Low-rank techniques for high-dimensional problems

Daniel Kressner

Chair of Numerical Algorithms and HPC MATHICSE / EPF Lausanne

daniel.kressner@epfl.ch
http://anchp.epfl.ch

CIME, Cetraro, 2015







◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

What is a tensor?

Tensor is a multi-dimensional array of numbers.

A *d*-th order tensor \mathcal{X} of size $n_1 \times n_2 \times \cdots \times n_d$ is a *d*-dimensional array with entries

$$\mathcal{X}_{i_1,i_2,\ldots,i_d}, \qquad i_\mu \in \{1,\ldots,n_\mu\} \text{ for } \mu = 1,\ldots,d.$$

 $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_d}.$

Multi-index notation:

$$\mathfrak{I} = \{1, \ldots, n_1\} \times \{1, \ldots, n_2\} \times \cdots \times \{1, \ldots, n_d\}.$$

Then $i \in \mathfrak{I}$ is a tuple of *d* indices:

$$i = (i_1, i_2, \ldots, i_d).$$

Allows to write entries of \mathcal{X} as \mathcal{X}_i for $i \in \mathfrak{I}$.

Tensors from multivariate functions

Discretization of function $f(\xi_1, \ldots, \xi_d)$ on hypercube \rightsquigarrow tensor of order d



▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

High-dimensional elliptic PDEs: 3D model problem

Consider

$$-\Delta u = f$$
 in Ω , $u|_{\partial\Omega} = 0$,

on unit cube $\Omega = [0, 1]^3$.

 Discretize on tensor grid. Uniform grid for simplicity:

$$\xi_{\mu}^{(j)} = jh, \quad h = \frac{1}{n+1}$$

for $\mu = 1, 2, 3$.

• Approximate solution tensor $U \in \mathbb{R}^{n \times n \times n}$:

$$\mathcal{U}_{i_1,i_2,i_3} \approx u(\xi_1^{(i_1)},\xi_2^{(i_2)},\xi_3^{(i_3)}).$$



◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

High-dimensional elliptic PDEs: Arbitrary dimensions

Finite difference discretization of model problem

$$-\Delta u = f$$
 in Ω , $u|_{\partial\Omega} = 0$

for $\Omega = [0, 1]^d$ takes the form

$$\left(\sum_{j=1}^{d} I \otimes \cdots \otimes I \otimes A \otimes I \otimes \cdots \otimes I\right) \mathbf{u} = \mathbf{f}.$$

To obtain such Kronecker structure in general:

- tensorized domain;
- highly structured grid;
- coefficients that can be written/approximated as sum of separable functions.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

Low-rank approximation of solution tensor:

Highly active research area.

Tensors from Taylor expansion

 $f : \mathbb{R}^m \to \mathbb{R}^n$ sufficiently smooth:

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2}f''(x)[h,h] + \frac{1}{3!}f^{(3)}(x)[h,h,h] + \frac{1}{4!}f^{(4)}(x)[h,h,h,h] + \frac{1}{5!}f^{(5)}(x)[h,h,h,h,h] + \cdots$$

with multilinear map $f^{(k)} : \mathbb{R}^{m \times \cdots \times m} \to \mathbb{R}^n$ represented by (k + 1)-dimensional tensor.

Low-rank approximation of $f^{(k)}$ used in:

- Model reduction and simulation of nonlinear circuits [Liu/Daniel/Wong'2015]
- Approximate representation and computation of random fields in UQ [DK/Kumar/Nobile/Tobler'2015], [Bonizzoni/Nobile/DK'2014].

Tensors from interconnected systems



- Set of subsystems with finite number of states interacting with each other.
- State of whole system characterized by combined states of subsystems.
- ▶ d subsystems with n states ~> n^d states in total!

Low rank tensors in reliability analysis:

- Approximation of *d*-dimensional tensors containing joint probability distributions.
- [Buchholz'2011], [DK/Macedo'2014].

