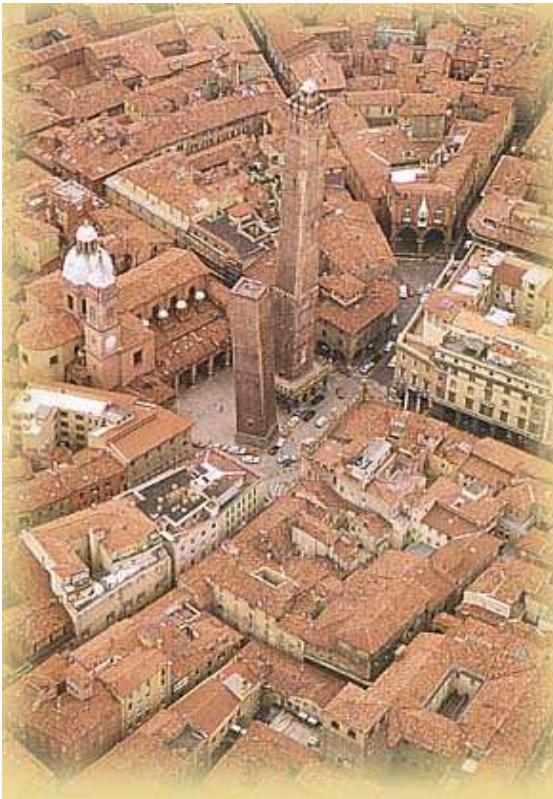




Precondizionatori Strutturati per Sistemi algebrici di Punto Sella

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Application problems



- Computational Fluid Dynamics
- Elasticity problems
- Mixed (FE) formulations of II and IV order elliptic PDEs
- Linearly Constrained Programs
- Linear Regression in Statistics
- Weighted Least Squares (Image restoration)
- ... Survey: Benzi, Golub and Liesen, Acta Num 2005

$$\begin{bmatrix} A & B^T \\ B & -C \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} f \\ g \end{bmatrix}$$

Constrained Quadratic minimization problem

$$\text{minimize} \quad J(u) = \frac{1}{2} \langle Au, u \rangle - \langle f, u \rangle$$

subject to $Bu = g$

$A \quad n \times n \quad \text{spd}, \quad B \ m \times n, \ m \leq n$ full rank



Lagrange multipliers approach

Karush-Kuhn-Tucker (KKT) system

Spectral properties



- $\mathcal{M} = \begin{bmatrix} A & B^T \\ B & O \end{bmatrix}$ $0 < \lambda_n \leq \dots \leq \lambda_1$ eigs of A
 $0 < \sigma_m \leq \dots \leq \sigma_1$ sing. vals of B

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- (Rusten & Winther 1992) $\Lambda(\mathcal{M})$ subset of

$$\left[\frac{1}{2}(\lambda_n - \sqrt{\lambda_n^2 + 4\sigma_1^2}), \frac{1}{2}(\lambda_1 - \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right] \cup \left[\lambda_n, \frac{1}{2}(\lambda_1 + \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right]$$

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- (Silvester & Wathen 1994), $0 \leq \sigma_m \leq \dots \leq \sigma_1$

$$\lambda_n - \lambda_{\max}(C) - \sqrt{(\lambda_n + \lambda_{\max}(C))^2 + 4\sigma_1^2}$$

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More results for special cases (e.g., Perugia & S. 2000)

Block diagonal Preconditioner



$$\mathcal{P} = \begin{bmatrix} \tilde{A} & 0 \\ 0 & \tilde{C} \end{bmatrix} \quad \text{sym. pos. def.}$$

$$\tilde{A} \approx A \quad \tilde{C} \approx BA^{-1}B^T + C$$

Rosten Winther (1992), Silvester Wathen (1993-1994), Klawonn (1998)

Fischer Ramage Silvester Wathen (1998...), . . .

