

Spectral analysis and structure preserving preconditioners for fractional diffusion equations

Marco Donatelli · Mariarosa Mazza · Stefano Serra-Capizzano



Department of Science and High Technology, University of Insubria, Italy

CIME-EMS Cetraro, June 24, 2014

1 Problem setting

2 Spectral analysis

- Constant coefficients case
- Nonconstant coefficients case

3 Solvers for FDEs

- Literature
- What's new?

4 Numerical results

5 Conclusions

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

We are interested in the following space-fractional diffusion equation (FDE)

$$\frac{\partial u(x, t)}{\partial t} = d_+(x, t) \frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} + d_-(x, t) \frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} + f(x, t),$$

where

- $(x, t) \in (L, R) \times (0, T]$,
- $\alpha \in (1, 2)$ is the fractional derivative order,
- $f(x, t)$ is the source term,
- $d_\pm(x, t) \geq 0$ are the diffusion coefficients,
- $\frac{\partial^\alpha u(x, t)}{\partial_\pm x^\alpha}$ are the left-handed (+) and the right-handed (-) fractional derivatives,

and with the following initial-boundary conditions

$$\begin{cases} u(L, t) = u(R, t) = 0, & t \in [0, T], \\ u(x, 0) = u_0(x), & x \in [L, R]. \end{cases}$$

Fractional Diffusion Equations (FDEs)

$$\frac{\partial^\alpha u(x, t)}{\partial \pm x^\alpha}$$

are defined by the **shifted Grünwald formula** as follows

$$\frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} = \lim_{\Delta x \rightarrow 0^+} \frac{1}{\Delta x^\alpha} \sum_{k=0}^{\lfloor (x-L)/\Delta x \rfloor} g_k^{(\alpha)} u(x - (k-1)\Delta x, t),$$

$$\frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} = \lim_{\Delta x \rightarrow 0^+} \frac{1}{\Delta x^\alpha} \sum_{k=0}^{\lfloor (R-x)/\Delta x \rfloor} g_k^{(\alpha)} u(x + (k-1)\Delta x, t),$$

Fractional Diffusion Equations (FDEs)

$\frac{\partial^\alpha u(x, t)}{\partial \pm x^\alpha}$ are defined by the **shifted Grünwald formula** as follows

$$\frac{\partial^\alpha u(x, t)}{\partial_+ x^\alpha} = \lim_{\Delta x \rightarrow 0^+} \frac{1}{\Delta x^\alpha} \sum_{k=0}^{\lfloor (x-L)/\Delta x \rfloor} g_k^{(\alpha)} u(x - (k-1)\Delta x, t),$$

$$\frac{\partial^\alpha u(x, t)}{\partial_- x^\alpha} = \lim_{\Delta x \rightarrow 0^+} \frac{1}{\Delta x^\alpha} \sum_{k=0}^{\lfloor (R-x)/\Delta x \rfloor} g_k^{(\alpha)} u(x + (k-1)\Delta x, t),$$

where $g_k^{(\alpha)}$ are the **alternating fractional binomial coefficients** defined as

$$g_k^{(\alpha)} = (-1)^k \binom{\alpha}{k} = \frac{(-1)^k}{k!} \alpha(\alpha-1) \cdots (\alpha-k+1) \quad k = 0, 1, \dots$$

with the formal notation $\binom{\alpha}{0} = 1$.

A discretization

Fix two positive integers N, M , and define the following partition of $[L, R] \times [0, T]$,

$$\begin{aligned}x_i &= L + i\Delta t, \quad \Delta x = \frac{(R-L)}{N+1}, \quad i = 0, \dots, N+1, \\t_m &= m\Delta t, \quad \Delta t = \frac{T}{M}, \quad m = 0, \dots, M,\end{aligned}$$

A discretization

Fix two positive integers N, M , and define the following partition of $[L, R] \times [0, T]$,

$$\begin{aligned}x_i &= L + i\Delta t, \quad \Delta x = \frac{(R-L)}{N+1}, \quad i = 0, \dots, N+1, \\t_m &= m\Delta t, \quad \Delta t = \frac{T}{M}, \quad m = 0, \dots, M,\end{aligned}$$

- ① discretization in time by an implicit Euler method

A discretization

Fix two positive integers N, M , and define the following partition of $[L, R] \times [0, T]$,

$$\begin{aligned}x_i &= L + i\Delta t, \quad \Delta x = \frac{(R-L)}{N+1}, \quad i = 0, \dots, N+1, \\t_m &= m\Delta t, \quad \Delta t = \frac{T}{M}, \quad m = 0, \dots, M,\end{aligned}$$