Low-rank tensor techniques

- ► Emerged during last 5 10 years in numerical analysis.
- Successfully applied to:
 - parameter-dependent / multi-dimensional integrals;
 - electronic structure calculations: Hartree-Fock / DFT;
 - stochastic and parametric PDEs;
 - high-dimensional Boltzmann / chemical master / Fokker-Planck / Schrödinger equations;
 - micromagnetism;
 - rational approximation problems;
 - computational homogenization;
 - computational finance;
 - multivariate regression and machine learning;
 - queuing models;
 - ▶ ...
- For references on these applications, see
 - W. Hackbusch (2012). Tensor Spaces and Numerical Tensor Calculus, Springer.
 - L. Grasedyck, DK, Ch. Tobler (2013). A literature survey of lowrank tensor approximation techniques. GAMM-Mitteilungen, 36(1).

Rank of a tensor

Rank-1 tensor = outer product of vectors:

 $\mathcal{X} = \mathbf{a} \circ \mathbf{b} \circ \mathbf{c}.$

CANDECOMP/PARAFAC (CP) decomposition = (seemingly) natural extension:

 $\mathcal{X} = a_1 \circ b_1 \circ c_1 + a_2 \circ b_2 \circ c_2 + \cdots + a_r \circ b_r \circ c_r.$



◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

CP decomposition

CP decomposition offers low data-complexity; for constant r:

linear complexity in d.

Theoretical issues:

- For tensors of order $d \ge 3$:
 - ► tensor rank r is not upper semi-continuous ~>

lack of closedness

- successive rank-1 approximations fail
- all algorithms based on optimization techniques (ALS, Gauss-Newton)

Practical issues:

- ► No SVD-based compression possible.
- CP ignores locality of interactions!



Picture taken from [Kolda/Bader'2009].

SVD-based formats

Aggregate interconnected system into two sub-systems

 $\hat{=}$ matricization of tensor \mathcal{X} .



SVD-based formats

- Singular value decay of matricization for 'large overflow model'.
- First two systems mapped to rows $\Rightarrow \mathbb{R}^{n_1 n_2 \times n_3 n_4}$ matrix.
- ▶ $n_1 = n_2 = n_3 = n_4 = 40$, plot first 80 (from a total of 1600) singular values.



SVD-based formats

Low-rank approximation of matricization:



Insufficient for high dimensions.

Solution:

Consider tensor format based on *aggregations into* $\{1, ..., k\}$ and $\{k + 1, ..., d\}$, for all k = 1, ..., d.

→ TT format.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Tensor network diagrams

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Tensor network diagrams

- Introduced by Roger Penrose.
- Heavily used in quantum mechanics (spin networks).

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

This is a scalar $\gamma \in \mathbb{R}$

 \bigcirc

◆□ > ◆□ > ◆ 三 > ◆ 三 > ● ○ ○ ○ ○

This is a vector $x \in \mathbb{R}^n$



These are two vectors $x, y \in \mathbb{R}^n$

· ---- ·

◆□ > ◆□ > ◆ 三 > ◆ 三 > ● ○ ○ ○ ○

This is the inner product between $x, y \in \mathbb{R}^n$





These are two matrices A, B

◆□ > ◆□ > ◆ 三 > ◆ 三 > ● ○ ○ ○ ○

This is the matrix product C = AB



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

This is the matrix product $C = U \Sigma V^T$



If $r \ll n$: Implicit representation of C via smaller matrices U, V, Σ .

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

This is a tensor \mathcal{X} of order 3



This is a tensor \mathcal{X} of order 3 in Tucker decomposition



$$\mathcal{X}_{ijk} = \sum_{\ell_1=1}^{r_1} \sum_{\ell_2=1}^{r_2} \sum_{\ell_3=1}^{r_3} C_{\ell_1 \ell_2 \ell_3} U_{i\ell_1} V_{j\ell_2} W_{k\ell_3}$$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Implicit representation of \mathcal{X} via

- $r_1 \times r_2 \times r_3$ core tensor C
- $n_1 \times r_1$ matrix U spans first mode
- $n_2 \times r_2$ matrix V spans second mode
- $n_3 \times r_3$ matrix W spans third mode.

