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ROBERTO CONTI



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International Mathematical Summer Center

Exploiting Hidden Structure in Matrix Computations. Algorithms and  
Applications

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# On Computing Matrix Polynomial Roots

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# Outline

- **Nonlinear eigenvalue problem**
- **Hermite interpolation problem**
- **Linearization in Hermite basis**
- **A clarifying example**

# Nonlinear eigenvalue problem

$$F(z)x = 0$$

- $F : \mathbb{C} \rightarrow \mathbb{C}^{n \times n}$ : a given matrix-valued function
- $z \in \mathbb{C}$ : *eigenvalue*
- $x \in \mathbb{C}^{n \times 1}$ : *eigenvector*

# Nonlinear eigenvalue problem

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**Application:** different areas of mechanics, such as machine foundations, electronic model of metal strip, etc, see:

A comprehensive collection of the eigenvalue problems from models of real life as well as structured ones is studied in:

T. Betcke, N. J. Higham, V. Mehrmann, C. Schröder, F. Tisseur, *NLEVP: A Collection of Nonlinear Eigenvalue Problems*, ACM Trans. Math. Software 39(2) (2013) 1–28.

# Hermite interpolation problem

$$F(z)x = 0$$

Assume  $F$  is not given explicitly:

For the interpolation nodes  $z_0, \dots, z_n \in \mathbb{C}$ , let

$$F^{(j)}(z_i) = F_{i,j}, \quad i = 0, \dots, n, \quad j = 0, \dots, s_i - 1$$

where  $s_i \geq 1$  denote the confluency of the  $i$ th interpolation node

$$s + 1 = \sum_{i=0}^n s_i.$$

The **Hermite interpolation problem** is to construct a matrix polynomial  $P(z)$  of degree  $s$  such that

$$\left. \frac{d^j P(z)}{dz^j} \right|_{z=z_i} = F_{i,j}, \quad i = 0, \dots, n, \quad j = 0, \dots, s_i - 1.$$

# A solution to the interpolation problem

A solution to the interpolation problem is presented in:

B. Sadiq, D. Viswanath, *Barycentric Hermite interpolation*, SIAM J. Sci. Comput. 35 (2013) 1254–1270.

We begin with the definition of the polynomial  $\omega(z)$  of degree  $s + 1$ :

$$\omega(z) = \prod_{i=0}^n (z - z_i)^{s_i},$$

## The Modified barycentric form of the Hermite interpolant

$$P(z) = \omega(z) \sum_{i=0}^n \sum_{j=0}^{s_i-1} \frac{M_{i,j} w_i}{(z - z_i)^{s_i-j}},$$

where  $M_{i,j} := \sum_{k=0}^j \frac{F_{i,k}}{k!} J_{j-k}$ , and  $w_{i,k}$  are the **generalized barycentric weights**.

# Generalized barycentric weights

Define the sequences of  $\mathcal{J}_r$  as follows:

$$\mathcal{J}_0 = 1, \quad k\mathcal{J}_k = \mathcal{P}_k + \sum_{j=1}^{k-1} \mathcal{J}_j \mathcal{P}_{k-j}, \quad k \geq 1$$

where  $\mathcal{P}_r := \sum_{j \neq k} \frac{s_j}{(z_j - z_k)^r}$ ,  $r \geq 1$ .

Now, we have:

$$w_{i,k} = w_i \mathcal{J}_k, \quad w_i := \prod_{\substack{k=0, \\ k \neq i}}^n \frac{1}{(z_i - z_k)^{s_k}}.$$

# Modified Hermite barycentric interpolant

Now, instead of the eigenproblem  $F(z)x = 0$ , we consider:

## Polynomial eigenvalue problem

$$P(z)x = 0$$



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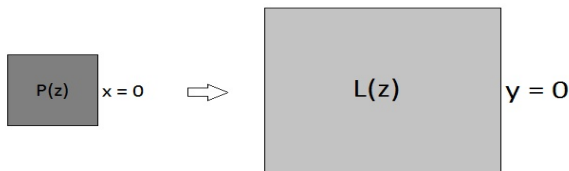
$$P(z)x = 0$$

The classical approach to numerically solving polynomial eigenvalue problems is **linearization**.

