



Kronecker sums of matrices

Computation, sparsity properties and applications

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Partially joint work with Michele Benzi, Emory Univ., and also with Claudio Canuto (PoliTo) and Marco Verani (PoliMi)

The Lyapunov operator

Given $M \in \mathbb{R}^{n \times n}$,

$$\mathcal{L} : X \mapsto MX + XM^T \quad \text{or} \quad \ell : x \mapsto (I \otimes M + M \otimes I)x$$

- A structured matrix
- A mathematical tool

In general: $\mathcal{L} : X \mapsto M_1X + XM_2^T$, with $M_1 \in \mathbb{R}^{n \times n}$, $M_2 \in \mathbb{R}^{m \times m}$

(Sylvester operator)

The Poisson equation - revisited

$$-u_{xx} - u_{yy} = f, \quad \text{in } \Omega = (0, 1)^2$$

+ Dirichlet b.c. (zero b.c. for simplicity)

Usual discretization $\Rightarrow Au = b$ (with $A = T \otimes I + I \otimes T$, $b = \text{vec}(F)$)

Discretization: $U_{i,j} \approx u_{x_i, y_j}$, with (x_i, y_j) interior nodes, so that

$$u_{xx}(x_i, y_j) \approx \frac{U_{i-1,j} - 2U_{i,j} + U_{i+1,j}}{h^2} = \frac{1}{h^2} [1, -2, 1] \begin{bmatrix} U_{i-1,j} \\ U_{i,j} \\ U_{i+1,j} \end{bmatrix}$$

$$u_{yy}(x_i, y_j) \approx \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{h^2} = \frac{1}{h^2} [U_{i,j-1}, U_{i,j}, U_{i,j+1}] \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

h : meshsize

The Poisson equation - matrix formulation

Let $T = \frac{1}{h^2} \text{tridiag}(-1, 2, -1)$

$$u_{xx}(x_i, y_j) \approx \frac{1}{h^2} [1, -2, 1] \begin{bmatrix} U_{i-1,j} \\ U_{i,j} \\ U_{i+1,j} \end{bmatrix} \quad u_{yy}(x_i, y_j) \approx \frac{1}{h^2} [U_{i,j-1}, U_{i,j}, U_{i,j+1}] \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

Collecting all nodes together,

$$-u_{xx} \approx TU, \quad -u_{yy} \approx UT$$

Therefore,

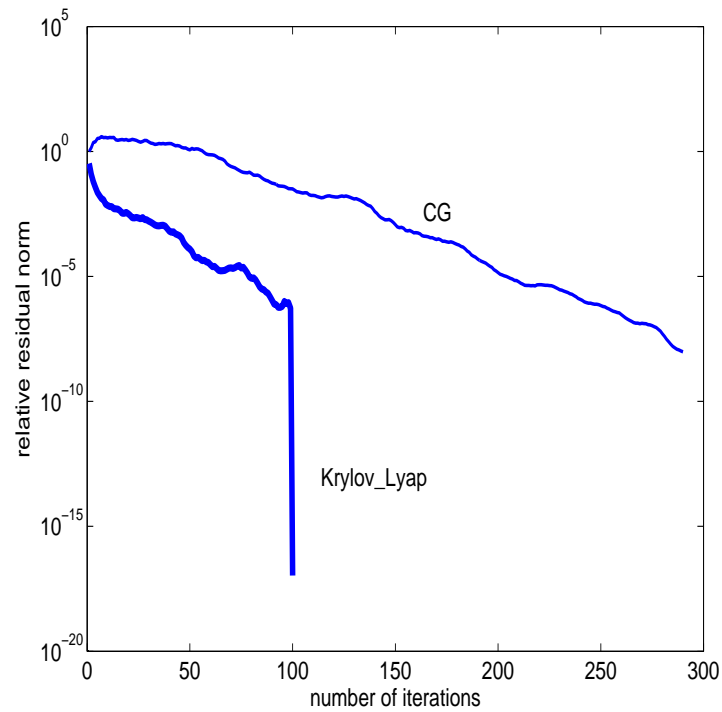
$$-u_{xx} - u_{yy} = f \quad \Rightarrow \quad TU + UT = F$$

(here $F_{ij} = f(x_i, y_j)$)

To be compared with $Au = b$

CG for $Ax = b$ vs Iterative solver for $TU + UT = F$

$$T \in \mathbb{R}^{n \times n}, A \in \mathbb{R}^{n^2 \times n^2}, \quad n = 100$$



For $\text{tol} = 10^{-6}$, Elapsed time: $\text{CG} \approx 0.8$, $\text{Krylov} \approx 0.4$

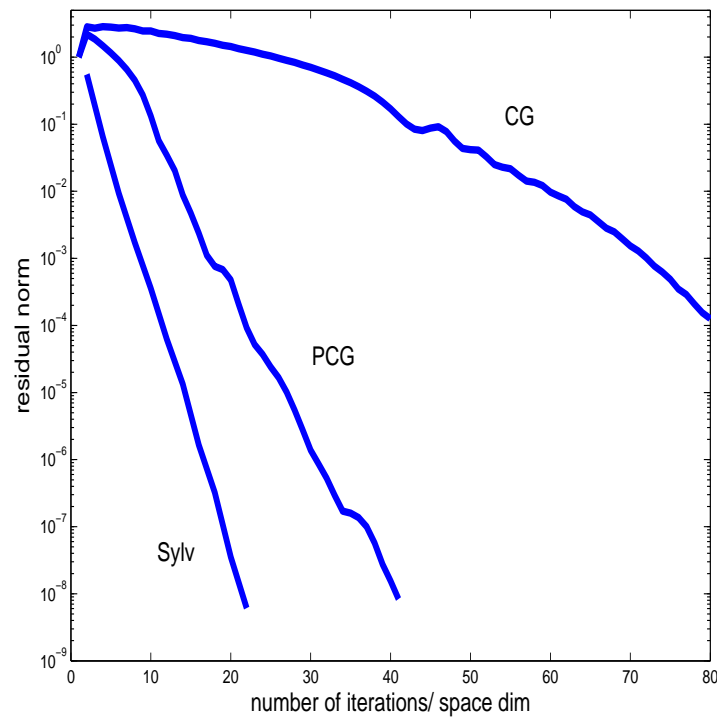
```
>> tic;lyap(T,F);toc
Elapsed time is 0.019335 seconds.
>> tic;A\b;toc
Elapsed time is 0.030765 seconds.
```

$$-\Delta u = 1, \quad \Omega = (0, 1)^3 \quad \Rightarrow \quad A = (T \otimes I \otimes I + I \otimes T \otimes I + I \otimes I \otimes T)$$

$$-\Delta u = 1, \quad \Omega = (0, 1)^3 \quad \Rightarrow \quad A = (T \otimes I \otimes I + I \otimes T \otimes I + I \otimes I \otimes T)$$

CG for $Ax = b$ vs Iterative solver for $(I \otimes T + T \otimes I)U + UT = F$

$$T \in \mathbb{R}^{n \times n}, \quad A \in \mathbb{R}^{n^3 \times n^3}, \quad n = 50$$



	CG	PCG	Matrix Eqn solver
Elapsed Time	2.91	0.56	0.08

... A classical approach

Matrix formulation is not new...

- Bickley & McNamee, 1960: Early literature on difference equations
- Wachspress, 1963: Model problem for ADI algorithm
- Ellner & Wachspress (1980's): interplay between the matrix and vector formulations (via preconditioning)

The stiffness matrix

$$S_g := M_1 \otimes I_n + I_n \otimes M_2$$

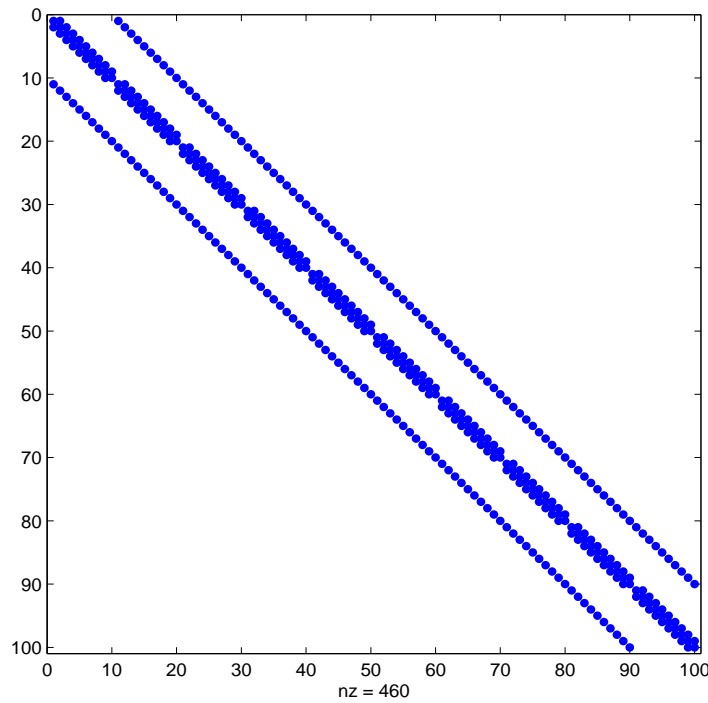
with $M_1 \neq M_2$, banded, with not necessarily the same dimensions

- Finite differences: M_j second order operator in one space dimension
 - \Rightarrow e.g., S_g : 2D Laplace operator in $[a, b]^2$
 - \Rightarrow e.g., S_g : 2D conv-diff operator with separable coeff.
- Legendre Spectral methods: $M_1 = M_2$ spd, nonconstant diag.
- ...