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$\lambda \neq 0$ eigs of $\mathcal{P}^{-\frac{1}{2}} \mathcal{M} \mathcal{P}^{-\frac{1}{2}}$,

$$\lambda \in [-a, -b] \cup [c, d], \quad a, b, c, d > 0$$

Triangular preconditioner

$$A \text{ spd}, \quad \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ 0 & -\tilde{C} \end{bmatrix}$$

Bramble & Pasciak, Elman, Klawonn, Axelsson & Neytcheva, S. 2004

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Spectrum of $\mathcal{M}\mathcal{P}^{-1}$:

small complex cluster around 1 + real interval

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Spectrum of $\mathcal{M}\mathcal{P}^{-1}$:

small complex cluster around 1 + real interval

More precisely: $\theta \in \Lambda(\mathcal{M}\mathcal{P}^{-1})$

$$\Im(\theta) \neq 0 \Rightarrow |\theta - 1| \leq \sqrt{1 - \lambda_{\min}(A\tilde{A}^{-1})} \quad (\text{if } 1 - \lambda_{\min}(A\tilde{A}^{-1}) \geq 0)$$

$$\Im(\theta) = 0 \Rightarrow \theta \in [\chi_1, \chi_2] \ni 1$$

Constraint Preconditioner

$$Q = \begin{bmatrix} \tilde{A} & B^T \\ B & -C \end{bmatrix}$$

Axelsson (1979), Ewing Lazarov Lu Vassilevski (1990), ... many more papers 1997 -

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$$\lambda \neq 0 \text{ eigs of } \mathcal{M}\mathcal{Q}^{-1}, \quad \lambda \in \mathbb{R}^+, \quad \lambda \in \{1\} \cup [\alpha_0, \alpha_1]$$

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$$\mathcal{Q}^{-1} = \begin{bmatrix} I & -B^T \\ O & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -(\mathbf{B}\mathbf{B}^T + \mathbf{C})^{-1} \end{bmatrix} \begin{bmatrix} I & O \\ -B & I \end{bmatrix}$$

($\tilde{A} = I$ if prescaling used)

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Results on eigenvectors (Dollar tr05)

More general factorizations (Dollar& Gould & Schilders & Wathen 06, Bergamaschi & Gondzio & Venturini & Zilli, tr05)

Computational Considerations.



3D Magnetostatic problem

$H \approx BB^T + C$ with H : Incomplete Cholesky fact.
(ICT package, Saad & Chow)

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Elapsed Time

size	MA27	QMR		QMR ILDLT(10)	
		\mathcal{Q}	$\widehat{\mathcal{Q}}(2)(it)$		
1119	0.6	3.0	1.7(18)	0.7	
2208	2.3	11.7	3.1(18)	1.5	
4371	10.2	64.6	8.4(20)	5.2	
8622	83.4	466.0	18.3(29)	31.0	
22675	753.5	3745.5	63.2(45)	246.0	

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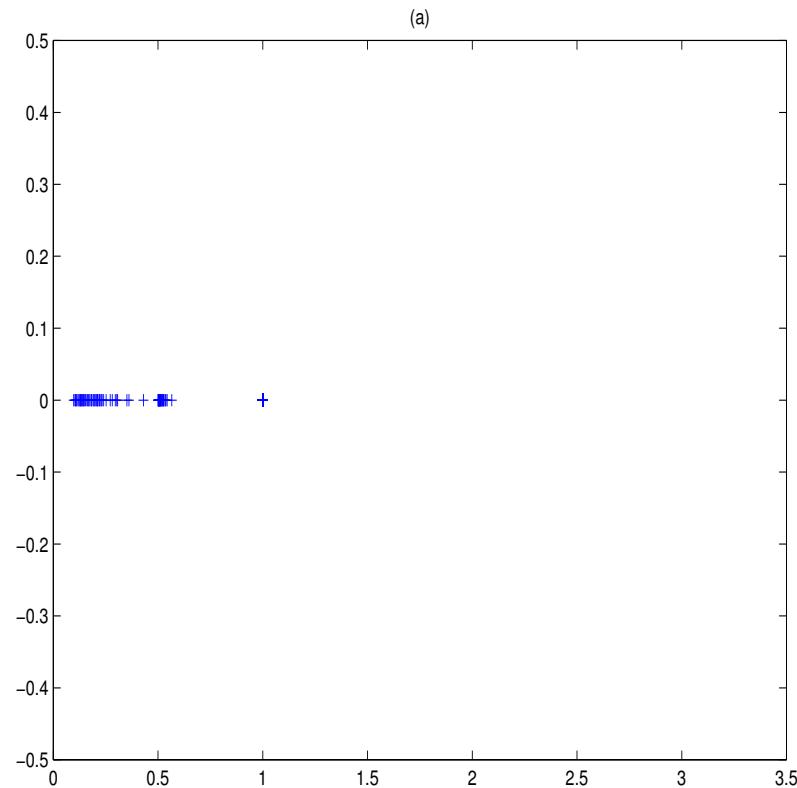
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8622	83.4	466.0	18.3(29)	31.0	510.1	24.3
22675	753.5	3745.5	63.2(45)	246.0	4161.4	128.2

