is the assignment of a number to a characteristic of an object or event, which can be compared with other objects or events.

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According to this definition, measurements (and hence data) can be seen as functions φ associating a real number $\varphi(x)$ with each point x of a set X of characteristics. (This definition admits a natural extension to vector-valued functions but, for the sake of simplicity, we will treat here the case of scalar-valued functions). If we wish to develop a theory that can be applied in real situations, we need stability with respect to noise. This naturally leads us to use a topology on the set Φ of possible measurements on a set X .

Assumptions in our model

We will make these assumptions:

- Data are represented as functions defined on topological spaces, since only data that are stable w.r.t. a certain criterion (e.g., with respect to some kind of measurement) can be considered for applications, and stability requires a topological structure.
- Data cannot be studied in a direct and absolute way. They are only knowable through acts of transformation made by an agent/observer. From the point of view of data analysis, only the pair (data, agent) matters. In general terms, agents are not endowed with purposes or goals: they are just ways and methods to transform data. Acts of measurement are a particular class of acts of transformation.

Assumptions in our model

We will make these assumptions:

- Agents are described by the way they transform data while respecting some kind of invariance. In other words, any agent can be seen as a group equivariant operator acting on a function space.
- Data similarity depends on the output of the considered agent.

A topology on the space X of characteristics

A natural topology on the set Φ of possible measurements is the one induced by the L^∞ metric $D_\Phi(\varphi_1, \varphi_2) := \|\varphi_1 - \varphi_2\|_\infty$.

Since measurements are the central concept in our approach, the topology on X is derived from D_Φ .

We define this pseudometric D_X on X by setting

$$D_X(x_1, x_2) := \sup_{\varphi \in \Phi} |\varphi(x_1) - \varphi(x_2)|.$$

In plain words: Two points $x_1, x_2 \in X$ are close to each other if and only if every measurement in Φ takes similar values at those points.

Every function in Φ is continuous

In this talk we will assume that the topological space Φ is compact.

EXAMPLE 1. $X := S^1 = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$, $\Phi =$ set of all 1-Lipschitzian functions from S^1 to $[0, 1]$.

EXAMPLE 2. $X := [-1, 1] \times [-1, 1]$, $\Phi =$ set of all functions from X to $[0, 1]$ that are 1-Lipschitzian both in $X_1 := [-1, 0] \times [-1, 1]$ and in $X_2 := (0, 1] \times [-1, 1]$. Please observe that the functions in Φ can be discontinuous at the points (x, y) with $x = 0$, with respect to the Euclidean topology on X . However, every function in Φ is continuous with respect to the topology induced by D_X .

Theorem

*If Φ is compact, then the topology induced by D_X coincides with the **initial topology** on X , i.e. the coarsest topology on X such that each function $\varphi \in \Phi$ is continuous.*

Homeomorphisms with respect to D_X

The next step consists in understanding what a Φ -preserving homeomorphism with respect to D_X is (a bijection $g : X \rightarrow X$ is called Φ -preserving if $\varphi \circ g \in \Phi$ and $\varphi \circ g^{-1} \in \Phi$ for every $\varphi \in \Phi$).

Theorem

The Φ -preserving homeomorphisms with respect to D_X are exactly the Φ -preserving bijections from X to X .

Let us now consider a group G of homeomorphisms from X to X , whose elements preserve Φ by right composition.

We will say that (Φ, G) is a PERCEPTION PAIR.

A pseudo-metric on our Φ -preserving group G

If a perception pair (Φ, G) is given, we can define the function

$$D_G(g_1, g_2) = \sup_{\varphi \in \Phi} D_\varphi(\varphi \circ g_1, \varphi \circ g_2) \quad (0.1)$$

from $G \times G$ to \mathbb{R} .

The function D_G is a pseudo-metric on G .

Please note that also the definition of D_G is inherited from the definition of D_φ .

Theorem

G is a topological group with respect to the pseudo-metric topology and the action of G on Φ through right composition is continuous.

Compactness of X and G

We recall that we are assuming Φ compact.

Theorem

If X is complete then it is also compact with respect to D_X .

Theorem

If G is complete then it is also compact with respect to D_G .

In this talk we will assume that X and G are complete, and hence compact.

A mathematical framework for data comparison

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Our ground truth: the natural pseudo-distance d_G

Definition

The pseudo-distance $d_G : \Phi \times \Phi \rightarrow \mathbb{R}$ is defined by setting

$$d_G(\varphi_1, \varphi_2) = \inf_{g \in G} D_\Phi(\varphi_1, \varphi_2 \circ g).$$

It is called the **natural pseudo-distance** associated with the group G .

