



Structured Preconditioners for Symmetric Saddle Point Problems

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The problem

$$\begin{bmatrix} A & B^T \\ B & -C \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} f \\ g \end{bmatrix}$$

- Computational Fluid Dynamics
- Elasticity problems
- Mixed (FE) formulations of II and IV order elliptic PDEs
- Linearly Constrained Programs
- Linear Regression in Statistics
- Weighted Least Squares (Image restoration)
- ... **Survey:** Benzi, Golub and Liesen, Acta Num 2005

Spectral properties. 1

$$\mathcal{M} = \begin{bmatrix} A & B^T \\ B & O \end{bmatrix} \quad \begin{array}{l} 0 < \lambda_n \leq \dots \leq \lambda_1 \quad \text{eigs of } A \\ 0 < \sigma_m \leq \dots \leq \sigma_1 \quad \text{sing. vals of } B \end{array}$$

(Rusten & Winther 1992) $\Lambda(\mathcal{M})$ subset of

$$\left[\frac{1}{2}(\lambda_n - \sqrt{\lambda_n^2 + 4\sigma_1^2}), \frac{1}{2}(\lambda_1 - \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right] \cup \left[\lambda_n, \frac{1}{2}(\lambda_1 + \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right]$$

Spectral properties. 2

$$\mathcal{M} = \begin{bmatrix} A & B^T \\ B & -C \end{bmatrix} \quad \begin{array}{l} 0 < \lambda_n \leq \dots \leq \lambda_1 \quad \text{eigs of } A \\ 0 \leq \sigma_m \leq \dots \leq \sigma_1 \quad \text{sing. vals of } B \end{array}$$

(Silvester & Wathen 1994)

$$\left[\frac{1}{2} \left(\lambda_n - \lambda_{\max}(C) - \sqrt{(\lambda_n + \lambda_{\max}(C))^2 + 4\sigma_1^2} \right), \frac{1}{2}(\lambda_1 - \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right] \\ \cup \left[\lambda_n, \frac{1}{2}(\lambda_1 + \sqrt{\lambda_1^2 + 4\sigma_m^2}) \right]$$

Additional results for more general cases (e.g., A sing., A nonsym, ...)

General preconditioning strategy

- Find \mathcal{P} such that

$$\mathcal{M}\mathcal{P}^{-1}\hat{u} = b \quad \hat{u} = \mathcal{P}u$$

is easier (faster) to solve than $\mathcal{M}u = b$

- A look at efficiency:
 - Dealing with \mathcal{P} should be cheap
 - Storage for \mathcal{P} should be low
 - Properties (algebraic/functional) exploited

Block diagonal, block triangular, block “constraint” preconditioners

Structure preserving preconditioning: Ideal cases

★ A nonsing., $C = 0$:

$$\mathcal{P} = \begin{bmatrix} A & 0 \\ 0 & BA^{-1}B^T \end{bmatrix} \Rightarrow \mathcal{M}\mathcal{P}^{-1} \quad \text{eigs: } 1, \frac{1}{2} \pm \frac{\sqrt{5}}{2}$$

MINRES converges in at most 3 iterations (Murphy, Golub & Wathen '02)

★ A nonsing., $C \neq 0$:

$$\mathcal{P} = \begin{bmatrix} A & B \\ 0 & BA^{-1}B^T + C \end{bmatrix} \Rightarrow \mathcal{M}\mathcal{P}^{-1} = \begin{bmatrix} I & 0 \\ BA^{-1} & I \end{bmatrix}$$

GMRES converges in at most 2 iterations

Ideal preconditioners are not feasible.

Approximations to ideal precs. are feasible - Perturbed behavior

Block diagonal Preconditioner

$$\mathcal{P} = \begin{bmatrix} \tilde{A} & 0 \\ 0 & \tilde{C} \end{bmatrix} \quad \text{sym. pos. def.}$$

$$\tilde{A} \approx A \quad \tilde{C} \approx BA^{-1}B^T + C$$

$\lambda \neq 0$ eigs of $\mathcal{P}^{-\frac{1}{2}}\mathcal{M}\mathcal{P}^{-\frac{1}{2}}$ (sym. indef.)

$$\lambda \in [-a, -b] \cup [c, d], \quad a, b, c, d > 0$$

Rusten Winther (1992), Silvester Wathen (1993-1994), ...