Spectrum of perturbed problem



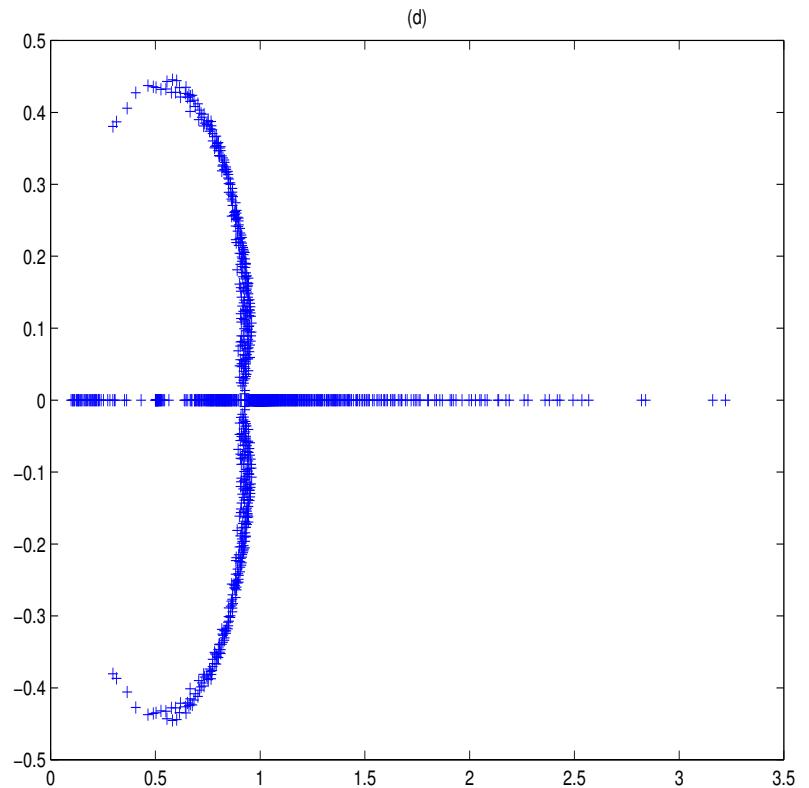
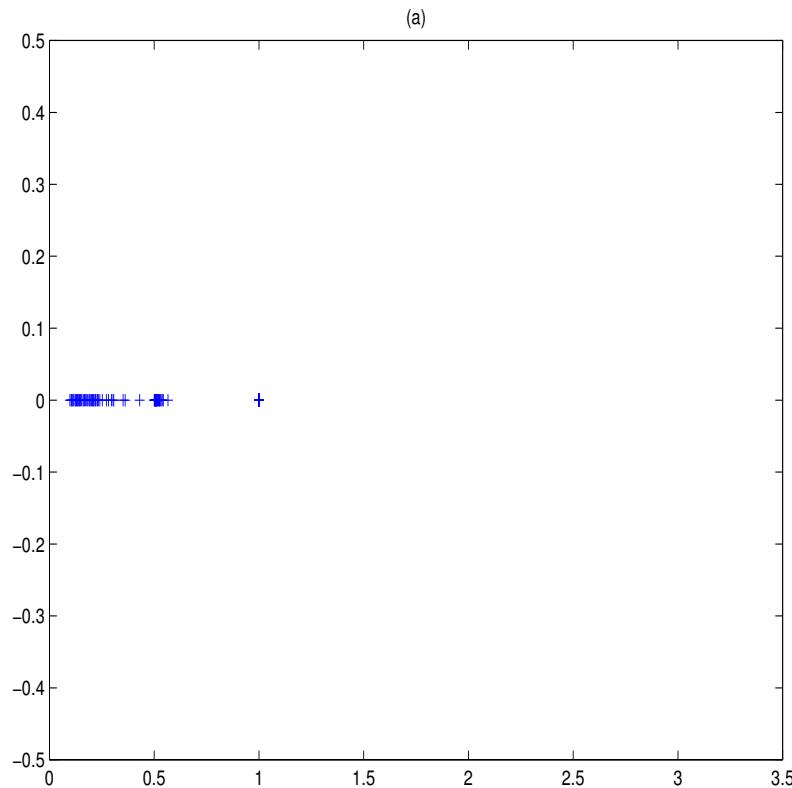
3D Magnetostatic problem