# Linearization



# Linearization



A pencil  $L(z)$  is a **linearization** of  $P(z)$ , if there exist unimodular matrix polynomials  $E(z), F(z)$  such that

$$E(z)L(z)F(z) = \begin{bmatrix} P(z) & 0 \\ 0 & I \end{bmatrix}.$$

# Linearization

Consider the interpolation nodes  $z_i, i = 0, \dots, n$ , with the confluency  $s_i$ , and  $N \times N$  matrix polynomial  $P(z)$  of degree  $s$  in the Hermite form, satisfying interpolation conditions.

$$P(z) = \omega(z) \sum_{i=0}^n \sum_{j=0}^{s_i-1} \frac{M_{i,j} w_i}{(z - z_i)^{s_i-j}}.$$

The pencil  $L(z)$  of size  $(s+2)N$  is a linearization for  $P(z)$ :

$$L(z) = \begin{bmatrix} J_0 & & & & -M_0 \\ & J_1 & & & -M_1 \\ & & \ddots & & \vdots \\ & & & J_n & -M_n \\ W_0 & W_1 & \dots & W_n & 0 \end{bmatrix}.$$

# Linearization

with the matrix

$$J_i = z l_{Ns_i} - \begin{bmatrix} z_i l_N & I_N & & \\ & z_i l_N & I_N & \\ & & \ddots & I_N \\ & & & z_i l_N \end{bmatrix} \in \mathbb{C}^{Ns_i \times Ns_i}, \quad i = 0, \dots, n.$$

The vectors

$$W_i = [w_i l_N \quad 0 \quad \dots \quad 0] \in \mathbb{C}^{N \times Ns_i} \quad i = 0, \dots, n,$$

and

$$M_i = [M_{i,s_i-1} \quad \dots \quad M_{i,1} \quad M_{i,0}]^T \in \mathbb{C}^{Ns_i \times N} \quad i = 0, \dots, n,$$

can be recovered directly from the interpolant.

# Example

The eigenvalues of  $F(z)$  are desired.

$$F(z_0) \quad F'(z_0) \quad F''(z_0)$$

$$F(z_1) \quad F'(z_1)$$

$$F(z_2)$$

$$s_0 = 3$$

$$s_1 = 2$$

$$s_2 = 1$$

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$$F(z_0) = F_{0,0} \quad F'(z_0) = F_{0,1} \quad F''(z_0) = F_{0,2}$$

$$F(z_1) = F_{1,0} \quad F'(z_1) = F_{1,1}$$

$$F(z_2) = F_{2,0}$$

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The polynomial interpolant exists and is given by:

$$P(z) = \omega(z) \left( \frac{M_{0,0} w_0}{(z - z_0)^3} + \frac{M_{0,1} w_0}{(z - z_0)^2} + \frac{M_{0,2} w_0}{(z - z_0)} + \frac{M_{1,0} w_1}{(z - z_1)^2} + \frac{M_{1,1} w_1}{(z - z_1)} + \frac{M_{2,0} w_2}{(z - z_2)} \right),$$

where

$$\omega(z) = (z - z_0)^3 (z - z_1)^2 (z - z_2),$$

$$w_i := \prod_{\substack{k=0, \\ k \neq i}}^n \frac{1}{(z_i - z_k)^{s_k}}.$$

The linearization is given by:

$$L(z) = \begin{pmatrix} (z - z_0)I_N & -I_N & & & & & -M_{0,2} \\ & (z - z_0)I_N & -I_N & & & & -M_{0,1} \\ & & (z - z_0)I_N & 0 & & & -M_{0,0} \\ & & & (z - z_1)I_N & -I_N & & -M_{1,1} \\ & & & & (z - z_1)I_N & 0 & -M_{1,0} \\ w_0 I_N & 0 & 0 & w_1 I_N & 0 & (z - z_2)I_N & -M_{2,0} \\ & & & & & w_2 I_N & 0 \end{pmatrix}.$$

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## Eigenvalue problem

Nonlinear eigenproblem  $F(z)x = 0 \Rightarrow$  Polynomial eigenproblem  $P(z)x = 0$

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$$\det P(z) = 0 \Leftrightarrow \det L(z) = 0$$

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- Further work is needed on the computational complexity.