- ① discretization in time by an implicit Euler method

+

A discretization

Fix two positive integers N, M , and define the following partition of $[L, R] \times [0, T]$,

$$\begin{aligned}x_i &= L + i\Delta t, \quad \Delta x = \frac{(R-L)}{N+1}, \quad i = 0, \dots, N+1, \\t_m &= m\Delta t, \quad \Delta t = \frac{T}{M}, \quad m = 0, \dots, M,\end{aligned}$$

- ① discretization in time by an implicit Euler method

+

- ② discretization in space of the fractional derivatives by the shifted Grünwald formula

A discretization

Fix two positive integers N, M , and define the following partition of $[L, R] \times [0, T]$,

$$\begin{aligned}x_i &= L + i\Delta t, \quad \Delta x = \frac{(R-L)}{N+1}, \quad i = 0, \dots, N+1, \\t_m &= m\Delta t, \quad \Delta t = \frac{T}{M}, \quad m = 0, \dots, M,\end{aligned}$$

- ① discretization in time by an implicit Euler method

+

- ② discretization in space of the fractional derivatives by the shifted Grünwald formula

=

consistent and unconditionally stable method^[1,2].

[1] Meerschaert, Tadjeran, *J. Comput. Appl. Math.*, 2004

[2] Meerschaert, Tadjeran, *Appl. Numer. Math.*, 2006

Matrix form of the discretized problem

$$\left(\nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T \right) u^{(m)} = \nu_{M,N} u^{(m-1)} + \Delta x^\alpha f^{(m)},$$

where

Matrix form of the discretized problem

$$\left(\nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T \right) u^{(m)} = \nu_{M,N} u^{(m-1)} + \Delta x^\alpha f^{(m)},$$

where

- $T_{\alpha,N}$ lower Hessenberg Toeplitz matrix

$$T_{\alpha,N} = - \begin{bmatrix} g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 & 0 \\ g_2^{(\alpha)} & g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ g_{N-1}^{(\alpha)} & \ddots & \ddots & \ddots & g_1^{(\alpha)} & g_0^{(\alpha)} \\ g_N^{(\alpha)} & g_{N-1}^{(\alpha)} & \cdots & \cdots & g_2^{(\alpha)} & g_1^{(\alpha)} \end{bmatrix}_{N \times N}$$

Matrix form of the discretized problem

$$\left(\nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T \right) u^{(m)} = \nu_{M,N} u^{(m-1)} + \Delta x^\alpha f^{(m)},$$

where

- $T_{\alpha,N}$ lower Hessenberg Toeplitz matrix

$$T_{\alpha,N} = - \begin{bmatrix} g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 & 0 \\ g_2^{(\alpha)} & g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ g_{N-1}^{(\alpha)} & \ddots & \ddots & \ddots & g_1^{(\alpha)} & g_0^{(\alpha)} \\ g_N^{(\alpha)} & g_{N-1}^{(\alpha)} & \cdots & \cdots & g_2^{(\alpha)} & g_1^{(\alpha)} \end{bmatrix}_{N \times N}$$

- $D_\pm^{(m)} = \text{diag}(d_{\pm,1}^{(m)}, \dots, d_{\pm,N}^{(m)})$ with $d_{\pm,i}^{(m)} := d_\pm(x_i, t_m)$,

,

Matrix form of the discretized problem

$$\left(\nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T \right) u^{(m)} = \nu_{M,N} u^{(m-1)} + \Delta x^\alpha f^{(m)},$$

where

- $T_{\alpha,N}$ lower Hessenberg Toeplitz matrix

$$T_{\alpha,N} = - \begin{bmatrix} g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 & 0 \\ g_2^{(\alpha)} & g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ g_{N-1}^{(\alpha)} & \ddots & \ddots & \ddots & g_1^{(\alpha)} & g_0^{(\alpha)} \\ g_N^{(\alpha)} & g_{N-1}^{(\alpha)} & \cdots & \cdots & g_2^{(\alpha)} & g_1^{(\alpha)} \end{bmatrix}_{N \times N}$$

- $D_\pm^{(m)} = \text{diag}(d_{\pm,1}^{(m)}, \dots, d_{\pm,N}^{(m)})$ with $d_{\pm,i}^{(m)} := d_\pm(x_i, t_m)$,
- $\nu_{M,N} = \frac{\Delta x^\alpha}{\Delta t}$,

Matrix form of the discretized problem

$$\left(\nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T \right) u^{(m)} = \nu_{M,N} u^{(m-1)} + \Delta x^\alpha f^{(m)},$$

where

- $T_{\alpha,N}$ lower Hessenberg Toeplitz matrix

$$T_{\alpha,N} = - \begin{bmatrix} g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 & 0 \\ g_2^{(\alpha)} & g_1^{(\alpha)} & g_0^{(\alpha)} & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ g_{N-1}^{(\alpha)} & \ddots & \ddots & \ddots & g_1^{(\alpha)} & g_0^{(\alpha)} \\ g_N^{(\alpha)} & g_{N-1}^{(\alpha)} & \cdots & \cdots & g_2^{(\alpha)} & g_1^{(\alpha)} \end{bmatrix}_{N \times N}$$