Spectrum of perturbed problem



3D Magnetostatic problem



$$\|(BB^T + C) - H\|_\infty \approx 2 \cdot 10^{-1} \|BB^T + C\|_\infty$$

Eigenvalue problem

$$\widehat{\mathcal{Q}} = \begin{bmatrix} I & O \\ B & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} I & B^T \\ O & I \end{bmatrix}, \quad H \approx BB^T, \quad C = O$$

$$\begin{bmatrix} A & B^T \\ B & O \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \lambda \widehat{\mathcal{Q}} \begin{bmatrix} x \\ y \end{bmatrix}$$

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can be written as

$$\begin{bmatrix} I & O \\ -B & I \end{bmatrix} \begin{bmatrix} A & B^T \\ B & O \end{bmatrix} \begin{bmatrix} I & -B^T \\ O & I \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

$$\begin{bmatrix} A & (I-A)B^T \\ B(I-A) & -B(2I-A)B^T \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

A “*different*” perspective

$$\begin{bmatrix} A & B^T \\ -B & C \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} f \\ -g \end{bmatrix} \quad \mathcal{M}_-x = d$$

Polyak 1970, ..., Wathen & Fischer & Silvester 1995, Fischer & Ramage & Silvester & Wathen 1998,
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- \mathcal{M} positive real $\Rightarrow \Lambda(\mathcal{M}_-) \text{ in } \mathbb{C}^+$

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- \mathcal{M} positive real $\Rightarrow \Lambda(\mathcal{M}_-)$ in \mathbb{C}^+
- More refined spectral information possible
- New classes of preconditioners
- General framework for spectral analysis of some indefinite preconditioners

Spectral properties of \mathcal{M}_-



$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & C \end{bmatrix}$$

A $n \times n$ sym. semidef. matrix, B $m \times n$, $m \leq n$

\mathcal{M}_- has at least $n - m$ real eigenvalues

Detailed analysis for $A = \eta I, C = O$ in:

- ★ Fischer & Ramage & Silvester & Wathen 1998
- ★ Fischer & Peherstorfer 2001

Reality condition



Let A be spd and $C = \beta I$, β real. If

$$\lambda_{\min}(A + \beta I) \geq 4 \lambda_{\max}(B^T A^{-1} B + \beta I),$$

then all eigenvalues of \mathcal{M}_- are real (and positive)

Benzi & S. 2006

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Benzi & S. 2006

The condition is sufficient, but not necessary:

$$\mathcal{M}_- = \left[\begin{array}{cc|c} \frac{1}{2} & 0 & 0 \\ 0 & 3 & 1 \\ \hline 0 & -1 & 0 \end{array} \right], \quad \begin{aligned} \lambda_{\min}(A) &= \frac{1}{2} \\ \lambda_{\max}(BA^{-1}B) &= \frac{1}{3} \end{aligned}$$

has real spectrum, but does not satisfy the condition

The (steady-state) Stokes problem

$$\left\{ \begin{array}{ll} -\Delta \mathbf{u} + \nabla p = \mathbf{f} & \text{in } \Omega \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \\ \mathcal{B}\mathbf{u} = \mathbf{g} & \text{on } \Gamma . \end{array} \right. \Rightarrow \mathcal{M}_\pm$$

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Numerical evidence: eigs of \mathcal{M}_- are all real and positive
(for several discretizations and b.c.)

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Numerical evidence: eigs of \mathcal{M}_- are **all** real and positive

(for several discretizations and b.c.)

