

Jacobi method for small matrices

Erna Begović

University of Zagreb

Joint work with **Vjeran Hari**

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OUTLINE

- Why small matrices?
- Jacobi method and pivot strategies
- Parallel strategies on 4×4 matrices
- Conclusion

JACOBI METHOD

- Goal: diagonal matrix.
- One step:

$$A^{(k+1)} = U_k^T A^{(k)} U_k, \quad k \geq 0, \quad A^{(0)} = A,$$

where $U_k = R(i(k), j(k), \phi(k))$ are orthogonal,

$$R(i, j, \phi) = \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & \cos \phi & & -\sin \phi \\ & & & & 1 & \\ & & & & & \ddots & \\ & & & & & & 1 \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \end{bmatrix}$$

$i \quad \quad \quad j$

PIVOT STRATEGIES

Pivot strategy is the function $k \mapsto (i(k), j(k))$.

- Cyclic strategies
- Serial strategies (row and column)
- Strategies with permutations inside columns / rows
- Examples:

$$\left[\begin{array}{ccccc} * & 0 & 2 & 4 & 6 \\ * & 1 & 5 & 8 & \\ * & 3 & 7 & & \\ * & 9 & & & \\ * & & & & \end{array} \right] \in \mathcal{C}_1, \quad \left[\begin{array}{ccccc} * & 6 & 9 & 7 & 8 \\ * & 3 & 5 & 4 & \\ * & 2 & 1 & & \\ * & 0 & & & \\ * & & & & \end{array} \right] \in \mathcal{C}_2,$$
$$\left[\begin{array}{ccccc} * & 9 & 8 & 4 & 2 \\ * & 7 & 6 & 1 & \\ * & 5 & 0 & & \\ * & 3 & & & \\ * & & & & \end{array} \right] \in \mathcal{C}_3, \quad \left[\begin{array}{ccccc} * & 3 & 1 & 0 & 2 \\ * & 6 & 5 & 4 & \\ * & 8 & 7 & & \\ * & 9 & & & \\ * & & & & \end{array} \right] \in \mathcal{C}_4.$$

REFERENCES

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Pivot strategies:

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PARALLEL STRATEGIES ON 4×4 MATRICES

We restrict our attention to those cyclic pivot strategies ([16 strategies](#)) that enable full parallelization of the method.

It will be sufficient to study pivot strategy

$$\begin{bmatrix} * & 4 & 0 & 2 \\ 4 & * & 3 & 1 \\ 0 & 3 & * & 5 \\ 2 & 1 & 5 & * \end{bmatrix},$$

which corresponds to parallel strategy

$$\begin{bmatrix} * & 2 & 0 & 1 \\ 2 & * & 1 & 0 \\ 0 & 1 & * & 2 \\ 1 & 0 & 2 & * \end{bmatrix}.$$

CONVERGENCE

- Off-norm of a symmetric matrix

$$S(A) = \frac{\sqrt{2}}{2} \text{off}(A) = \frac{\sqrt{2}}{2} \|A - \text{diag}(A)\|_F = \sqrt{\sum_{i=1}^{n-1} \sum_{j=i+1}^n a_{ij}^2}, \quad A = A^T.$$

We find the constant γ , $0 \leq \gamma < 1$, such that

$$S^2(A^{[3]}) \leq \gamma S^2(A),$$

where $A^{[3]}$ is obtained from A after three full cycles.

SLOW CONVERGENCE - EXAMPLE

$$A = A^{(0)} = \begin{bmatrix} d + p_1 + p_2 & 0 & \epsilon + p_1 & -a + p_1 \\ 0 & d + p_2 & a & -\epsilon \\ \epsilon + p_1 & a & d + p_1 & 0 \\ -a + p_1 & \epsilon & 0 & d \end{bmatrix},$$

where $a = 1$, $\epsilon = 10^{-k-10}$, $d = 1 + \epsilon$, $p_2 = 10^{-1.5k}$, $p_3 = 10^{-1.5k-10}$ and

$$S(A) = 1.41421356237309504880168872420969807856967187537694.$$

SLOW CONVERGENCE - EXAMPLE

k	$(i(k), j(k))$	$S(A^{(k)})$
1	(1, 3)	1.41421356237309504880168872420969807856967187537694
2	(2, 4)	1.41421356237309504880168872420969807856967187537694
3	(1, 4)	1.41421356237309504880168872420969807856967187537694
4	(2, 3)	1.41421356237309504880168872420969807856967187537694
5	(1, 2)	1.41421356237309504880168872420969807856967187537694
6	(3, 4)	1.41421356237309504880168872420969807856967187537694
7	(1, 3)	1.41421356237309504880168872420969807856967187537694
8	(2, 4)	1.41421356237309504880168872420969807856967187537694
9	(1, 4)	0.99
10	(2, 3)	0.14142135623730950488016887242096980785696718753769e-89