If $G = \{Id : x \mapsto x\}$, then d_G equals the sup-norm distance D_Φ on Φ .
If G_1 and G_2 are groups of Φ -preserving self-homeomorphisms of X and $G_1 \subseteq G_2$, then the definition of d_G implies that

$$d_{G_2}(\varphi_1, \varphi_2) \leq d_{G_1}(\varphi_1, \varphi_2) \leq D_\Phi(\varphi_1, \varphi_2)$$

for every $\varphi_1, \varphi_2 \in \Phi$.

Our ground truth: the natural pseudo-distance d_G

The natural pseudo-distance d_G is our ground truth: it describes the differences that the agent/observer can perceive between the measurements in Φ with respect to the equivalence expressed by the group G .

A possible objection: *“The use of the concept of homeomorphism makes the natural pseudo-distance d_G difficult to apply. For example, in shape comparison two similar objects can be non-homeomorphic, hence this pseudo-metric cannot be applied to real problems.”*

A possible objection

Answer: the homeomorphisms do not concern the “objects” but the space X where the measurements are made.

- For example, if we are interested in grey level images, the domain of our measurements can be modelled as the real plane and each image can be represented as a function from \mathbb{R}^2 to \mathbb{R} . Therefore, the space X is not given by the (possibly non-homeomorphic) objects displayed in the pictures, but by the topological space \mathbb{R}^2 .
- If we make two CAT scans, the topological space X is always given by an helix turning many times around a body, and no requirement is made about the topology of such a body.

In other words, it is usually legitimate to assume that the topological space X is determined only by the measuring instrument we are using to get our measurements.

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Group equivariant non-expansive operators

The natural pseudo-distance d_G represents our ground truth.

Unfortunately, d_G is difficult to compute. This is also a consequence of the fact that we can easily find subgroups G of $\text{Homeo}(X)$ that cannot be approximated with arbitrary precision by smaller **finite** subgroups of G (i.e. $G = \text{group of rigid motions of } X = \mathbb{R}^3$).

Nevertheless, in this talk we will show that d_G can be approximated with arbitrary precision by means of a **DUAL** approach based on persistent homology and group equivariant non-expansive operators (**GENEOs**).

The space of GENEOS

Definition

Assume that (Φ, G) , (Ψ, H) are two perception pairs and that a homomorphism $T : G \rightarrow H$ has been fixed. A *Group Equivariant Non-Expansive Operator (GENEO)* from (Φ, G) to (Ψ, H) is a map $F : \Phi \rightarrow \Psi$ such that the following properties hold for every $\varphi_1, \varphi_2 \in \Phi$:

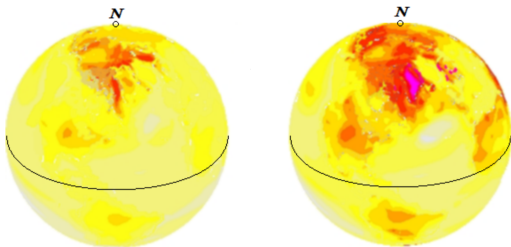
1. $F(\varphi \circ g) = F(\varphi) \circ T(g)$ for every $g \in G$;
2. $D_\Psi(F(\varphi_1), F(\varphi_2)) \leq D_\Phi(\varphi_1, \varphi_2)$.

We will use the symbol \mathcal{F}^{all} to denote the set of all GENEOS from (Φ, G) to (Ψ, H) with respect to T .

An example of GENEIO

We give an example of the use of the definition of GENEIO between two different perception pairs (Φ, G) , (Ψ, H) .

Let us assume to be interested in the comparison of the distributions of temperatures on a sphere, taken at two different times:



Let us also imagine that only two opposite points N, S can be localized on the sphere.

An example of GENE0

In this case we can set

- $X = S^2$
- $\Phi =$ set of 1-Lischitzian functions from S^2 to a fixed interval $[a, b]$
- $G =$ group of rotations of S^2 around the axis $N - S$

We can also consider the “equator” of our sphere, represented as the space S^1 .