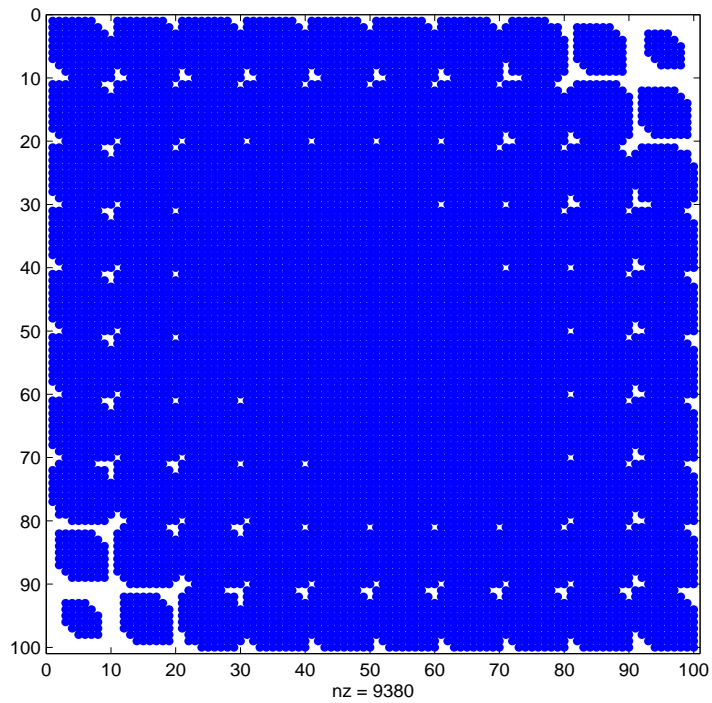
The inverse of the 2D Laplace matrix on the unit square

$$S := M \otimes I_n + I_n \otimes M, \quad M = \text{tridiag}(-1, 2, -1)$$

Sparsity pattern:



Matrix S

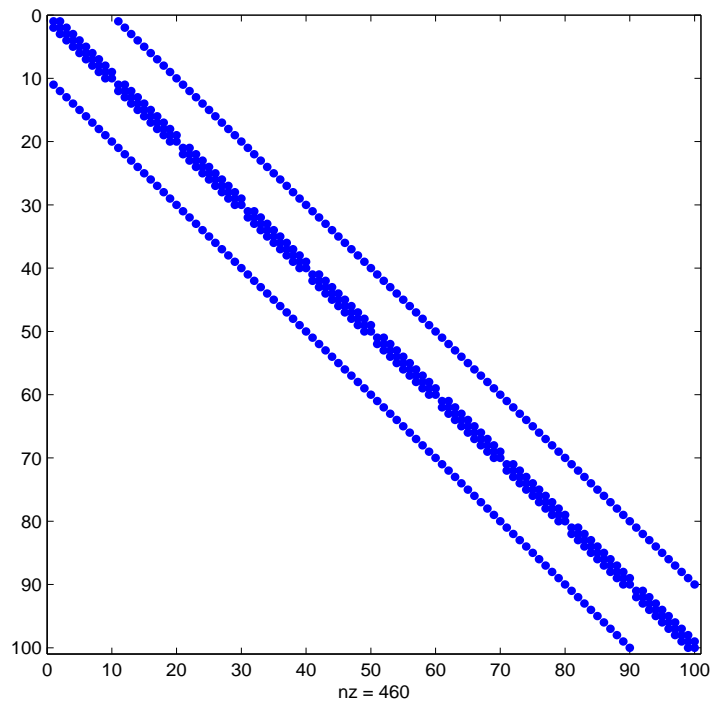


S^{-1}

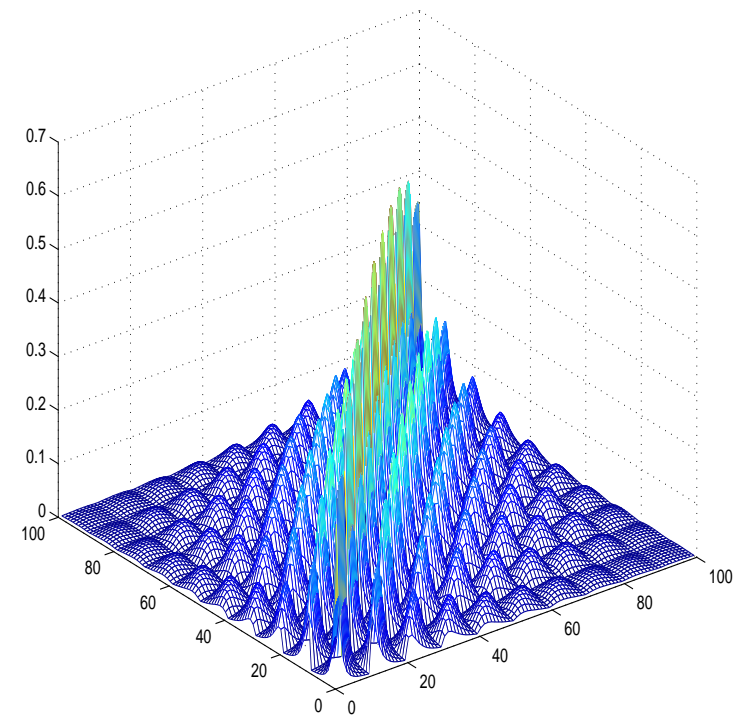
The inverse of the 2D Laplace matrix on the unit square

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Sparsity pattern:



S



$|((S^{-1})_{ij})|$

The exponential decay of the entries of S^{-1}

The classical bound (Demko, Moss & Smith):

If S spd is banded with bandwidth b , then

$$|(S^{-1})_{ij}| \leq \gamma q^{\frac{|i-j|}{b}}$$

where

κ : condition number of S

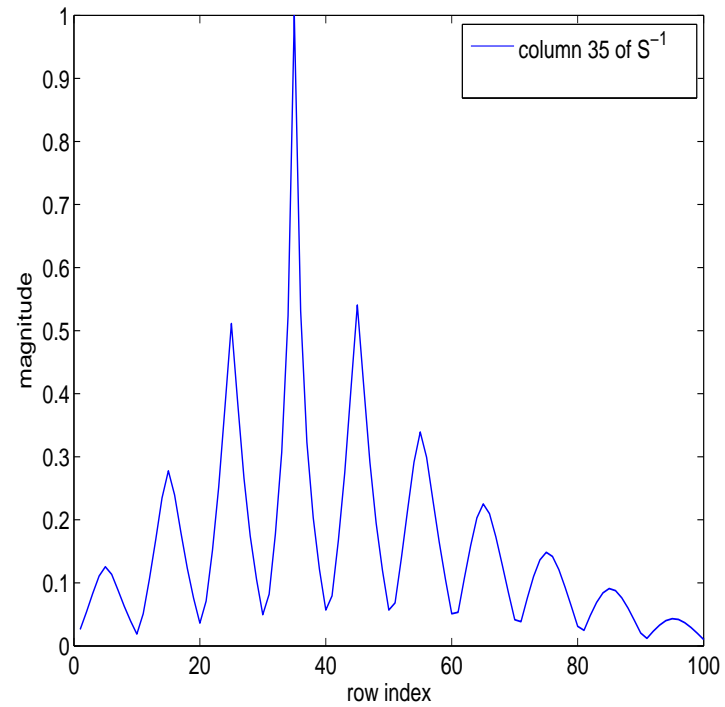
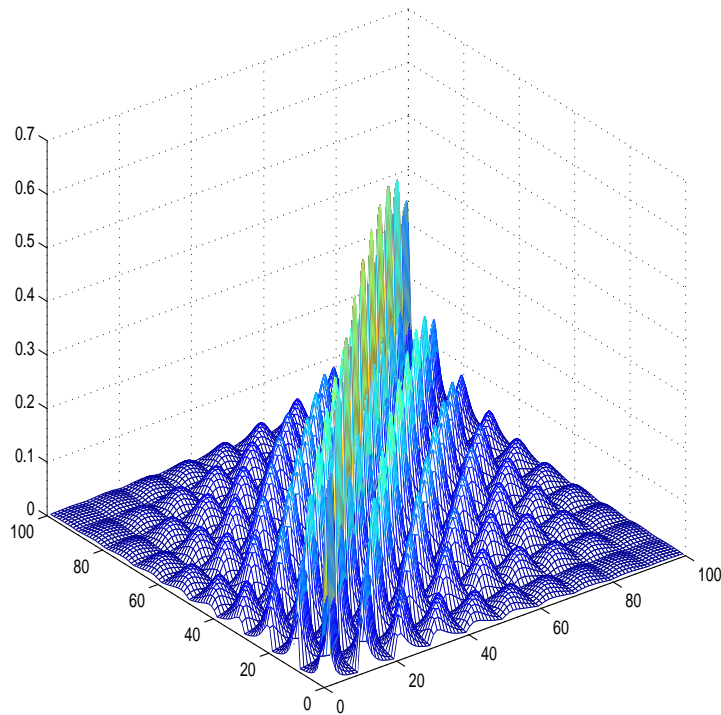
$$q := \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} < 1$$

$$\gamma := \max\{\lambda_{\min}(S)^{-1}, \hat{\gamma}\}, \text{ and } \hat{\gamma} = \frac{(1 + \sqrt{\kappa})^2}{2\lambda_{\max}(S)}$$

($\lambda_{\min}(\cdot)$, $\lambda_{\max}(\cdot)$ smallest and largest eigenvalues of the given symmetric matrix)

Many contributions: Bebendorf, Hackbusch, Benzi, Boito, Razouk, Golub, Tuma, Concus, Meurant, Mastronardi, Ng, Tyrtysnikov, Nabben, ...