Explanation:

$\Omega = [0, 1] \times [0, 1]$, Dirichlet b.c. div-stable discr.

$$\lambda_{\min}(A) \approx 2\pi^2 \approx 19,$$

$$\lambda_{\max}(BA^{-1}B^T) \approx 1$$

$$\Rightarrow \lambda_{\min}(A) > 4\lambda_{\max}(BA^{-1}B^T)$$

(In)definite inner product

$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & C \end{bmatrix}$$

$$J = \begin{bmatrix} I & O \\ O & -I \end{bmatrix}$$

J indefinite

\mathcal{M}_- is *J*-sym.

(In)definite inner product

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If $\Lambda(\mathcal{M}_-) \subset \mathbb{R}^+$, there exists a nonstandard inner product with which \mathcal{M}_- is spd (and diag.ble)

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If $\Lambda(\mathcal{M}_-) \subset \mathbb{R}^+$, there exists a nonstandard inner product with which \mathcal{M}_- is spd (and diag.ble)

$$G = \begin{bmatrix} A - \gamma I & B^T \\ B & \gamma I \end{bmatrix}, \quad \mathcal{M}_- G = G \mathcal{M}_-^T$$

(In)definite inner product

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If $\Lambda(\mathcal{M}_-) \subset \mathbb{R}^+$, there exists a nonstandard inner product with which \mathcal{M}_- is spd (and diag.ble)

$$G = \begin{bmatrix} A - \gamma I & B^T \\ B & \gamma I \end{bmatrix}, \quad \mathcal{M}_- G = G \mathcal{M}_-^T$$

If $\gamma = \frac{1}{2}\lambda_{\min}(A)$ and $\lambda_{\min}(A) > 4\lambda_{\max}(BA^{-1}B^T)$ (with $C = O$)

$\Rightarrow G$ is spd $\Rightarrow G$ defines an inner product for \mathcal{M}_-

Preconditioning

$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & C \end{bmatrix} = \begin{bmatrix} A & O \\ O & C \end{bmatrix} + \begin{bmatrix} O & B^T \\ -B & O \end{bmatrix}$$
$$= \mathcal{H} + \mathcal{S}$$

Preconditioning

$$\mathcal{M}_- = \begin{bmatrix} A & B^T \\ -B & C \end{bmatrix} = \begin{bmatrix} A & O \\ O & C \end{bmatrix} + \begin{bmatrix} O & B^T \\ -B & O \end{bmatrix}$$

$$= \mathcal{H} + \mathcal{S}$$

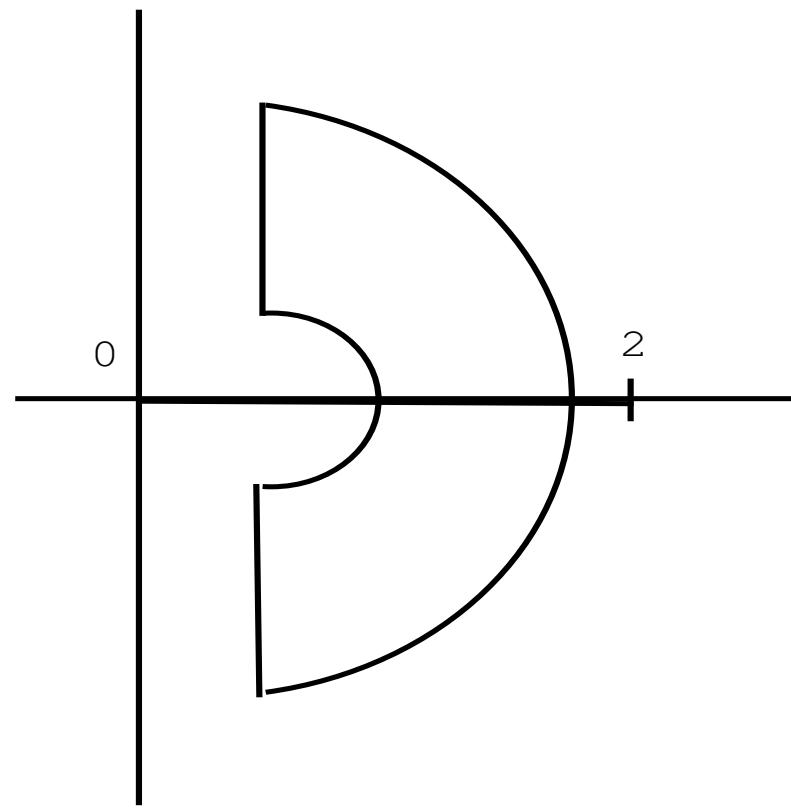
Use the preconditioner

$$\mathcal{R}_\alpha = \frac{1}{2\alpha} (\mathcal{H} + \alpha I)(\mathcal{S} + \alpha I) \quad \alpha \in \mathbb{R}, \alpha > 0$$