Therefore, we can also set

- $Y =$ the equator S^1 of S^2
- $\Psi =$ set of 1-Lischitzian functions from S^1 to $[a, b]$
- $H =$ group of rotations of S^1

An example of GENEEO

In this case we can build a simple example of GENEEO from (Φ, G) to (Ψ, H) by setting

- $T(g)$ equal to the rotation $h \in H$ of the equator S^1 that is induced by the rotation g of S^2 , for every $g \in G$.
- $F(\varphi)$ equal to the function ψ that takes each point y belonging to the equator S^1 to the average of the temperatures along the meridian containing y , for every $\varphi \in \Phi$;

We can easily check that F verifies the properties defining the concept of group equivariant non-expansive operator with respect to the homomorphism $T : G \rightarrow H$.

In his talk, Mattia will illustrate other examples of GENEEOs.

Two pseudo-metrics for the space \mathcal{F}^{all}

The following two pseudo-metrics can be of use:

Definition

If $F_1, F_2 \in \mathcal{F}^{\text{all}}$, we set

$$\begin{aligned} D_{\text{GENEO}}(F_1, F_2) &:= \sup_{\varphi \in \Phi} D_{\Psi}(F_1(\varphi), F_2(\varphi)) \\ D_{\text{GENEO},H}(F_1, F_2) &:= \sup_{\varphi \in \Phi} d_H(F_1(\varphi), F_2(\varphi)). \end{aligned} \quad (0.1)$$

Proposition

D_{GENEO} and $D_{\text{GENEO},H}$ are pseudo-metrics on \mathcal{F}^{all} . Moreover, $D_{\text{GENEO},H} \leq D_{\text{GENEO}}$.

Some good news

Let \mathcal{F}^{all} be the set of all GNEOs from (Φ, G) to (Ψ, H) with respect to a fixed homomorphism $T : G \rightarrow H$.

Theorem

\mathcal{F}^{all} **is compact** with respect to both D_{GENEO} and $D_{\text{GENEO}, H}$.

Corollary

\mathcal{F}^{all} can be ε -approximated by a finite subset for every $\varepsilon > 0$.

Theorem

If Ψ is convex, then \mathcal{F}^{all} **is convex**.

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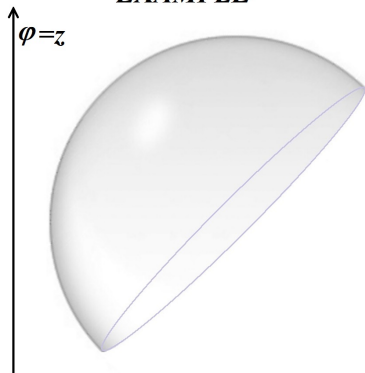
The link between the natural pseudo-distance and persistent homology via GENEOS

Building new GENEOS

What is persistent homology?

If $\varphi : X \rightarrow \mathbb{R}$ is a continuous functions, we can consider the sublevel sets $X_t := \{x \in X : \varphi(x) \leq t\}$. When t varies we see the birth and death of k -dimensional holes.

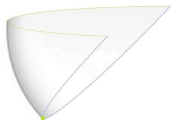
EXAMPLE



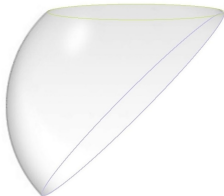
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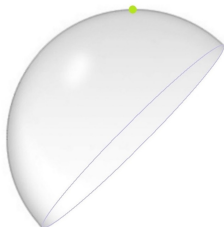
EXAMPLE



No 1-dimensional hole



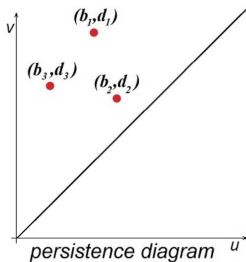
Birth of a 1-dimensional hole



Death of the 1-dimensional hole

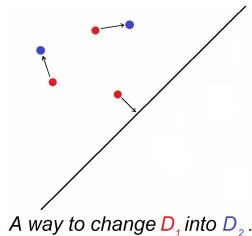
What is persistent homology?

In plain words, the **persistence diagram** in degree k of φ is the collection of the pairs (b_i, d_i) where b_i and d_i are the times of birth and death of the i -th hole of dimension k .



The points of the persistence diagram are endowed with multiplicity. Each point of the diagonal $u = v$ is assumed to be a point of the persistence diagram, endowed with infinite multiplicity.

Comparison of persistence diagrams



Persistence diagrams can be compared by means of the **bottleneck distance** d_{match} . The bottleneck distance between two persistence diagrams D_1, D_2 is the minimum cost of changing the points of D_1 into the points of D_2 , where the cost of moving each point is given by the max-norm distance in \mathbb{R}^2 . Moving a point to the diagonal is equivalent to delete it.