The true decay



... a very peculiar pattern

⇒ much higher sparsity

Where do the repeated peaks come from?

For $S = M \otimes I_n + I_n \otimes M \in \mathbb{R}^{n^2 \times n^2}$:

$$x_t := (S^{-1})_{:,t} = S^{-1}e_t \quad \Leftrightarrow \quad \text{Solve : } Sx_t = e_t$$

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Let

$X_t \in \mathbb{R}^{n \times n}$ be such that $x_t = \text{vec}(X_t)$

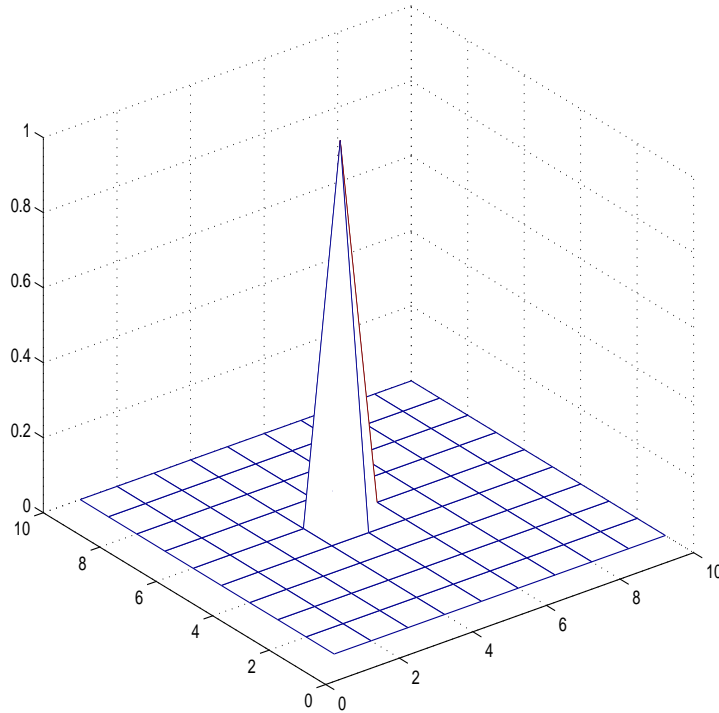
$E_t \in \mathbb{R}^{n \times n}$ be such that $e_t = \text{vec}(E_t)$

Then

$$Sx_t = e_t \quad \Leftrightarrow \quad MX_t + X_tM = E_t$$

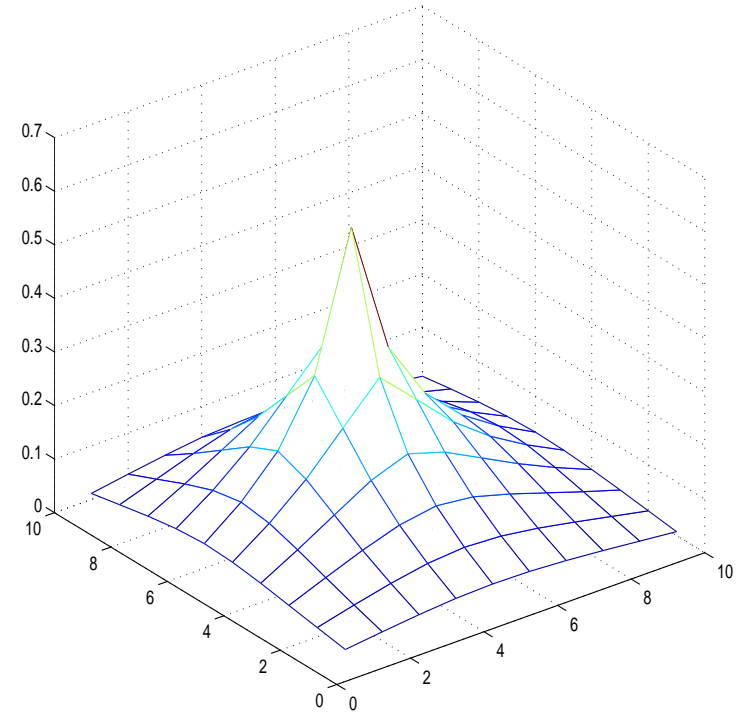
For S the 2D Laplace operator, $t = 1, \dots, n^2$

$$t = 35, \quad Sx_t = e_t \quad \Leftrightarrow \quad MX_t + X_tM = E_t$$



matrix E_t

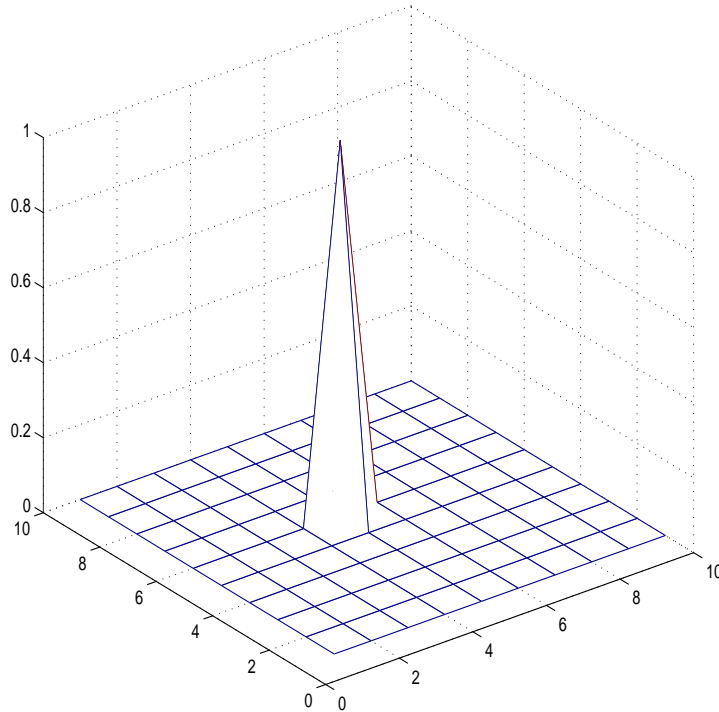
and



matrix X_t

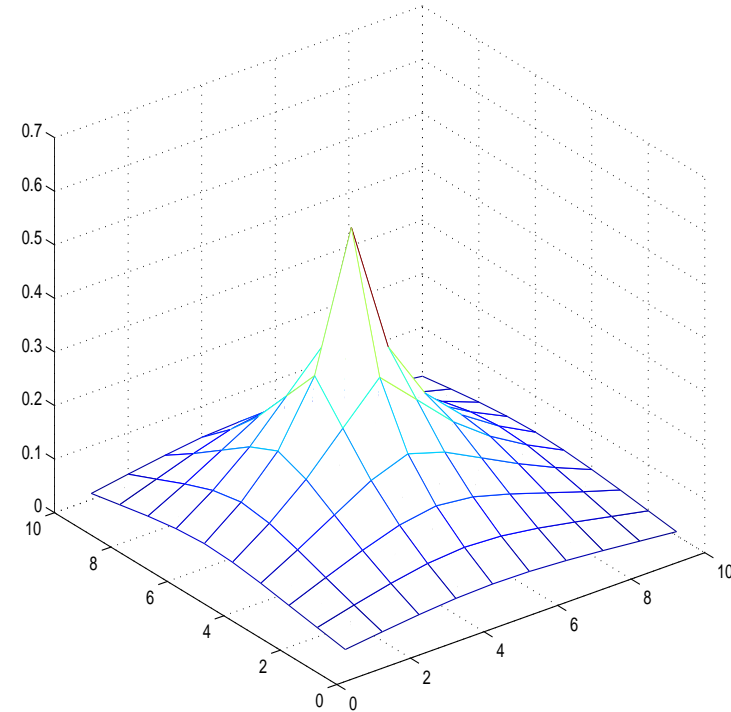
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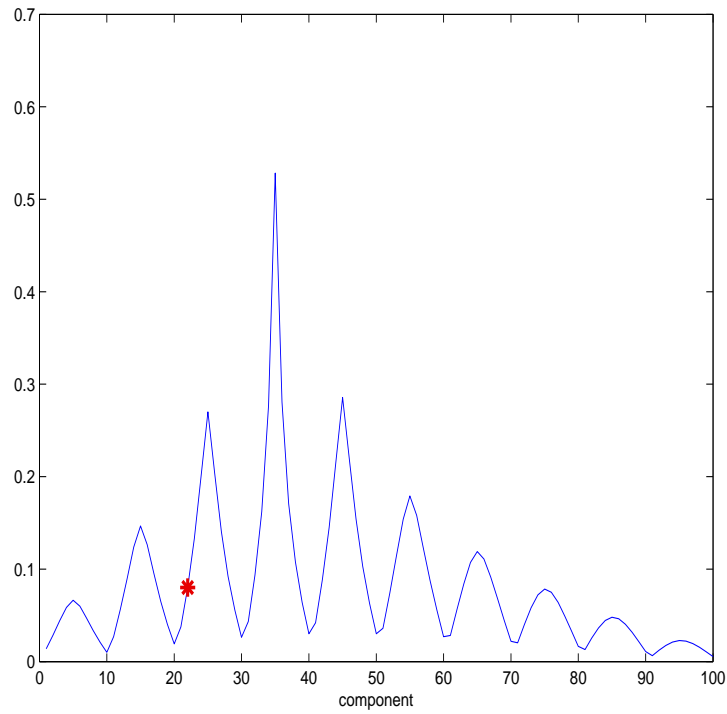
and