- $D_\pm^{(m)} = \text{diag}(d_{\pm,1}^{(m)}, \dots, d_{\pm,N}^{(m)})$ with $d_{\pm,i}^{(m)} := d_\pm(x_i, t_m)$,
- $\nu_{M,N} = \frac{\Delta x^\alpha}{\Delta t}$,
- $f^{(m)} = [f_1^{(m)}, \dots, f_N^{(m)}]^T$ with $f_i^{(m)} := f(x_i, t_m)$,
- $u^{(m)} = [u_1^{(m)}, \dots, u_N^{(m)}]^T$ with $u_i^{(m)}$ a numerical approximation of $u(x_i, t_m)$

Constant coefficients case

Preliminaries: symbol

Def1 Let $f \in L^1(-\pi, \pi]$ and let $\{f_j\}_{j \in \mathbb{Z}}$ the sequence of its Fourier coefficients defined as

$$f_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\theta) e^{-ij\theta} d\theta, \quad j \in \mathbb{Z}.$$

Then the Toeplitz sequence $\{T_n(f)\}_{n \in \mathbb{N}}$ with $T_n(f) = [f_{i-j}]_{i,j=1}^n$ is called the family of Toeplitz matrices generated by f , which in turn is called the **symbol** $\{T_n(f)\}_{n \in \mathbb{N}}$.

Constant coefficients case

Preliminaries: spectral distribution

Def2 Let $f : G \rightarrow \mathbb{C}$ be a measurable function, defined on a measurable set $G \subset \mathbb{R}^k$ with $k \geq 1$, $0 < m_k(G) < \infty$. Let $\{A_N\}$ be a sequence of matrices of size N with eigenvalues $\lambda_j(A_N)$, $j = 1, \dots, N$

- $\{A_N\}$ is distributed as the pair (f, G) in the sense of the eigenvalues, in symbols $\{A_N\} \sim_\lambda (f, G)$, if the following limit relation holds for all $F \in C_0(\mathbb{C})$:

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^N F(\lambda_j(A_N)) = \frac{1}{m_k(G)} \int_G F(f(t)) dt.$$

- The definition of distribution in the sense of the singular values is obtained replacing $\lambda_j \rightarrow \sigma_j$, $f(t) \rightarrow |f(t)|$, $C_0(\mathbb{C}) \rightarrow C_0(\mathbb{R}_0^+)$.

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant** coefficient case $D_{\pm}^{(m)} = d_{\pm} \cdot I$, $d_{\pm} > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of Toeplitz matrices.

Res1 The symbol associated to the matrix-sequence $\{T_{\alpha,N}\}_{N \in \mathbb{N}}$ is given by

$$f_{\alpha}(\theta) = - \sum_{k=-1}^{\infty} g_{k+1}^{(\alpha)} e^{ik\theta} = -e^{-i\theta} \left(1 - e^{i\theta}\right)^{\alpha}.$$

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant** coefficient case $D_{\pm}^{(m)} = d_{\pm} \cdot I$, $d_{\pm} > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of Toeplitz matrices.

Res1 The symbol associated to the matrix-sequence $\{T_{\alpha,N}\}_{N \in \mathbb{N}}$ is given by

$$f_{\alpha}(\theta) = - \sum_{k=-1}^{\infty} g_{k+1}^{(\alpha)} e^{ik\theta} = -e^{-i\theta} \left(1 - e^{i\theta}\right)^{\alpha}.$$

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant and equal** coefficient case $D_{\pm}^{(m)} = d \cdot I$, $d > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of **symmetric** Toeplitz matrices.

Res2 Let us assume that $\nu_{M,N} = o(1)$. Given the matrix-sequence

$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$, we have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (d \cdot p_{\alpha}(\theta), [-\pi, \pi]),$$

where $p_{\alpha}(\theta) = f_{\alpha}(\theta) + f_{\alpha}(-\theta) = f_{\alpha}(\theta) + \overline{f_{\alpha}(\theta)}$ is a real-valued continuous function.

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant and equal** coefficient case $D_{\pm}^{(m)} = d \cdot I$, $d > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of **symmetric** Toeplitz matrices.