Triangular preconditioner

$$A \text{ spd, } \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ 0 & -\tilde{C} \end{bmatrix} \quad \tilde{A} \approx A, \quad \tilde{C} \approx BA^{-1}B^T + C$$

(Bramble & Pasciak, Elman, Klawonn, Axelsson & Neytcheva, Simoncini)

Spectrum of $\mathcal{M}\mathcal{P}^{-1}$:

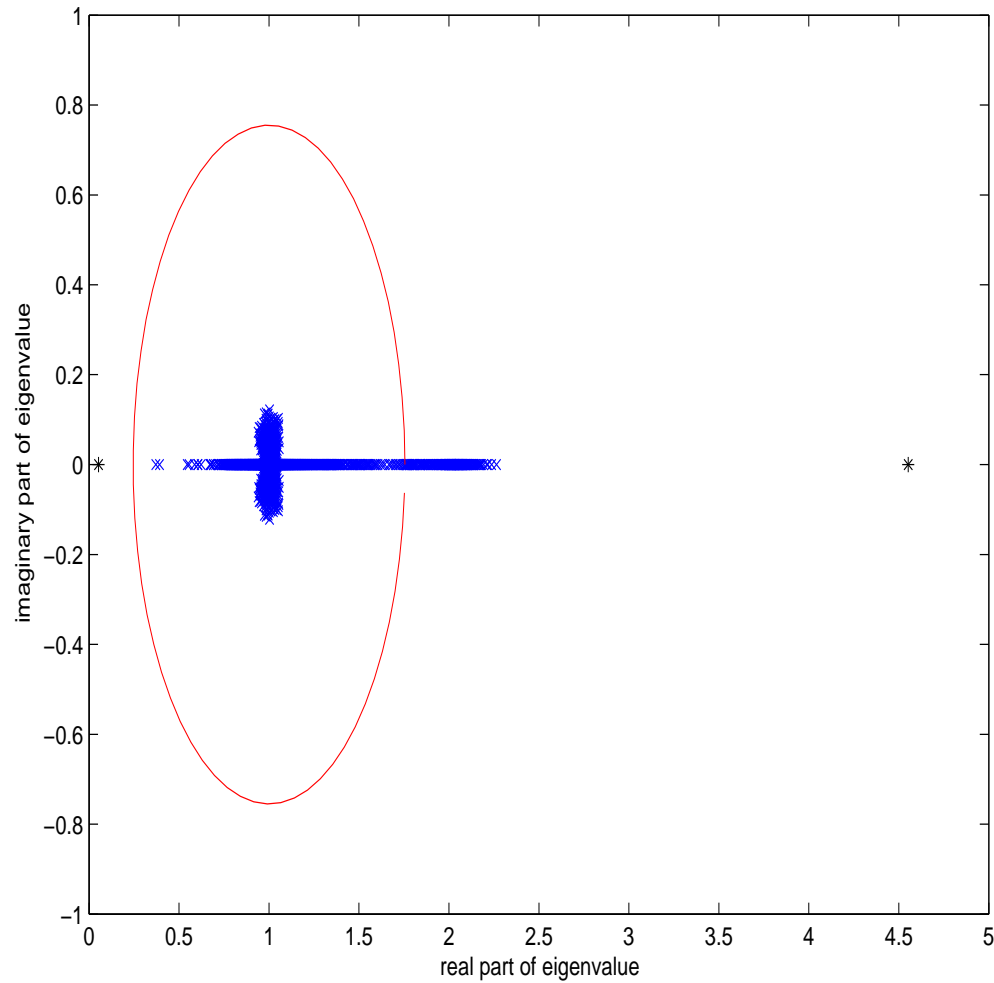
small complex cluster around 1 \cup real interval :

More precisely: $\theta \in \Lambda(\mathcal{M}\mathcal{P}^{-1})$

$$\Im(\theta) \neq 0 \Rightarrow |\theta - 1| \leq \sqrt{1 - \lambda_{\min}(A\tilde{A}^{-1})} \quad (\text{if } 1 - \lambda_{\min}(A\tilde{A}^{-1}) \geq 0)$$

$$\Im(\theta) = 0 \Rightarrow \theta \in [\chi_1, \chi_2] \text{ with } 1 \in [\chi_1, \chi_2]$$

An example



size: 2208, $\tilde{A} = \text{cholinc}(A, 10^{-2})$, $\tilde{C} = \text{cholinc}(C, 10^{-2})$

More to show? An open problem

$$\begin{bmatrix} A & B^T \\ 0 & -C \end{bmatrix} \Rightarrow \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ 0 & -\tilde{C} \end{bmatrix}$$

- ★ Pretty clear understanding of perturbed spectrum

Eigenvectors???

Constraint Preconditioner

$$\mathcal{M}Q^{-1} \quad Q = \begin{bmatrix} \tilde{A} & B^T \\ B & -C \end{bmatrix}$$

Axelsson ('79), Ewing Lazarov Lu Vassilevski ('90), many papers after '97

Remark: $[B, -C]x_k = 0$ for all iterates x_k (constraint)

$\lambda \neq 0$ eigs of $\mathcal{M}Q^{-1}$: $\lambda \in \mathbb{R}^+$, $\lambda \in \{1\} \cup [\alpha_0, \alpha_1]$

Detailed results on eigen/principal vectors (Dollar tr05)

More general factorizations (Dollar & Gould & Schilders & Wathen 06)