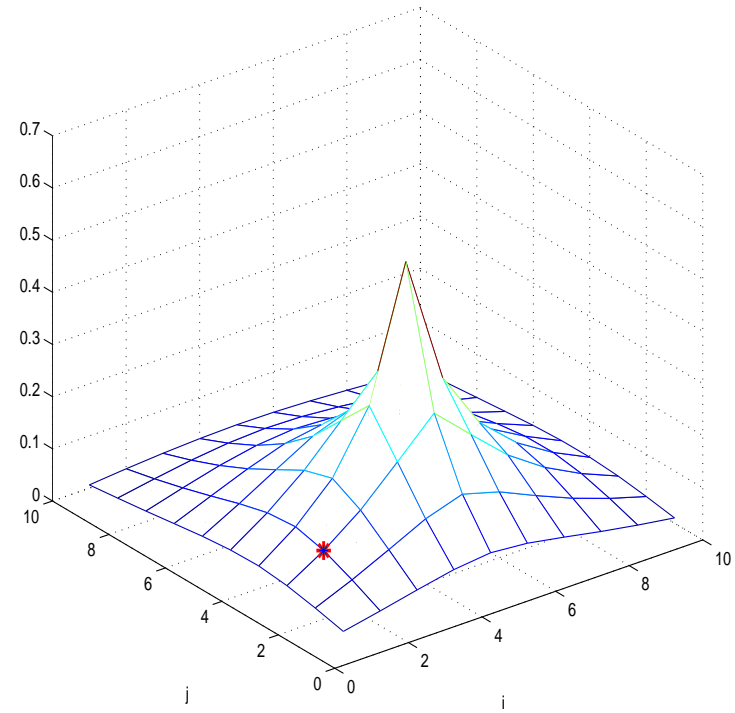
matrix X_t

E_t has only one nonzero element

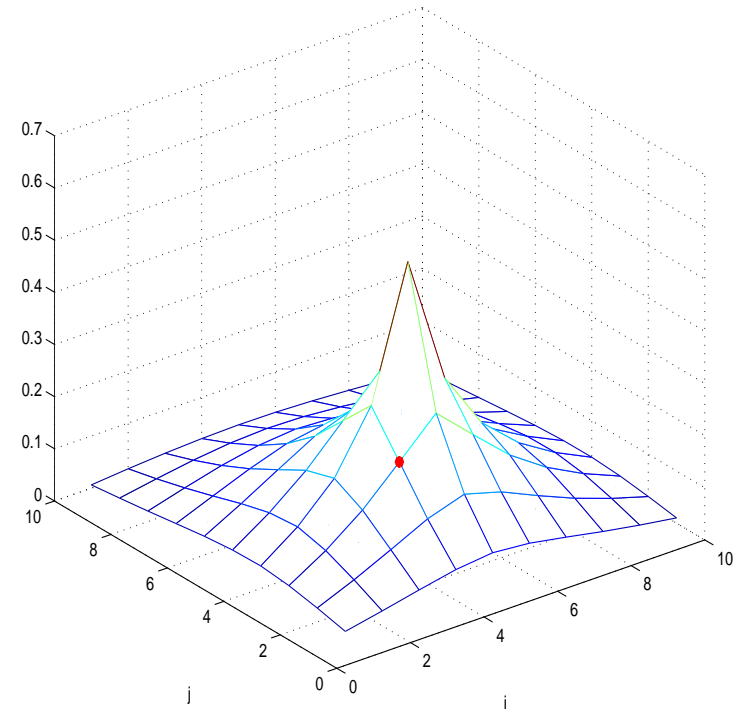
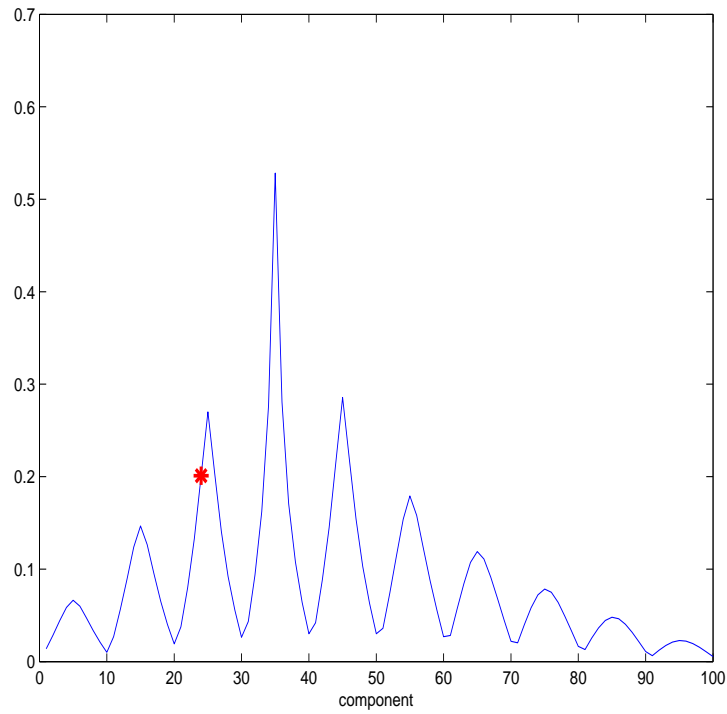
Lexicographic order: $(E_t)_{ij}$, $j = \lfloor (t-1)/n \rfloor + 1$, $i = tn \lfloor (t-1)/n \rfloor$