Res2 Let us assume that $\nu_{M,N} = o(1)$. Given the matrix-sequence

$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$, we have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (d \cdot p_{\alpha}(\theta), [-\pi, \pi]),$$

where $p_{\alpha}(\theta) = f_{\alpha}(\theta) + f_{\alpha}(-\theta) = f_{\alpha}(\theta) + \overline{f_{\alpha}(\theta)}$ is a real-valued continuous function.

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant and equal** coefficient case $D_{\pm}^{(m)} = d \cdot I$, $d > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of **symmetric** Toeplitz matrices.

Res2 Let us assume that $\nu_{M,N} = o(1)$. Given the matrix-sequence $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$, we have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (d \cdot p_{\alpha}(\theta), [-\pi, \pi]),$$

where $p_{\alpha}(\theta) = f_{\alpha}(\theta) + f_{\alpha}(-\theta) = f_{\alpha}(\theta) + \overline{f_{\alpha}(\theta)}$ is a real-valued continuous function.

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant and equal** coefficient case $D_{\pm}^{(m)} = d \cdot I$, $d > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of **symmetric** Toeplitz matrices.

Res2 Let us assume that $\nu_{M,N} = o(1)$. Given the matrix-sequence $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$, we have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (d \cdot p_{\alpha}(\theta), [-\pi, \pi]),$$

where $p_{\alpha}(\theta) = f_{\alpha}(\theta) + f_{\alpha}(-\theta) = f_{\alpha}(\theta) + \overline{f_{\alpha}(\theta)}$ is a real-valued continuous function.

Constant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Note: In the **constant and equal** coefficient case $D_{\pm}^{(m)} = d \cdot I$, $d > 0$, then $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a sequence of **symmetric** Toeplitz matrices.

Res2 Let us assume that $\nu_{M,N} = o(1)$. Given the matrix-sequence $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$, we have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (d \cdot p_{\alpha}(\theta), [-\pi, \pi]),$$

where $p_{\alpha}(\theta) = f_{\alpha}(\theta) + f_{\alpha}(-\theta) = f_{\alpha}(\theta) + \overline{f_{\alpha}(\theta)}$ is a real-valued continuous function.

Preliminaries: GLT sequences

There are three main features of the GLT class that we shortly mention here.

GLT1 Each GLT sequence has a symbol f in the sense of the singular values over a domain $G = [0, 1]^d \times [-\pi, \pi]^d$ with $d \geq 1$: if the sequence is Hermitian, then the distribution also holds in the eigenvalue sense.

GLT2 The GLT class is a $*$ -algebra. The symbol of linear combinations, products, inversions, conjugations of GLT sequences is obtained by following the same algebraic manipulations on the symbols of the involved GLT sequences.

Preliminaries: GLT sequences

There are three main features of the GLT class that we shortly mention here.

GLT1 Each GLT sequence has a symbol f in the sense of the singular values over a domain $G = [0, 1]^d \times [-\pi, \pi]^d$ with $d \geq 1$: if the sequence is Hermitian, then the distribution also holds in the eigenvalue sense.

GLT2 The GLT class is a $*$ -algebra. The symbol of linear combinations, products, inversions, conjugations of GLT sequences is obtained by following the same algebraic manipulations on the symbols of the involved GLT sequences.

GLT3 Every Toeplitz sequence with symbol f is a GLT sequence with the same symbol. Every sequence of diagonal matrices $\text{diag}(a(j/N))$ where N is the size of the matrix and a is Riemann integrable over $[0, 1]$ is a GLT sequence with symbol a .

Preliminaries: GLT sequences

There are three main features of the GLT class that we shortly mention here.

GLT1 Each GLT sequence has a symbol f in the sense of the singular values over a domain $G = [0, 1]^d \times [-\pi, \pi]^d$ with $d \geq 1$: if the sequence is Hermitian, then the distribution also holds in the eigenvalue sense.

GLT2 The GLT class is a $*$ -algebra. The symbol of linear combinations, products, inversions, conjugations of GLT sequences is obtained by following the same algebraic manipulations on the symbols of the involved GLT sequences.

GLT3 Every Toeplitz sequence with symbol f is a GLT sequence with the same symbol. Every sequence of diagonal matrices $\text{diag}(a(j/N))$ where N is the size of the matrix and a is Riemann integrable over $[0, 1]$ is a GLT sequence with symbol a .

Nonconstant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Let us assume that $\nu_{M,N} = o(1)$ and that, fixed t_m , $d_{\pm}(x) := d_{\pm}(x, t_m)$ are Riemann integrable over $[L, R]$.