Tucker decomposition & multilinear rank

Reshape tensor into matrix by slicing, e.g. for first dimension:

$$\mathcal{X} = \bigcup_{n_1 \times (n_2 \cdot n_3)} \quad \in \mathbb{R}^{n_1 \times (n_2 \cdot n_3)}$$

Multilinear rank of tensor $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ defined by tuple

$$\mathbf{r} = (r_1, r_2, r_3), \text{ with } \mathbf{r}_i = \operatorname{rank}(X_{(i)}).$$



Representation of rank-**r**-tensor: Tucker decomposition:

$$\mathcal{X} = \mathcal{C} \times_1 U \times_2 V \times_3 W$$

 $U \in \mathbb{R}^{n_1 \times r_1}, V \in \mathbb{R}^{n_2 \times r_2}, W \in \mathbb{R}^{n_3 \times r_3}$, and core tensor $C \in \mathbb{R}^{r_1 \times r_2 \times r_3}$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Six-dimensional tensor \mathcal{X} in TT format



- X implicitly represented by four r × n × r tensors and two n × r matrices
- Quantum mechanics: MPS (matrix product states)
- Matrix-based tensor formats introduced in numerical analysis by Grasedyck, Hackbusch, Kühn, Oseledets, Tyrtishnikov.

・ コット (雪) (小田) (コット 日)

Six-dimensional tensor \mathcal{X} in TT format



This partition corresponds to low-rank factorization

 $X^{(1,2,3)} = UV^{T}, \qquad X^{(1,2,3)} \in \mathbb{R}^{n_{1}n_{2}n_{3} \times n_{4}n_{5}n_{6}}, \ U \in \mathbb{R}^{n_{1}n_{2}n_{3} \times r_{3}}, \ V \in \mathbb{R}^{n_{4}n_{5}n_{6} \times r_{3}}$

 $X^{(1,2,3)}$ is matricization of \mathcal{X} :

Merge multi-indices (1,2,3) into row indices and multi-indices (4,5,6) into column indices

The ranks of $X^{(1,...,\mu)}$ for $\mu = 1, ..., d-1$ are the TT ranks of \mathcal{X} .

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ □ のへぐ

Inner product of two tensors in TT format



Carrying out contractions requires O(dnr⁴) instead of O(n^d) operations for tensors of order d.

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Operations with tensors in TT format

Easy:

- inner product, 2-norm
- multiplication with Kronecker structured A

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

- recompression/truncation
- (partial) contractions

Operations with tensors in TT format

Easy:

- inner product, 2-norm
- multiplication with Kronecker structured A

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

- recompression/truncation
- (partial) contractions

Hard:

almost everything else

Operations with tensors in TT format

Easy:

- inner product, 2-norm
- multiplication with Kronecker structured A
- recompression/truncation
- (partial) contractions

Hard:

almost everything else

2 classes of algorithms for solving (linear algebra) problems:

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

- iterate and truncate
- constrain and optimize

All under the assumption that ranks stay small!

TT format for function-related tensors

- When to expect good low-rank approximations?
- Approximation error from separation wrt to $\{x_1, \ldots, x_a\}$:

$$f(x_1,\ldots,x_a,x_{a+1},\ldots,x_d)\approx\sum_{k=1}^r g_k(x_1,\ldots,x_a)h_k(x_{a+1},\ldots,x_d)$$

for a = 1, ..., d - 1.

For analytic functions

error
$$\leq \exp(-r^{\max\{1/a,1/(d-a)\}})$$
.

▶ [Temlyakov'1992, Uschmajew/Schneider'2013]: For *f* ∈ *B*^{s,mix}

error
$$\leq r^{-2s} (\log r)^{2s(\max\{a,d-a\}-1)}$$

Smoothness is neither sufficient nor necessary for high dimensions!