Left: Row of S^{-1}

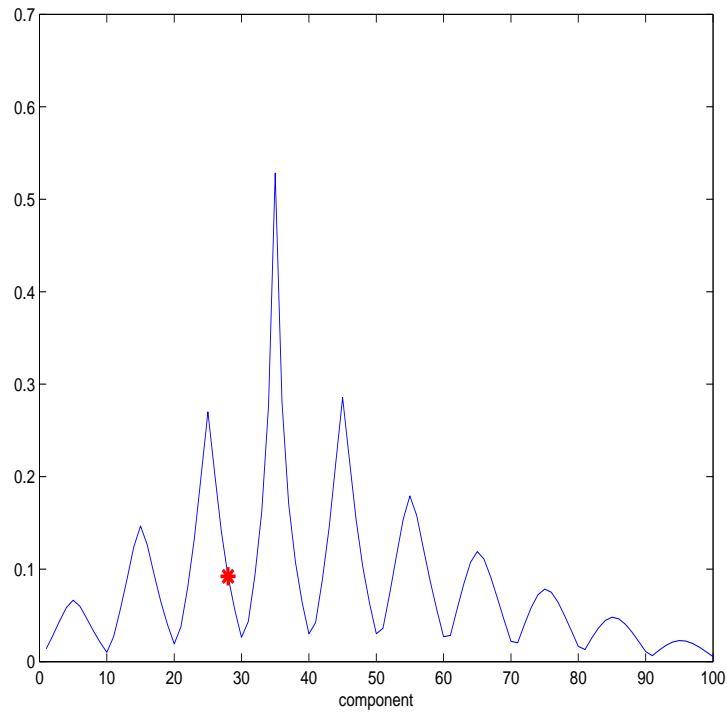


Right: same row on the grid

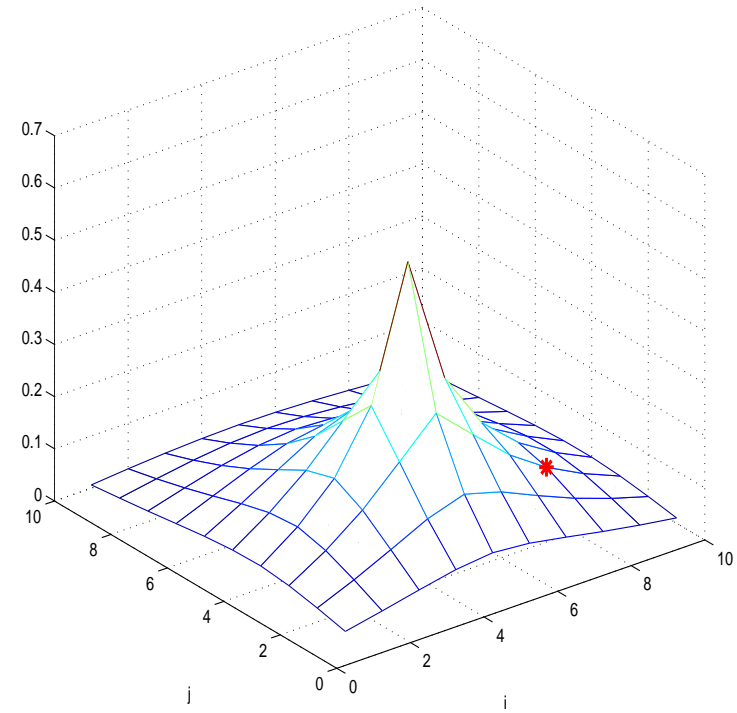


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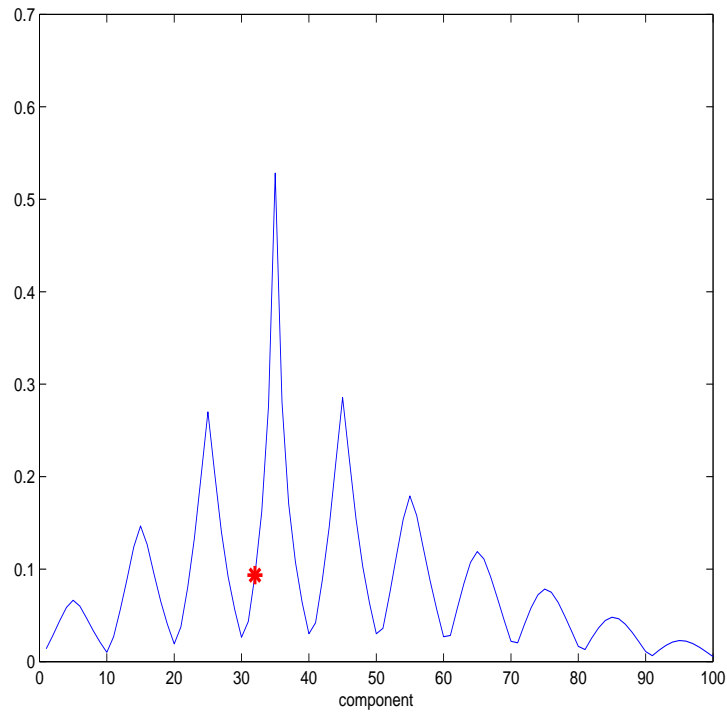
Right: same row on the grid



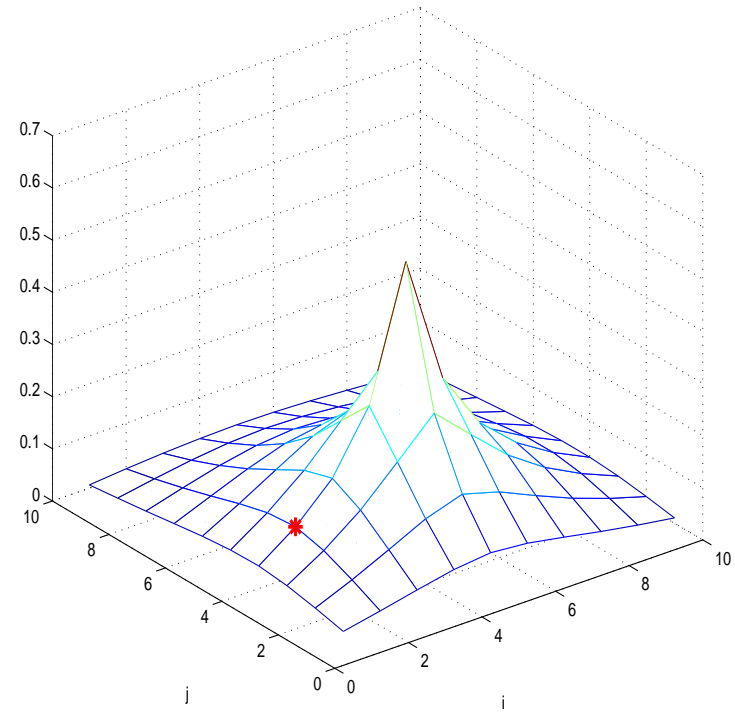
Left: Row of S^{-1}



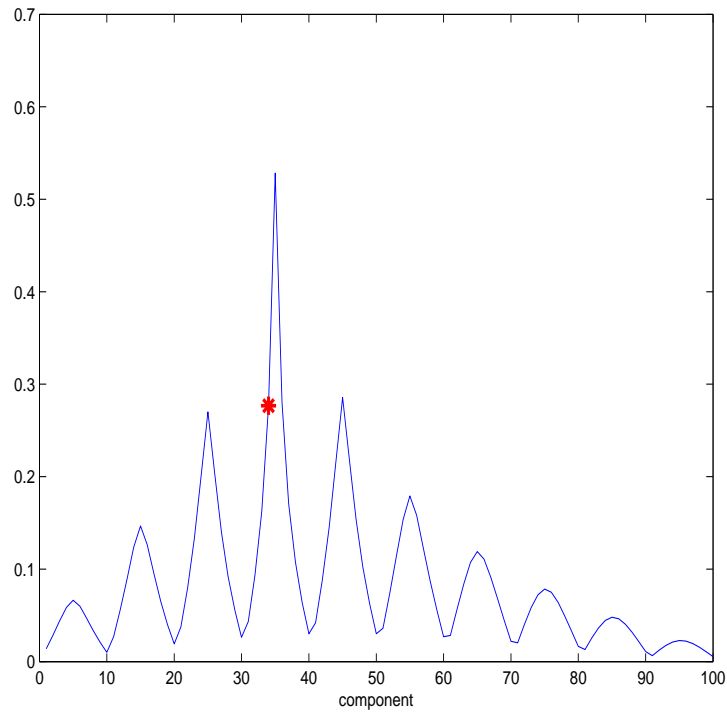
Right: same row on the grid



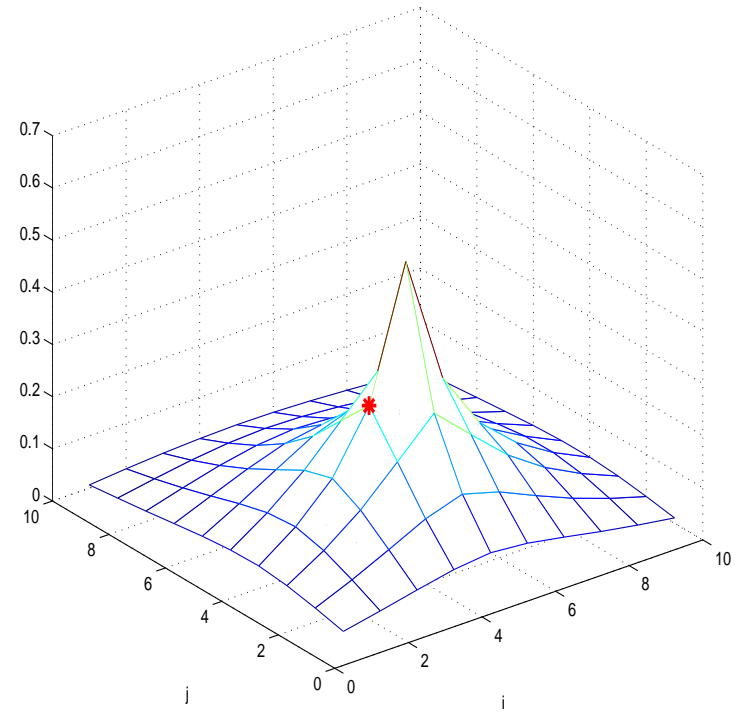
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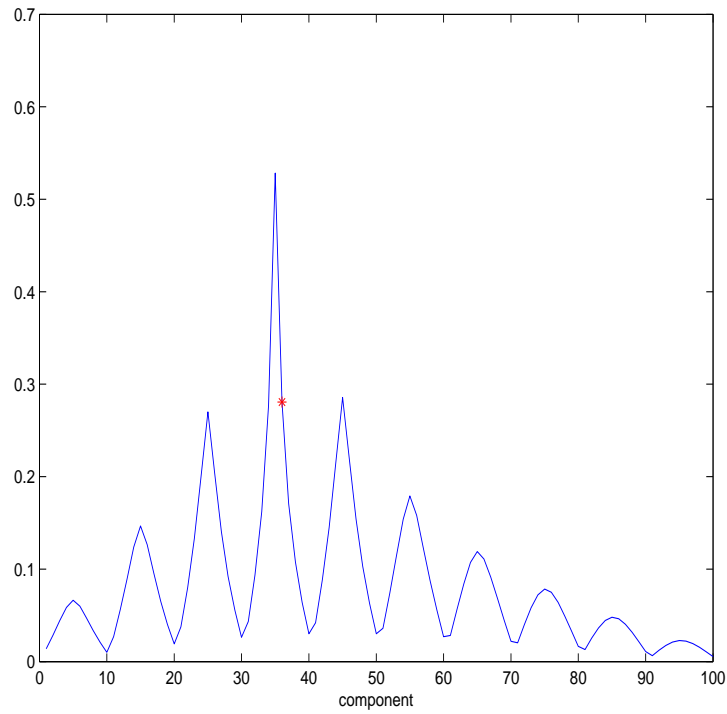
Right: same row on the grid