Res3 The matrix sequence $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a **GLT sequence** with symbol

$$h_{\alpha}(x, \theta) = d_+(x) f_{\alpha}(\theta) + d_-(x) f_{\alpha}(-\theta), \quad (x, \theta) \in [L, R] \times [-\pi, \pi],$$

and

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\sigma} (h_{\alpha}(x, \theta), [L, R] \times [-\pi, \pi]).$$

If $d_+(x) = d_-(x)$, we also have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (h_{\alpha}(x, \theta), [L, R] \times [-\pi, \pi]).$$

Nonconstant coefficients case

Symbol and spectral distribution of $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$

Recall the coefficient matrix

$$\mathcal{M}_{\alpha,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} T_{\alpha,N} + D_-^{(m)} T_{\alpha,N}^T$$

Let us assume that $\nu_{M,N} = o(1)$ and that, fixed t_m , $d_{\pm}(x) := d_{\pm}(x, t_m)$ are Riemann integrable over $[L, R]$.

Res3 The matrix sequence $\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\}_{N \in \mathbb{N}}$ is a **GLT sequence** with symbol

$$h_{\alpha}(x, \theta) = d_+(x) f_{\alpha}(\theta) + d_-(x) f_{\alpha}(-\theta), \quad (x, \theta) \in [L, R] \times [-\pi, \pi],$$

and

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\sigma} (h_{\alpha}(x, \theta), [L, R] \times [-\pi, \pi]).$$

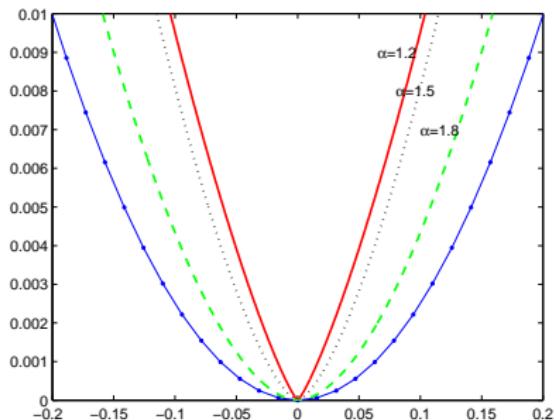
If $d_+(x) = d_-(x)$, we also have

$$\left\{ \mathcal{M}_{\alpha,N}^{(m)} \right\} \sim_{\lambda} (h_{\alpha}(x, \theta), [L, R] \times [-\pi, \pi]).$$

Nonconstant coefficients case

Zero of the symbols $p_\alpha(\theta)$ and $h_\alpha(x, \theta)$

Res4 The function $p_\alpha(\theta)$ has a zero of order $\alpha \in (1, 2)$ at 0.



Comparison between the symbol of the Laplacian operator $\ell(\theta) = 2 - 2 \cos(\theta)$ (blue bullet line) with $p_\alpha(\theta)$ for $\alpha = 1.2$ (red solid line), $\alpha = 1.5$ (black dotted line) and $\alpha = 1.8$ (green dashed line) in a neighborhood of 0.

Res5 If both diffusion coefficients are bounded and positive, the symbol $h_\alpha(x, \theta)$ has always a zero at $\theta = 0$ of order $\alpha < 2$.

CGNR with circulant preconditioner and MGM method

Meth1 Conjugate Gradient for Normal Residual (CGNR) with the circulant preconditioner

$$S_N^{(m)} = \nu_{M,N} I + \bar{d}_+^{(m)} s(T_{\alpha,N}) + \bar{d}_-^{(m)} s(T_{\alpha,N})^T,$$

with $\bar{d}_{\pm}^{(m)} = \frac{1}{N} \sum_{i=1}^N d_{\pm,i}^{(m)}$ and $s(T_{\alpha,N})$ the Strang circulant preconditioner.
Superlinearly convergence in the constant coefficients case^[3].

Meth2 Multigrid method (MGM) with damped-Jacobi as smoother and classical linear interpolation. Optimal convergence of the two-grid in the constant and equal coefficients case^[4].

[3] Lei, Sun, *J. Comput. Phys.*, 2013

[4] Pang, Sun, *J. Comput. Phys.*, 2012

What's new?

Bad news for the circulant preconditioner

- When $\nu_{M,N} = o(1)$, $\{(S_N^{(m)})^{-1} \mathcal{M}_{\alpha,N}^{(m)}\}$ is a GLT sequence such that

$$\{(S_N^{(m)})^{-1} \mathcal{M}_{\alpha,N}^{(m)}\} \sim_{\sigma} \left(\frac{h_{\alpha}(x, \theta)}{g_{\alpha}(\theta)}, [L, R] \times [-\pi, \pi] \right)$$

where $g_{\alpha}(\theta) = \bar{d}_+^{(m)} f_{\alpha}(\theta) + \bar{d}_-^{(m)} f_{\alpha}(-\theta)$. Whenever the diffusion coefficients are nonconstant functions, the preconditioned sequence **CANNOT** be clustered at one, since the function $h_{\alpha}(x, \theta)/g(\theta)$ is a nontrivial function depending on the variable x .