(Bai & Golub & Ng 2003), Benzi & Gander & Golub 2003, Benzi & Golub 2004, S. & Benzi 2004, Benzi & Ng, 2004

Spectral bounds

Spectrum of $\mathcal{R}_\alpha^{-1} \mathcal{M}_-$ (case $C = 0$)



(S. & Benzi 2004)

Reality condition



Assume A is spd and $C = 0$. If

$$\alpha \leq \frac{1}{2}\lambda_{\min}(A)$$

then all eigenvalues of $\mathcal{R}_\alpha^{-1}\mathcal{M}_-$ are real (S. & Benzi '04)

Reality condition

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then all eigenvalues of $\mathcal{R}_\alpha^{-1}\mathcal{M}_-$ are real (S. & Benzi '04)

But even more general:

If $\lambda_{\min}(A) > 4\lambda_{\max}(BA^{-1}B^T)$ then

all eigenvalues are **real** for **any** α

(cf. Stokes problem)

Location of \mathcal{M}_- 's spectrum

Let $\lambda \in \Lambda(\mathcal{M}_-)$, $x = [u; v]$ e'vect., A spd (cf. Sidi '03, $C = O$)

- ★ If $\Im(\lambda) \neq 0$ then

$$\begin{aligned}\frac{1}{2}(\lambda_{\min}(A) + \lambda_{\min}(C)) \leq \quad \Re(\lambda) \quad &\leq \frac{1}{2}(\lambda_{\max}(A) + \lambda_{\max}(C)) \\ |\Im(\lambda)| \quad &\leq \sigma_{\max}(B).\end{aligned}$$

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- ★ If $\Im(\lambda) = 0$ then for $v \neq 0$

$$\min\{\lambda_{\min}(A), \lambda_{\min}(C)\} \leq \lambda \leq \max\{\lambda_{\max}(A), \lambda_{\max}(C)\}$$

and for $v = 0$, $\lambda_{\min}(A) \leq \lambda \leq \lambda_{\max}(A)$

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$$\min\{\lambda_{\min}(A), \lambda_{\min}(C)\} \leq \lambda \leq \max\{\lambda_{\max}(A), \lambda_{\max}(C)\}$$

and for $v = 0$, $\lambda_{\min}(A) \leq \lambda \leq \lambda_{\max}(A)$

$$\mathcal{M}_- = \left[\begin{array}{cc|c} 2 & 0 & 1 \\ 0 & 1 & 0 \\ \hline -1 & 0 & 1 \end{array} \right] \quad \lambda_1 = 1, \quad \lambda_{2,3} = \frac{3}{2} \pm i \frac{\sqrt{3}}{2}.$$

Inexact Indefinite Precond.

$$\begin{bmatrix} A & (I - A)B^T \\ B(I - A) & -B(2I - A)B^T \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

Inexact Indefinite Precond.

$$\begin{bmatrix} A & (I - A)B^T \\ B(I - A) & -B(2I - A)B^T \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