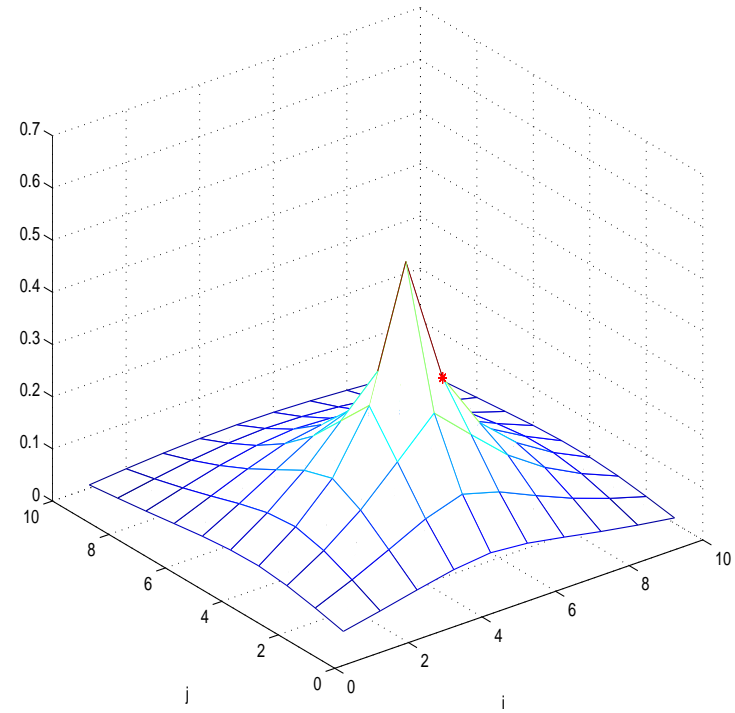
Left: Row of S^{-1}



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Resolving the entry indexing using $MX_t + X_tM = E_t$

$$(S^{-1})_{k,t} = (S^{-1})_{\ell+n(m-1),t} = e_\ell^\top X_t e_m, \quad \ell, m \in \{1, \dots, n\}$$

\Rightarrow All the elements of the t -th column, $(S^{-1})_{:,t}$, are obtained by varying $m, \ell \in \{1, \dots, n\}$

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\Rightarrow All the elements of the t -th column, $(S^{-1})_{:,t}$, are obtained by varying $m, \ell \in \{1, \dots, n\}$

From the Lyapunov equation theory,

$$X_t = \frac{1}{2\pi} \int_{-\infty}^{\infty} (i\omega I + M)^{-1} E_t (i\omega I + M)^{-*} d\omega$$

with $E_t = e_i e_j^\top$, $j = \lfloor (t-1)/n \rfloor + 1$, $i = t - n \lfloor (t-1)/n \rfloor$

Therefore,

$$e_\ell^\top X_t e_m = \frac{1}{2\pi} \int_{-\infty}^{\infty} e_\ell^\top (i\omega I + M)^{-1} e_i e_j^\top (i\omega I + M)^{-*} e_m d\omega$$

Qualitative bounds

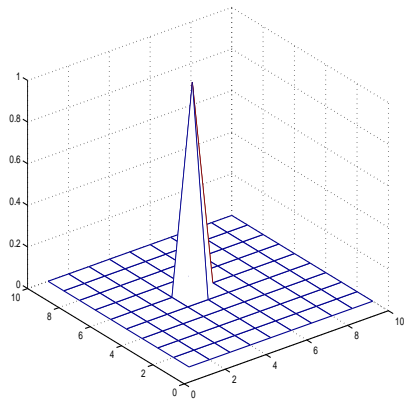
Let $\kappa = \lambda_{\max}/\lambda_{\min} = \text{cond}(M)$

i) Assume $\ell, i, m, j : \ell \neq i, m \neq j$. $\mathbf{n}_2 := |\ell - i| + |m - j| - 2 > 0$

$$|(S^{-1})_{k,t}| \leq \frac{\sqrt{\kappa^2 + 1}}{2\lambda_{\min}} \frac{1}{\sqrt{\mathbf{n}_2}}.$$

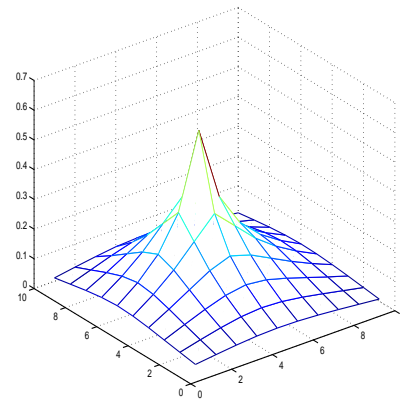
ii) Assume $\ell, i, m, j : \ell = i$ or $m = j$. $\mathbf{n}_1 := |\ell - i| + |m - j| - 1 > 0$

$$|(S^{-1})_{k,t}| \leq \frac{\kappa\sqrt{\kappa^2 + 1}}{2} \frac{1}{\sqrt{\mathbf{n}_1}}.$$



(i, j)

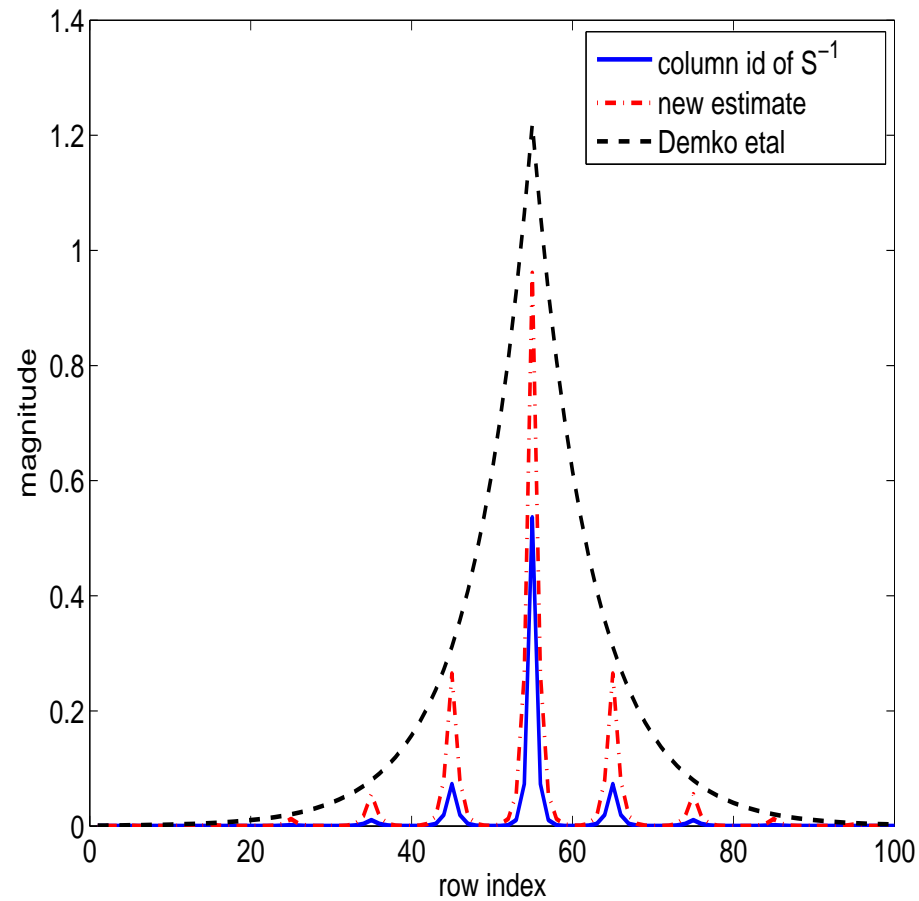
and



(ℓ, m)