- Circulant preconditioner **CANNOT** give a good clustering in the multidimensional problems also in the constant coefficient setting due to the negative results in [5].

[5] Serra-Capizzano, Tyrtyshnikov, *SIAM J. Matrix Anal. Appl.*, 1999

What's new?

Bad news for the circulant preconditioner

- When $\nu_{M,N} = o(1)$, $\{(S_N^{(m)})^{-1} \mathcal{M}_{\alpha,N}^{(m)}\}$ is a GLT sequence such that

$$\{(S_N^{(m)})^{-1} \mathcal{M}_{\alpha,N}^{(m)}\} \sim_{\sigma} \left(\frac{h_{\alpha}(x, \theta)}{g_{\alpha}(\theta)}, [L, R] \times [-\pi, \pi] \right)$$

where $g_{\alpha}(\theta) = \bar{d}_+^{(m)} f_{\alpha}(\theta) + \bar{d}_-^{(m)} f_{\alpha}(-\theta)$. Whenever the diffusion coefficients are nonconstant functions, the preconditioned sequence **CANNOT** be clustered at one, since the function $h_{\alpha}(x, \theta)/g(\theta)$ is a nontrivial function depending on the variable x .

- Circulant preconditioner **CANNOT** give a good clustering in the multidimensional problems also in the constant coefficient setting due to the negative results in [5].

[5] Serra-Capizzano, Tyrtyshnikov, *SIAM J. Matrix Anal. Appl.*, 1999

What's new?

MGM as a valid alternative

- Constant case Given a sequence of Toeplitz matrices $\{A_N\}_{N \in \mathbb{N}}$ with a nonnegative symbol f , if the grid transfer operator is the classical linear interpolation, for the convergence analysis of the V-cycle it has to hold

$$\limsup_{\theta \rightarrow 0} \frac{2 + 2 \cos(\theta + \pi)}{f(\theta)} = c < \infty.$$

Under the assumption $\nu_{M,N} = o(1)$ and $d_{\pm}(x, t) = d > 0$, the symbol of the Toeplitz sequence $\{\mathcal{M}_{\alpha, N}^{(m)}\}_{N \in \mathbb{N}}$ is $f(\theta) = d \cdot p_{\alpha}(\theta)$ and it satisfies this condition with $c = 0$.

- Nonconstant case When d_+ and d_- are uniformly bounded and positive the optimality of the MGM is preserved.

Theoretical results contained in [6,7] allow to expect the same behaviour of the MGM also in the multidimensional case.

[6] Aricò, Donatelli, *Numer. Math.*, 2007
[7] Serra-Capizzano, *Numer. Math.*, 2002

What's new?

MGM as a valid alternative

- Constant case Given a sequence of Toeplitz matrices $\{A_N\}_{N \in \mathbb{N}}$ with a nonnegative symbol f , if the grid transfer operator is the classical linear interpolation, for the convergence analysis of the V-cycle it has to hold

$$\limsup_{\theta \rightarrow 0} \frac{2 + 2 \cos(\theta + \pi)}{f(\theta)} = c < \infty.$$

Under the assumption $\nu_{M,N} = o(1)$ and $d_{\pm}(x, t) = d > 0$, the symbol of the Toeplitz sequence $\{\mathcal{M}_{\alpha, N}^{(m)}\}_{N \in \mathbb{N}}$ is $f(\theta) = d \cdot p_{\alpha}(\theta)$ and it satisfies this condition with $c = 0$.

- Nonconstant case When d_+ and d_- are uniformly bounded and positive the optimality of the MGM is preserved.

Theoretical results contained in [6,7] allow to expect the same behaviour of the MGM also in the multidimensional case.

- [6] Aricò, Donatelli, *Numer. Math.*, 2007
- [7] Serra-Capizzano, *Numer. Math.*, 2002

What's new?

Structure preserving preconditioners for CGNR and GMRES

Why preserving the structure?

- overcome negative results in the multidimensional case;
- have a preconditioned linear system with a well-conditioned matrix of the eigenvectors.

① First preconditioner

$$P_{1,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} B_N + D_-^{(m)} B_N^T,$$

where $B_N = \text{tridiag}_N(0, 1, -1)$ is an approximation of the first derivative operator.

② Second preconditioner

$$P_{2,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} L_N + D_-^{(m)} L_N^T,$$

where $L_N = \text{tridiag}_N(-1, 2, -1)$ is the Laplacian matrix.

What's new?