ALS-based algorithms

2D eigenvalue problem

- $-\triangle u(x) + V(x)u = \lambda u(x)$ in $\Omega = [0, 1] \times [0, 1]$ with Dirichlet b.c. and Henon-Heiles potential V
- Regular discretization
- Reshaped ground state into matrix



Excellent rank-10 approximation possible

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) = \min_{x \neq 0} \frac{\langle x, \mathcal{A}x \rangle}{\langle x, x \rangle}.$$

(ロ) (同) (三) (三) (三) (○) (○)

We now...

- reshape vector x into $n \times n$ matrix X;
- reinterpret Ax as linear operator $A : X \mapsto A(X)$.

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) = \min_{X
eq 0} rac{\langle X, \mathcal{A}(X)
angle}{\langle X, X
angle}$$

(ロ) (同) (三) (三) (三) (○) (○)

with matrix inner product $\langle\cdot,\cdot\rangle.$ We now...

restrict X to low-rank matrices.

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{T} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Approximation error governed by low-rank approximability of X.

(ロ) (同) (三) (三) (三) (○) (○)

Solved by Riemannian optimization techniques or ALS.

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{X = \mathcal{U}V^{\top} \neq 0}} \frac{\langle X, \mathcal{A}(X) \rangle}{\langle X, X \rangle}.$$

Initially:

- ▶ fix target rank r
- ▶ $U \in \mathbb{R}^{m \times r}$, $V^{n \times r}$ randomly, such that V is ONB

$$\begin{split} \tilde{\lambda} - \lambda &= \mathbf{6} \times \mathbf{10^3} \\ \text{residual} &= \mathbf{3} \times \mathbf{10^3} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{X = UV^{T} \neq 0} \frac{\langle X, \mathcal{A}(X) \rangle}{\langle X, X \rangle}.$$

Fix *V*, optimize for *U*.

$$\begin{array}{lll} \langle X, \mathcal{A}(X) \rangle & = & \operatorname{vec}(UV^{\mathsf{T}})^{\mathsf{T}} \mathcal{A} \operatorname{vec}(UV^{\mathsf{T}}) \\ & = & \operatorname{vec}(U)^{\mathsf{T}} (V \otimes I)^{\mathsf{T}} \mathcal{A} (V \otimes I) \operatorname{vec}(U) \end{array}$$

 \rightsquigarrow Compute smallest eigenvalue of reduced matrix (*rn* × *rn*) matrix

 $(V \otimes I)^T \mathcal{A}(V \otimes I).$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Note: Computation of reduced matrix benefits from Kronecker structure of \mathcal{A} .

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\boldsymbol{X} = UV^{\tau} \neq 0} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Fix V, optimize for U.

$$\begin{split} \tilde{\lambda} - \lambda &= \mathbf{2} \times \mathbf{10^3} \\ \text{residual} &= \mathbf{2} \times \mathbf{10^3} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize U, fix U, optimize for V.

$$\begin{array}{lll} \langle X, \mathcal{A}(X) \rangle &=& \mathsf{vec}(UV^{\mathsf{T}})^{\mathsf{T}} \mathcal{A} \, \mathsf{vec}(UV^{\mathsf{T}}) \\ &=& \mathsf{vec}(V^{\mathsf{T}})(I \otimes U)^{\mathsf{T}} \mathcal{A}(I \otimes U) \mathsf{vec}(V^{\mathsf{T}}) \end{array}$$

 \rightsquigarrow Compute smallest eigenvalue of reduced matrix (*rn* × *rn*) matrix

 $(I \otimes U)^T \mathcal{A}(I \otimes U).$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Note: Computation of reduced matrix benefits from Kronecker structure of \mathcal{A} .