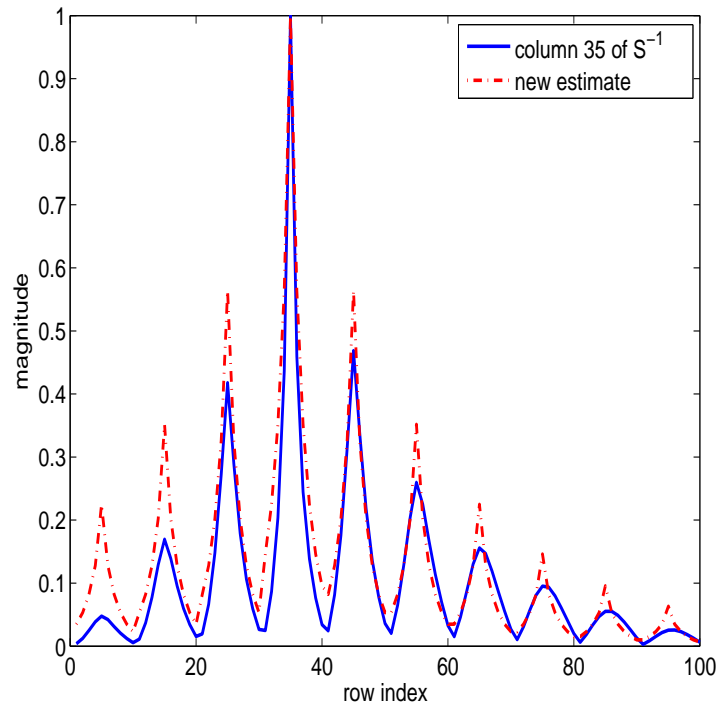
Examples. Symmetric positive definite matrix

$$M = \text{tridiag}(-0.5, \underline{2}, -0.5) \in \mathbb{R}^{10 \times 10}$$



Examples. Legendre stiffness matrix (scaled to have peak equal to 1)

$$M = \text{tridiag}(\delta_k, \underline{\gamma_k}, \delta_k)$$



$$\gamma_k = \frac{2}{(4k - 3)(4k + 1)}$$

$$k = 1, \dots, n, \quad \text{and}$$

$$\delta_k = \frac{-1}{(4k + 1)\sqrt{(4k - 1)(4k + 3)}}$$

$$k = 1, \dots, n - 1$$

Connections to point-wise estimates for discrete Laplacian

For the discrete Green function G_h on the discrete d -dimensional grid R_h , there exist constants h_0 and C such that for $h \leq h_0$, $x, y \in R_h$,

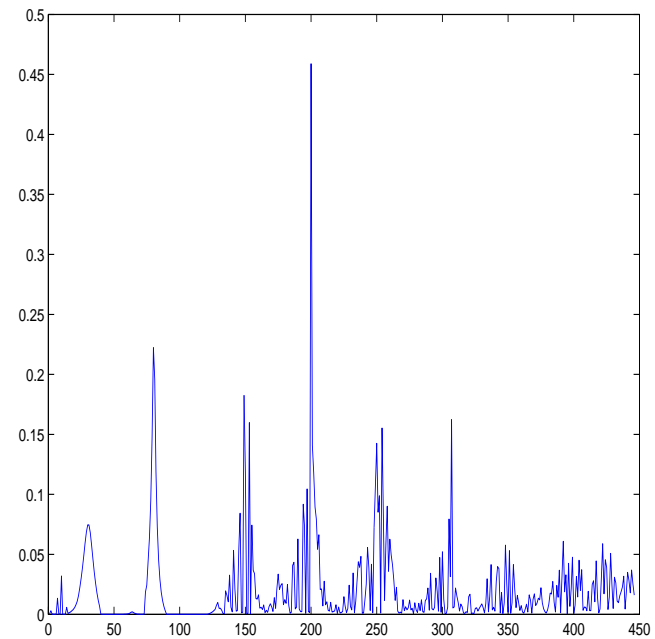
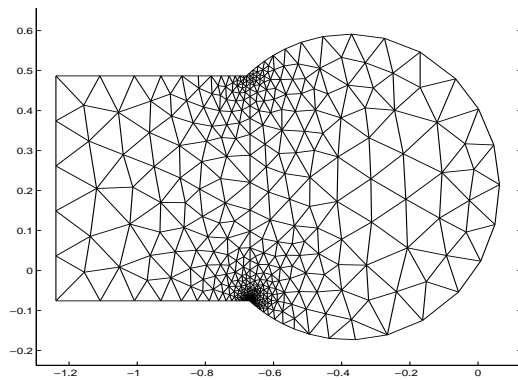
$$G_h(x, y) \leq \begin{cases} C \log \frac{C}{|x-y|+h} & \text{if } d = 2 \\ \frac{C}{(|x-y|+h)^{d-2}} & \text{if } d \geq 3 \end{cases}$$

(Bramble & Thomee, '69)

Our estimate: entries depend on inverse square root of the distance!

Generalizations. Next step.

A : Negative Laplacian matrix



Left: Discretization of the domain

Right: entries of column 200 of A^{-1} for that domain

An application. I

Adaptive Legendre-Galerkin discretizations for PDEs:

H_0^1 Tensorized Babuska-Shen basis in $\Omega = (0, 1) \times (0, 1)$:

$$\eta_{\mathbf{k}}(x_1, x_2) = \eta_{k_1}(x_1)\eta_{k_2}(x_2), \quad k_1, k_2 \geq 2, \quad \mathbf{k} = (k_1, k_2)$$

$\{\eta_{k_i}\}$: k_i -order Legendre polyn (1D BS basis)

Stiffness matrix:

$$(\eta_{\mathbf{k}}, \eta_{\mathbf{m}})_{H_0^1(\Omega)} = (\eta_{k_1}, \eta_{m_1})_{H_0^1(I)}(\eta_{k_2}, \eta_{m_2})_{L^2(I)} + (\eta_{k_1}, \eta_{m_1})_{L^2(I)}(\eta_{k_2}, \eta_{m_2})_{H_0^1(I)}$$

Kronecker structure: $S_{\eta}^p = M_p \otimes I_p + I_p \otimes M_p$ (max p polyn degree)

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Note: If higher order polynomial used, then S_{η}^p simply expands (augmented M_p)

An application. II

Adaptive Legendre-Galerkin discretizations for PDEs:

- Inner product:

$$v = \sum \hat{v}_{\mathbf{k}} \eta_{\mathbf{k}}, \quad \|v\|_{H_0^1}^2 = \hat{v}^T S_{\eta} \hat{v}$$

An application. II

Adaptive Legendre-Galerkin discretizations for PDEs:

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- (Full!) Orthonormalization: $\{\Phi_{\mathbf{k}}\}$ orth basis,

$$v = \sum \tilde{v}_{\mathbf{k}} \Phi_{\mathbf{k}}, \quad \|v\|_{H_0^1}^2 = \tilde{v}^T G^T S_{\eta} (G \tilde{v}) = \tilde{v}^T \tilde{v}$$

with $G = L^{-1}$ where $S_{\eta} = LL^T$

An application. II

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with $G = L^{-1}$ where $S_{\eta} = LL^T$

- (Cheap!) Quasi-orthonormalization: $\{\Psi_{\mathbf{k}}\}$ quasi-orth basis,

$$v = \sum \check{v}_{\mathbf{k}} \Psi_{\mathbf{k}}, \quad \|v\|_{H_0^1}^2 = \check{v}^T \check{G}^T S_{\eta} (\check{G}\check{v}) \approx \check{v}^T D\check{v}$$

\check{G} very sparse version of G , D diagonal

An application. II

Adaptive Legendre-Galerkin discretizations for PDEs:

- Inner product:

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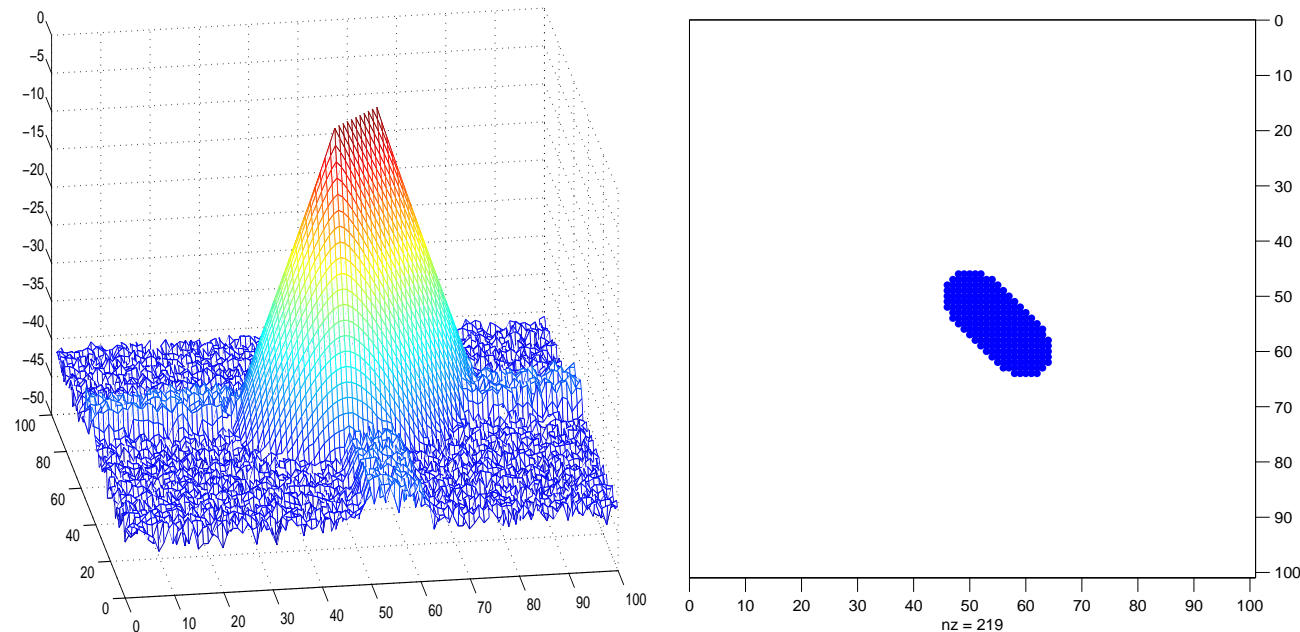
\check{G} very sparse version of G , D diagonal