Structure preserving preconditioners for CGNR and GMRES

$$P_{1,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} B_N + D_-^{(m)} B_N^T$$

$$P_{2,N}^{(m)} = \nu_{M,N} I + D_+^{(m)} L_N + D_-^{(m)} L_N^T$$

Computational cost: $P_{1,N}^{(m)}$, $P_{2,N}^{(m)}$ tridiagonal $\rightarrow O(N)$ operations for the associated system $\rightarrow O(N \log N)$ operations for preconditioned Krylov method.

Spectral properties: Both $P_{1,N}^{(m)}$ and $P_{2,N}^{(m)}$ cannot provide a clustering of the singular values or of the eigenvalues of the preconditioned linear system just as the circulant preconditioner $S_N^{(m)}$.

Numerical Example: nonconstant coefficient case

The following example consists in an anomalous diffusive process of a Gaussian pulse

$$\begin{cases} \frac{\partial u(x,t)}{\partial t} = d_+(x,t) \frac{\partial^\alpha u(x,t)}{\partial_+ x^\alpha} + d_-(x,t) \frac{\partial^\alpha u(x,t)}{\partial_- x^\alpha} + f(x,t), & (x,t) \in (0,2) \times (0,1], \\ u(0,t) = u(2,t) = 0, & t \in [0,1], \\ u(x,0) = u_0(x), & x \in [0,2]. \end{cases}$$

- diffusion coefficients:

$$d_+(x,t) = 0.1(1+x^2+t^2), \quad d_-(x,t) = 0.1(1+(2-x)^2+t^2)$$

- source term:

$$f(x,t) = 0$$

- initial condition

$$u_0(x) = e^{-\frac{(x-x_c)^2}{2\sigma^2}}$$

with $x_c = 1.2$ and $\sigma = 0.08$

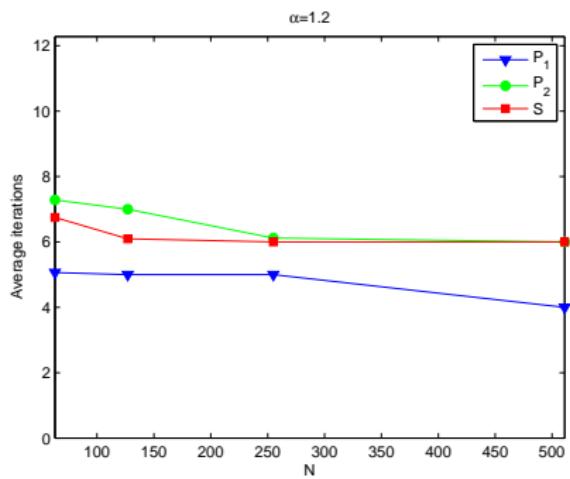
- $\Delta x = \Delta t$, $\nu_{M,N} = \frac{\Delta x^\alpha}{\Delta t} = \Delta x^{\alpha-1}$ which, being $0 < \alpha - 1 < 1$, tends to zero as N tends to ∞ .

Numerical Example: nonconstant coefficient case

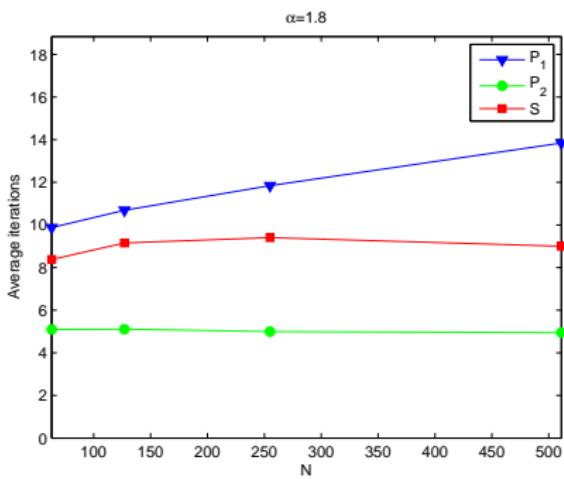
The number of iterations is computed as $\frac{1}{M} \sum_{m=1}^M \text{Iter}(m)$, where $\text{Iter}(m)$ is the number of required iterations at time t_m , $m = 0, \dots, M$. (tolerance = 10^{-7})

α	$N + 1$	P_1		P_2		S	
		CGNR	GMRES	CGNR	GMRES	CGNR	GMRES
1.2	2^6	5.1	5.0	7.3	6.6	6.8	7.6
	2^7	5.0	5.0	7.0	5.1	6.1	7.0
	2^8	5.0	4.8	6.1	4.1	6.0	7.0
	2^9	4.0	4.0	6.0	3.4	6.0	6.9
1.5	2^6	7.1	8.8	7.0	5.6	7.2	8.4
	2^7	6.8	9.2	7.0	5.1	7.1	8.8
	2^8	6.2	9.2	7.0	5.0	7.0	8.8
	2^9	6.0	9.4	6.5	5.0	7.0	8.7
1.8	2^6	9.9	14.6	5.1	4.9	8.4	8.0
	2^7	10.7	18.7	5.1	5.0	9.2	8.0
	2^8	11.8	23.3	5.0	5.0	9.4	7.9
	2^9	13.8	29.0	4.9	5.0	9.0	7.8