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize U, fix U, optimize for V.

$$\begin{split} \tilde{\lambda} - \lambda &= \textbf{1.5} \times \textbf{10}^{-7} \\ \text{residual} &= \textbf{7.7} \times \textbf{10}^{-3} \end{split}$$



▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ● ●

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize V, fix V, optimize for U.

$$\begin{split} \tilde{\lambda} - \lambda &= \mathbf{1} \times \mathbf{10^{-12}} \\ \text{residual} &= \mathbf{6} \times \mathbf{10^{-7}} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize U, fix U, optimize for V.

$$\begin{split} \tilde{\lambda} - \lambda &= \textbf{7.6} \times \textbf{10}^{-\textbf{13}} \\ \textbf{residual} &= \textbf{7.2} \times \textbf{10}^{-\textbf{8}} \end{split}$$



ALS for TT format

Originates from quantum mechanics = one-site DMRG.

Goal:

$$\min\left\{\frac{\langle \mathcal{X}, \mathcal{A}(\mathcal{X}) \rangle}{\langle \mathcal{X}, \mathcal{X} \rangle} : \mathcal{X} \in \mathcal{M}_{\mathbf{r}}, \ \mathcal{X} \neq \mathbf{0}\right\}$$
$$\mathcal{M}_{\mathbf{r}} = \mathbf{0}$$

ALS: Choose one node *t*, fix all other nodes, set new tensor at node *t* to minimize Rayleigh quotient $\frac{\langle \mathcal{X}, \mathcal{A}(\mathcal{X}) \rangle}{\langle \mathcal{X}, \mathcal{X} \rangle}$. This is done for all nodes (a sweep), and sweeps are continued until convergence.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

Numerical Experiments - Sine potential, d = 10



Size = $128^{10} \approx 10^{21}$. Maximal TT rank 40.

(日)

э

Numerical Experiments - Henon-Heiles, d = 20



Size = $128^{20} \approx 10^{42}$. Maximal TT rank 40.

・ロット (雪) (日) (日)

э

Numerical Experiments - $1/||\xi||_2$ potential, d = 20



Size = $128^{20} \approx 10^{42}$. Maximal TT rank 30.

・ロット (雪) ・ (日) ・ (日)

э

Manifold-based algorithms

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

Robust low-rank tensor completion

$$\begin{array}{ll} \underset{\mathcal{X}}{\text{minimize}} & f(\mathcal{X}) := \frac{1}{2} \| \mathcal{P}_{\Omega}(\mathcal{X} - \mathcal{A}) \|^2 \\ \text{subject to} & \mathcal{X} \in \mathcal{M}_{\mathbf{r}} \end{array}$$



Applications:

- Completion of multidimensional data, e.g. hyperspectral images, CT Scans
- Compression of multivariate functions with singularities
- Non-intrusive methods for stochastic PDEs

・ コット (雪) (小田) (コット 日)

 Context-aware recommender systems

Manifold of low-rank tensors

$$\mathcal{M}_{\mathbf{r}} := \left\{ \mathcal{X} \in \mathbb{R}^{n_1 \times \ldots \times n_d} : \mathsf{rank}(\mathcal{X}) = \mathbf{r} \right\}$$

- *M*_r is a smooth manifold for TT format and its variants. [Holtz/Rohwedder/Schneider'2012], [Uschmajew/Vandereycken'2012]
- ► Riemannian with metric induced by standard inner product $\langle \mathcal{X}, \mathcal{Y} \rangle = \langle \mathcal{X}_{(1)}, \mathcal{Y}_{(1)} \rangle$ (sum of element-wise product)

Manifold structure used in

- dynamical low-rank approximation
 [Koch/Lubich'2010], [Arnold/Jahnke'2012],
 [Lubich/Rohwedder/Schneider/Vandereycken'2012],
 [Khoromskij/Oseledets/Schneider'2012], ...
- best multilinear approximation [Eldén/Savas'2009], [Ishteva/Absil/Van Huffel/De Lathauwer'2011], [Curtef/Dirr/Helmke'2012]
- robust tensor completion [DK/Steinlechner/Vandereycken'2013]