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Persistent homology enters this theoretical framework by means of an equality allowing us to approximate the natural pseudo-distance:

Theorem

If $(\Phi, G) = (\Psi, H)$, then

$$d_G(\varphi_1, \varphi_2) = \sup_{F \in \mathcal{F}^{\text{all}}} d_{\text{match}}(\text{Dgm}(F(\varphi_1)), \text{Dgm}(F(\varphi_2)))$$

where $\text{Dgm}(F(\varphi))$ is the persistence diagram of the function $F(\varphi)$ and d_{match} is the usual bottleneck distance.

(More details in the paper [P. Frosini, G. Jabłoński, *Combining persistent homology and invariance groups for shape comparison*, *Discrete & Comput. Geometry*, vol. 55 (2016), n. 2, pages 373-409.])

The pseudo-metric $D_{\text{match}}^{\mathcal{F}}$

Let us take a finite ε -approximation \mathcal{F} of \mathcal{F}^{all} . We can then define the pseudo-metric

$$D_{\text{match}}^{\mathcal{F}}(\varphi_1, \varphi_2) := \sup_{F \in \mathcal{F}} d_{\text{match}}(\text{Dgm}(F(\varphi_1)), \text{Dgm}(F(\varphi_2))).$$

The following properties hold for every $\varphi_1, \varphi_2 \in \Phi$ and every $g \in G$:

- $D_{\text{match}}^{\mathcal{F}}(\varphi_1, \varphi_2 \circ g) = D_{\text{match}}^{\mathcal{F}}(\varphi_1, \varphi_2)$;
- $D_{\text{match}}^{\mathcal{F}}(\varphi_1, \varphi_2) \leq d_G(\varphi_1, \varphi_2) \leq \|\varphi_1 - \varphi_2\|_{\infty}$;
- $|d_G(\varphi_1, \varphi_2) - D_{\text{match}}^{\mathcal{F}}(\varphi_1, \varphi_2)| \leq 2\varepsilon$.

Another link with TDA

The computational machinery developed in persistent homology can be used in our mathematical approach as a proxy for the fast comparison of GENEOS, by replacing $D_{\text{GENEO}}(F_1, F_2)$ with the pseudo-metric

$$\Delta_{\text{GENEO}}(F_1, F_2) := \sup_{\varphi \in \Phi} d_{\text{match}}(\text{Dgm}(F_1(\varphi)), \text{Dgm}(F_2(\varphi))).$$

The following result immediately follows from the stability of persistence diagrams:

Proposition

$$\Delta_{\text{GENEO}}(F_1, F_2) \leq D_{\text{GENEO}}(F_1, F_2).$$

In other words, persistent homology provides an efficient way for the comparison of GENEOS.

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Building new GENEOS

Our approach to group equivariant Topological Data Analysis is based on the availability of GENEOS.

How could we build new GENEOS from other GENEOS?

A simple method consists in composing GENEOS:

Proposition

If F_1 is a GENEOS from (Φ_1, G_1) to (Φ_2, G_2) with respect to $T_1 : G_1 \rightarrow G_2$ and F_2 is a GENEOS from (Φ_2, G_2) to (Φ_3, G_3) , then $F_2 \circ F_1$ is a GENEOS from (Φ_1, G_1) to (Φ_3, G_3) with respect to $T_2 \circ T_1 : G_1 \rightarrow G_3$.

Building GENEOS via 1-Lipschitzian functions

We can also produce new GENEOS by means of a 1-Lipschitzian function applied to other GENEOS:

Proposition

Assume that two perception pairs (Φ, G) , (Ψ, H) and a homomorphism $T : G \rightarrow H$ are given. Let \mathcal{L} be a 1-Lipschitzian map from \mathbb{R}^n to \mathbb{R} , where \mathbb{R}^n is endowed with the norm

$\|(x_1, \dots, x_n)\|_\infty := \max_{1 \leq i \leq n} |x_i|$. Assume also that F_1, \dots, F_n are GENEOS from (Φ, G) to (Ψ, H) with respect to T . Let us define

$\mathcal{L}^(F_1, \dots, F_n)$ by setting*

$\mathcal{L}^(F_1, \dots, F_n)(\varphi)(x) := \mathcal{L}(F_1(\varphi)(x), \dots, F_n(\varphi)(x))$. If*

$\mathcal{L}^(F_1, \dots, F_n)(\Phi) \subseteq \Psi$, then $\mathcal{L}^*(F_1, \dots, F_n)$ is a GENEOS from (Φ, G) to (Ψ, H) with respect to T .*

From this proposition the following three results follow.