Q: Does such a \check{G} exist? ...Yes! Because of sparsity of S_{η}^{-1}

More applications. Using sparsity in solution strategies

$$MX + XM = BB^T$$

$M = \text{tridiag}(-1, 4, -1) \in \mathbb{R}^{n \times n}$, $n = 100$ and $B = [e_{50}, \dots, e_{60}]$

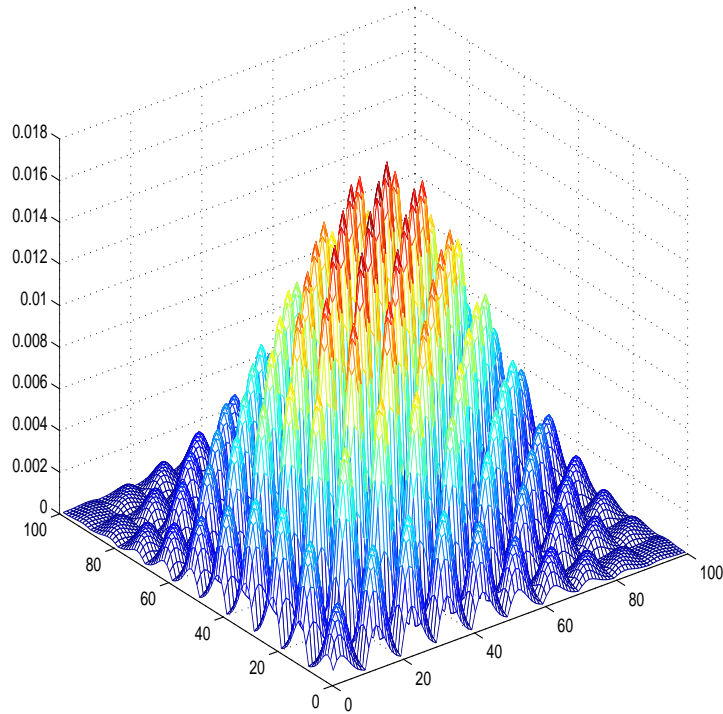


Left: pattern of X with log scale, $\text{nnz}(X) = 9724$

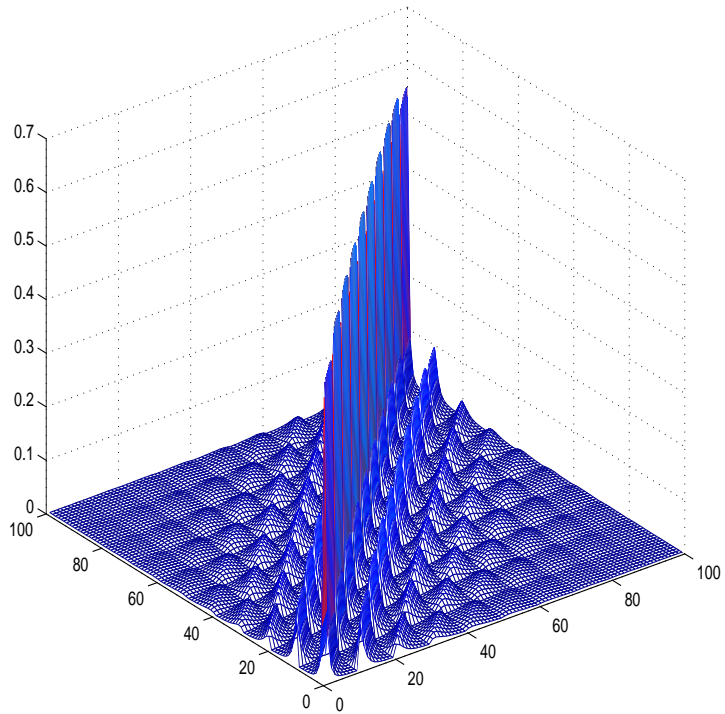
Right: Sparsity pattern of truncated ver. of X : all entries below 10^{-5} are omitted

More applications. Decay of functions of Kronecker sum matrices

$$A = M \otimes I + I \otimes M \quad (\text{discretization of negative Laplacian})$$



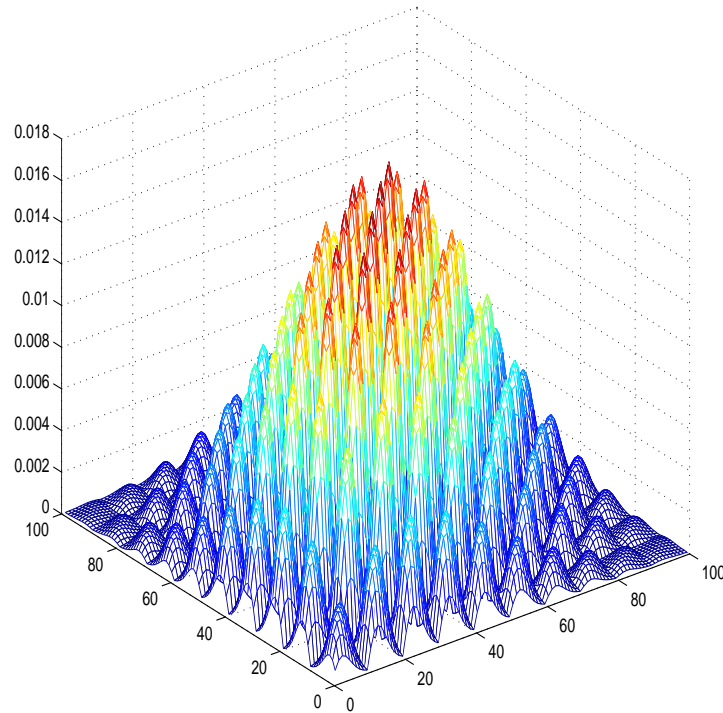
$$|e^{-5A}|_{ij}$$



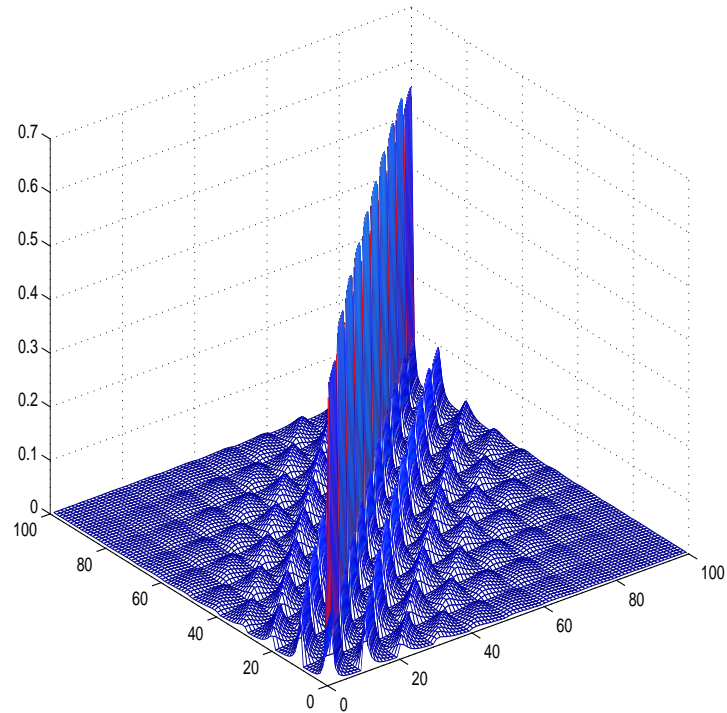
$$|A^{-\frac{1}{2}}|_{ij}$$

More applications. Decay of functions of Kronecker sum matrices

$$A = M \otimes I + I \otimes M \quad (\text{discretization of negative Laplacian})$$



$$|e^{-5A}|_{ij}$$



$$|A^{-\frac{1}{2}}|_{ij}$$

In addition: drastically lower computational costs for $f(A)v$

Conclusions and further work ahead

- The Lyapunov operator has a very rich structure
- Appropriate computational devices
- Powerful mathematical tool
- Structure recurrent in many application problems...
- ... Generalize to more hidden structures

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