SLOW CONVERGENCE - EXAMPLE

As long as the rotation angle is “close enough” to $\pm\frac{\pi}{4}$, the off-norm will not change in the next two steps.

k	(i, j)	$\sin \phi(i, j)$
1	(1, 3)	-0.70710678118654752440084434442717950962116550533689
2	(2, 4)	0.70710678118654752440084434442717950962114782766736
3	(1, 4)	0.70710678118654752440084436210484903221376812582298
4	(2, 3)	-0.70710678118654752440084436210484903221376812582299
5	(1, 2)	0.70710678118654752440084436210484903928483593768847
6	(3, 4)	0.70710678118654752440084436210484903928481826001894
7	(1, 3)	0.24999999999999987500000000000003906250000000000390e-15
8	(2, 4)	-0.24999999999999987500000000000003906250000000000390e-15

CHANGING THE APPROACH

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Pivot strategy $\mathcal{O} = (1, 3), (2, 4), (1, 4), (2, 3), (1, 2), (3, 4)$ on matrix

$$A = \begin{bmatrix} a_{11} & 0 & a_{13} & a_{14} \\ 0 & a_{22} & a_{23} & a_{24} \\ a_{13} & a_{23} & a_{33} & 0 \\ a_{14} & a_{24} & 0 & a_{44} \end{bmatrix}.$$

Let

$$Q = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}, \quad Q^T X Q = \begin{bmatrix} x_{11} & x_{13} & x_{14} & -x_{12} \\ x_{31} & x_{33} & x_{34} & -x_{32} \\ x_{41} & x_{43} & x_{44} & -x_{42} \\ -x_{21} & -x_{23} & -x_{24} & x_{22} \end{bmatrix}.$$

OPERATOR \mathcal{T}

Definition

For $A \in \mathcal{S}_4$ we define

$$\mathcal{T} = (R(1, 3, \phi)R(2, 4, \psi)Q)^T A (R(1, 3, \phi)R(2, 4, \psi)Q),$$

where $R(1, 3, \phi)$ and $R(2, 4, \psi)$ are Jacobi rotations which annihilate the elements a_{13} and a_{24} of A , respectively, and $\phi, \psi \in [-\frac{\pi}{4}, \frac{\pi}{4}]$.

Properties of \mathcal{T} :

- $\mathcal{T}^k(A) = (Q^k)^T A^{(2k)} Q^k, \quad k \geq 0,$
- $S(\mathcal{T}^k(A)) = S(A^{(2k)}), \quad k \geq 0.$

MAIN THEOREM

Proposition

Let $A \in \mathcal{S}_4$ be such that $a_{12} = 0$, $a_{34} = 0$ and $\epsilon = 10^{-5}$. Then

$$S(\mathcal{T}^6(A)) \leq (1 - \epsilon)S(A).$$

Theorem

Let $A \in \mathcal{S}_4$ be such that $a_{12} = 0$, $a_{34} = 0$ and let $A^{(12)}$ be obtained by applying 12 steps of the Jacobi method under the strategy $\mathcal{O} = (1, 3), (2, 4), (1, 4), (2, 3), (1, 2), (3, 4)$ to A . Then

$$S(A^{(12)}) \leq (1 - 10^{-5})S(A).$$

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CONCLUSION

Theorem

Let $A \in \mathcal{S}_4$ and let $A^{[3]}$ be obtained by applying 3 full cycles of the Jacobi method under **any** cyclic strategy on A . Then there is a constant γ such that

$$S^2(A^{[3]}) \leq \gamma S^2(A), \quad 0 \leq \gamma < 1.$$

CONCLUSION

Theorem

Let $A \in \mathcal{S}_4$ and let $A^{[3]}$ be obtained by applying 3 full cycles of the Jacobi method under **any** cyclic strategy on A . Then there is a constant γ such that

$$S^2(A^{[3]}) \leq \gamma S^2(A), \quad 0 \leq \gamma < 1.$$

Thank you!