Structure preserving preconditioners for CGNR

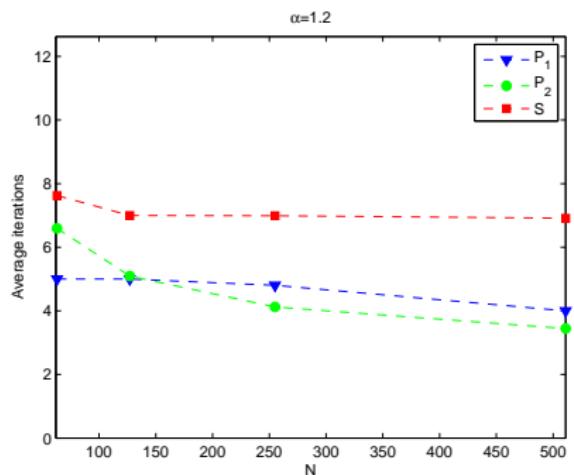


Average number of iterations
varying N for $\alpha = 1.2$

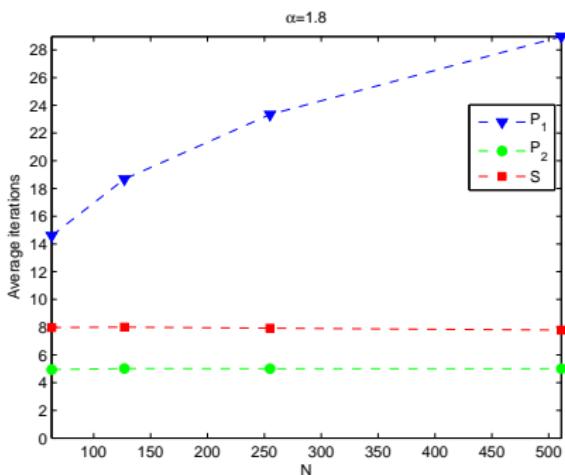


Average number of iterations
varying N for $\alpha = 1.8$

Structure preserving preconditioners for GMRES



Average number of iterations
varying N for $\alpha = 1.2$



Average number of iterations
varying N for $\alpha = 1.8$

Conclusions

- Asymptotic eigenvalue/singular value distribution for nonconstant coefficient FDEs.
- Analysis of known methods of preconditioned Krylov and multigrid type, with both positive and negative results.
- Two new tridiagonal structure preserving preconditioners.

Future works

A future work will concern a detailed analysis of the problem in the multidimensional setting where a promising technique seems to be the use of appropriate multigrid strategies.

-  Aricò A., Donatelli M., (2007) A V-cycle Multigrid for multilevel matrix algebras: proof of optimality, *Numer. Math.*, Vol. 105-4, pp. 511–547.
-  Donatelli M., Mazza M., Serra-Capizzano S., (2015) Spectral analysis and structure preserving preconditioners for fractional diffusion equations, *Technical report/Department of Information Technology, Uppsala University, ISSN 1404-3203; 2015-002*, manuscript submitted for publication
-  Lei S.L., Sun H.W., (2013) A circulant preconditioner for fractional diffusion equations, *J. Comput. Phys.*, Vol. 242, pp. 715–725.
-  Meerschaert M.M., Tadjeran C., (2004) Finite difference approximations for fractional advection-dispersion flow equations, *J. Comput. Appl. Math.*, Vol. 172, pp. 65–77.
-  Meerschaert M.M., Tadjeran C., (2006) Finite difference approximations for two-sided space-fractional partial differential equations, *Appl. Numer. Math.*, Vol. 56-1, pp. 80–90.
-  Pang H., Sun H.W., (2012) Multigrid method for fractional diffusion equations, *J. Comput. Phys.*, Vol. 231, pp. 693–703.
-  Serra-Capizzano S., (2002) Convergence analysis of Two-Grid methods for elliptic Toeplitz and PDEs matrix-sequences, *Numer. Math.*, Vol. 92-3, pp. 433–465.
-  Serra-Capizzano S., (2006) The GLT class as a generalized Fourier Analysis and applications, *Linear Algebra Appl.*, Vol. 419, pp. 180–233.
-  Serra-Capizzano S., Tyrtyshnikov E., (1999) Any circulant-like preconditioner for multilevel matrices is not superlinear, *SIAM J. Matrix Anal. Appl.*, Vol. 21-2, pp. 431–439.