Riemannian optimization in a nutshell

- optimize in direction of Riemannian gradient
- combine different directions using vector transport





Geometric nonlinear CG for tensor completion

Input: Initial guess $\mathcal{X}_0 \in \mathcal{M}_r$. $\eta_0 \leftarrow -\text{grad} f(\mathcal{X}_0)$ $\alpha_0 \leftarrow \operatorname{argmin}_{\alpha} f(\mathcal{X}_0 + \alpha \eta_0)$ $\mathcal{X}_1 \leftarrow R_{\mathcal{X}_0}(\alpha_0 \eta_0)$ for *i* = 1, 2, ... do Compute gradient: $\xi_i \leftarrow \text{grad} f(\mathcal{X}_i)$ Conjugate direction by PR+ updating rule: $\eta_i \leftarrow -\xi_i + \beta_i \mathcal{T}_{\chi_{i-1} \to \chi_i} f(\eta_{i-1})$ Initial step size from linearized line search: $\alpha_i \leftarrow \operatorname{argmin}_{\alpha} f(\mathcal{X}_i + \alpha \eta_i)$ Armijo backtracking for sufficient decrease: Find smallest integer m > 0 such that $f(\mathcal{X}_i) - f(\mathcal{R}_{\mathcal{X}_i}(2^{-m}\alpha_i\eta_i)) > -1 \cdot 10^{-4} \langle \xi_i, 2^{-m}\alpha_i\eta_i \rangle$ Obtain next iterate: $\mathcal{X}_{i+1} \leftarrow R_{\mathcal{X}_i}(2^{-m}\alpha_i\eta_i)$ Cost/iteration: $O(nr^d + |\Omega|r^{d-1})$ ops. end for

Reconstruction of CT Scan

$199 \times 199 \times 150$ tensor from scaled CT data set "INCISIX", (taken from OSIRIX MRI/CT data base

[www.osirix-viewer.com/datasets/])

Slice of original tensor



Sampled tensor (6.7%)



HOSVD approx. of rank 21



Low-rank completion of rank 21



Compares very well with existing results w.r.t. low-rank recovery and speed, e.g., [Gandy/Recht/Yamada/'2011].

Hyperspectral Image

Set of photographs, $(204 \times 268 \text{ px})$ taken across a large range of wavelengths. 33 samples from ultraviolet to infrared [Image data: Foster et al.'2004] Stacked into a tensor of size $204 \times 268 \times 33$

10% of the Original Hyperspectral Imega Tensor, 16th Slice Size of Tensor is [204, 268, 33]



Completed Tensor, 16th Slice Final Rank is k = [50 50 6]



◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Here: Only 10% of entries known; [Signoretti et al.'2011] use 50%.

How many samples do we need?

Matrix case: $O(n \cdot \log^{\beta} n)$ samples suffice! [Candès/Tao'2009] \Rightarrow Completion of tensor by applying matrix completion to

matricization: $O(n^2 \log(n))$. Gives upper bound!

Tensor case: Certainly: $|\Omega| \ll O(n^2)$ In all cases of convergence \rightsquigarrow exact reconstruction.

Conjecture: $|\Omega| = O(n \cdot \log^{\beta} n)$



・ロト・西ト・ヨト・ヨー うへぐ

Conclusions and Outlook

- Scientific computing with low-rank tensors rapidly evolving field and highly technical.
- Low-rank tensors successfully solve certain classes of high-dimensional problems.
- Precise scope of applications far from clear; many applications remain to be explored. More analysis needed!

Software packages:

 MATLAB: Tensor toolbox, N-way toolbox, Tensorlab, TT-toolbox, htucker

(ロ) (同) (三) (三) (三) (○) (○)

- Python: ttpy
- C/C++: ALPS, TensorCalculus library
- Julia: TensorOperations.jl

▶ ...