Building new GENEOS via translations, the maximum operator and weighted averages

Assume that two perception pairs (Φ, G) , (Ψ, H) and a homomorphism $T : G \rightarrow H$ are given.

Proposition (Translation)

Let F be a GENEOS from (Φ, G) to (Ψ, H) with respect to T . The operator $F_b(\varphi) := \varphi - b$ is a GENEOS from (Φ, G) to (Ψ, H) with respect to T , for every $b \in \mathbb{R}$ such that $F_b(\Phi) \subseteq \Psi$.

Proposition (Maximum)

If F_1, \dots, F_n are GENEOSs from (Φ, G) to (Ψ, H) with respect to T , then the operator $F(\varphi) := \max_i F_i(\varphi)$ is a GENEOS from (Φ, G) to (Ψ, H) with respect to T , provided that $F(\Phi) \subseteq \Psi$.

Building new GENEOS via translations, weighted averages and the maximum operator

Proposition (Weighted average)

If F_1, \dots, F_n are GENEOS from (Φ, G) to (Ψ, H) with respect to T and $(a_1, \dots, a_n) \in \mathbb{R}^n$ with $\sum_{i=1}^n |a_i| \leq 1$, then the operator $F(\varphi) := \sum_{i=1}^n a_i F_i(\varphi)$ is a GENEOS from (Φ, G) to (Ψ, H) with respect to T , provided that $F(\Phi) \subseteq \Psi$.

Our results show that if we work with spaces Φ, Ψ of measurements that are compact and convex, then the topological space of all GENEOS from (Φ, G) to (Ψ, H) with respect to T is compact and convex.

An interesting GENE0 in kD persistent homology

Previous propositions imply the following statement.

Proposition

Assume F_1, \dots, F_n are GENE0s from (Φ, G) to (Ψ, H) with respect to T , and that $(a_1, \dots, a_n), (b_1, \dots, b_n) \in \mathbb{R}^n$, with $a_1, \dots, a_n > 0$, $\sum_{i=1}^n a_i = 1$ and $\sum_{i=1}^n b_i = 0$. Then the operator

$$F(\varphi) := \max \left\{ \frac{\min_j a_j}{a_1} \cdot (F_1(\varphi) - b_1), \dots, \frac{\min_j a_j}{a_n} \cdot (F_n(\varphi) - b_n) \right\}$$

is a GENE0 from (Φ, G) to (Ψ, H) with respect to T , provided that $F(\Phi) \subseteq \Psi$.

This result can be easily generalized from the case $\Phi \subseteq C^0(X, \mathbb{R})$ to the case $\Phi \subseteq C^0(X, \mathbb{R}^m)$.

An interesting GENE0 in kD persistent homology

Let us now take $G = H$, $T = id$ and $n = m$ in the extended version of the previous proposition. By considering the projection operators $F_i(\varphi) := \varphi_i$ for every $\varphi = (\varphi_1, \dots, \varphi_n) \in \Phi \subseteq C^0(X, \mathbb{R}^n)$, we obtain the operator

$$F(\varphi) = \max \left\{ \frac{\min_j a_j}{a_1} \cdot (\varphi_1 - b_1), \dots, \frac{\min_j a_j}{a_n} \cdot (\varphi_n - b_n) \right\}.$$

This operator is important in kD persistent homology, as a key tool to reduce kD persistent Betti number functions to families of 1D persistent Betti number functions. It is interesting to observe that such an operator is a group equivariant non-expansive operator.

Conclusions and open questions

We have introduced a topological-geometrical model where we can formalize and attack this problem: how can we find efficient methods to approximate a given agent/observer by a GENE0 belonging to a compact and convex space of GENE0s?

This problem leads us to the following open questions:

- How can we build a good library of GENE0s?
- How can we find a method to choose a finite set \mathcal{F}^* of GENE0s that allows for both a good approximation of the natural pseudo-distance d_G and a fast computation?
- In which cases can the set of GENE0s be equipped with the structure of a Riemannian manifold?
- Could we compose operators to form networks, in the same way as computational units are connected in an artificial neural network?

(→ **Mattia's talk**)

Thanks for your attention!