Eigenvalue bounds: Let $\widehat{C} = B(2I - A)B^T H^{-1}$

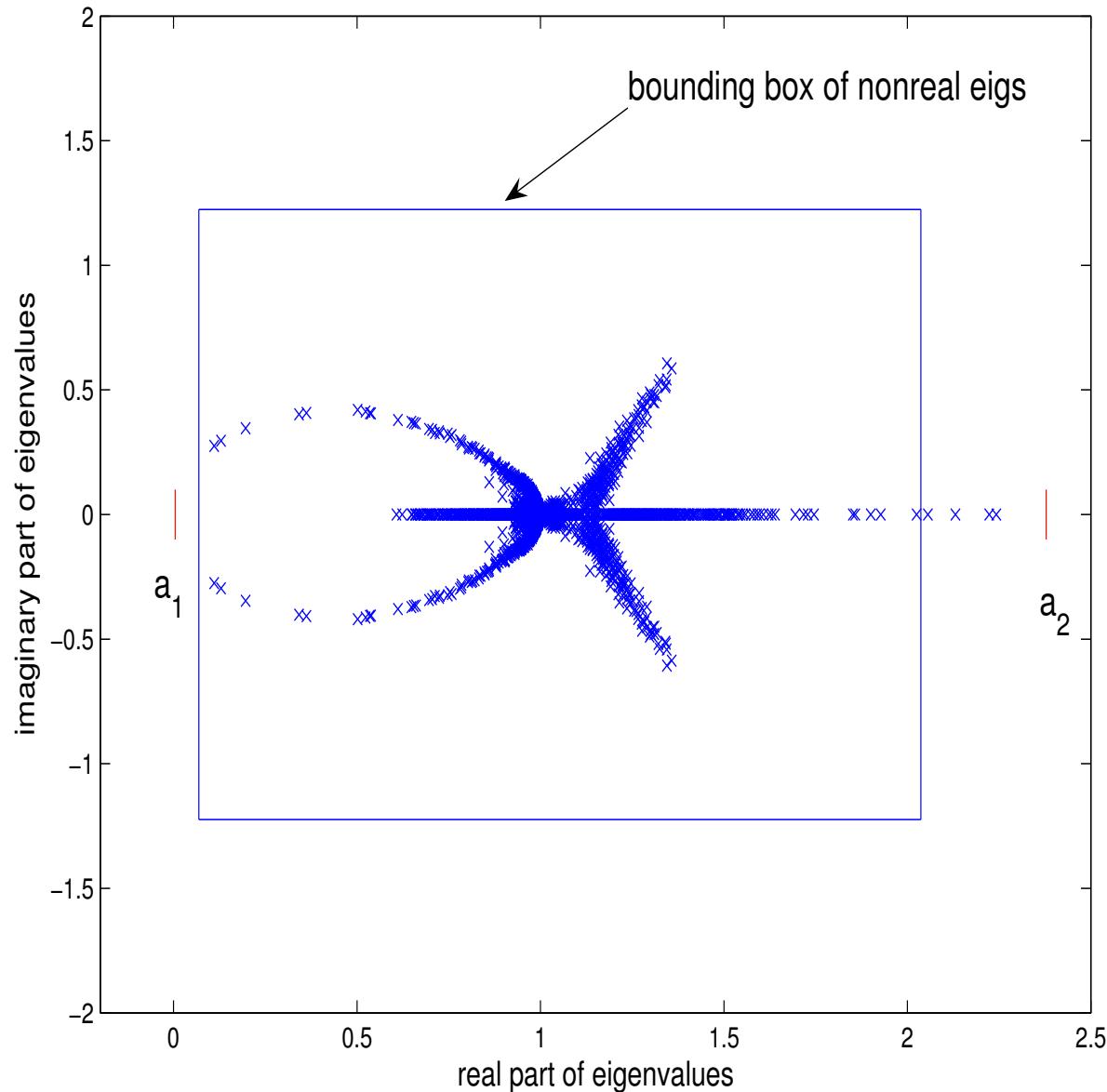
★ If $\Im(\lambda) \neq 0$ then

$$\begin{aligned} \frac{1}{2}(\lambda_{\min}(A) + \lambda_{\min}(\widehat{C})) \leq \Re(\lambda) &\leq \frac{1}{2}(\lambda_{\max}(A) + \lambda_{\max}(\widehat{C})) \\ |\Im(\lambda)| &\leq \sigma_{\max}((I - A)BH^{-\frac{1}{2}}). \end{aligned}$$

★ If $\Im(\lambda) = 0$ then

$$\min\{\lambda_{\min}(A), \lambda_{\min}(\widehat{C})\} \leq \lambda \leq \max\{\lambda_{\max}(A), \lambda_{\max}(\widehat{C})\}$$

Spectral bounds



Final Considerations



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- Visit <http://www.dm.unibo.it/~simoncin>