The feasible preconditioner

$$Q = \begin{bmatrix} \tilde{A} & B^T \\ B & -C \end{bmatrix}$$

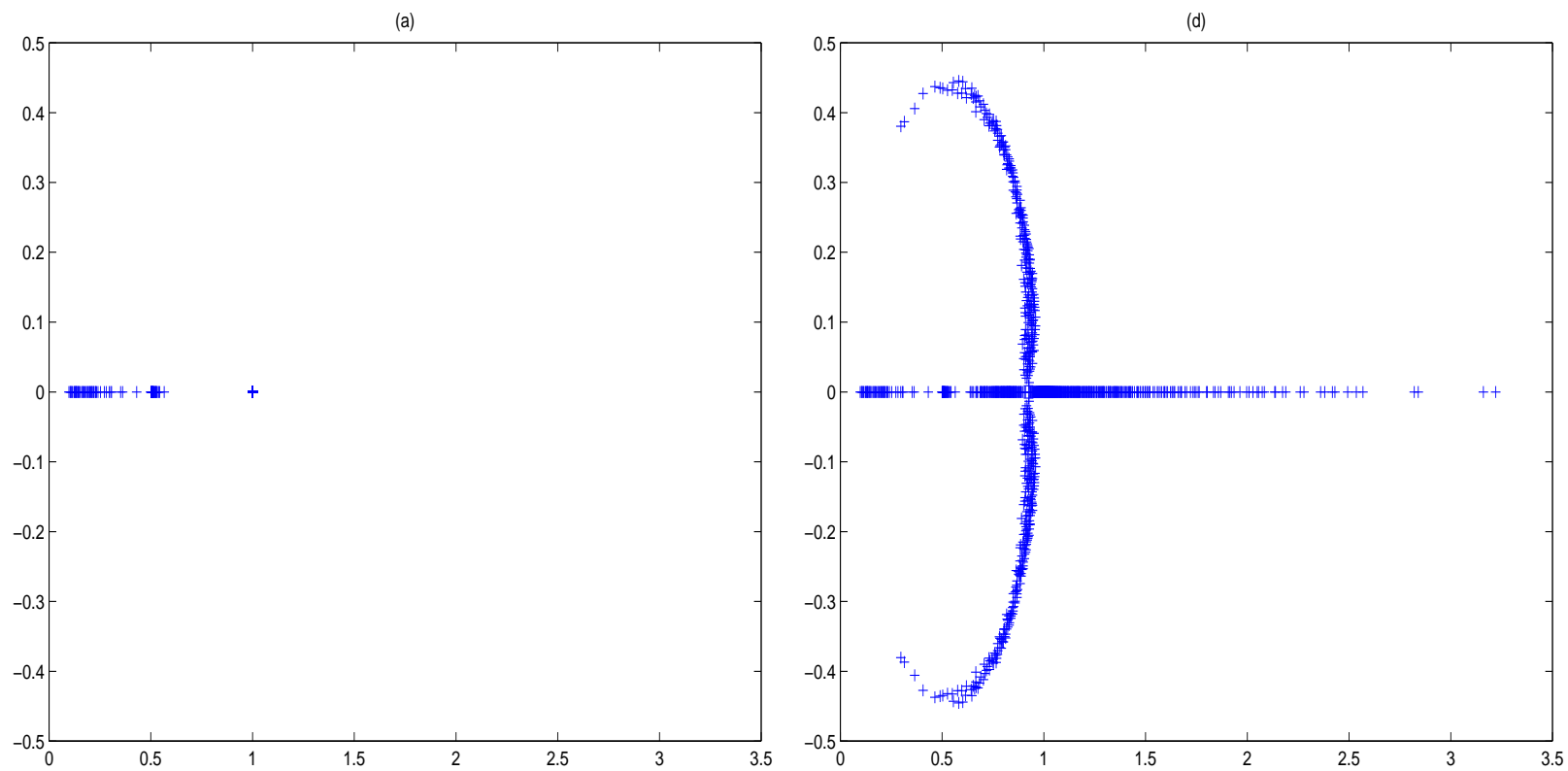
$$Q^{-1} = \begin{bmatrix} I & -B^T \\ O & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -(\mathbf{B}\mathbf{B}^T + \mathbf{C})^{-1} \end{bmatrix} \begin{bmatrix} I & O \\ -B & I \end{bmatrix}$$

($\tilde{A} = I$ if prescaling used)

$$BB^T + C \approx H \quad \text{e.g., } H = \text{cholinc}(BB^T + C, \text{tol})$$

Question: How much does H affect the preconditioner ?

Spectrum of perturbed matrix



$$\|(BB^T + C) - H\|_\infty \approx 2 \cdot 10^{-1} \|BB^T + C\|_\infty$$

Eigenvalue bounds

$C = 0 \Rightarrow H \approx BB^T$, A spd.

Let $\hat{S} = B(2I - A)B^T H^{-1}$ (scale A so that $\hat{S} \geq 0$)

★ If $\Im(\lambda) \neq 0$ then

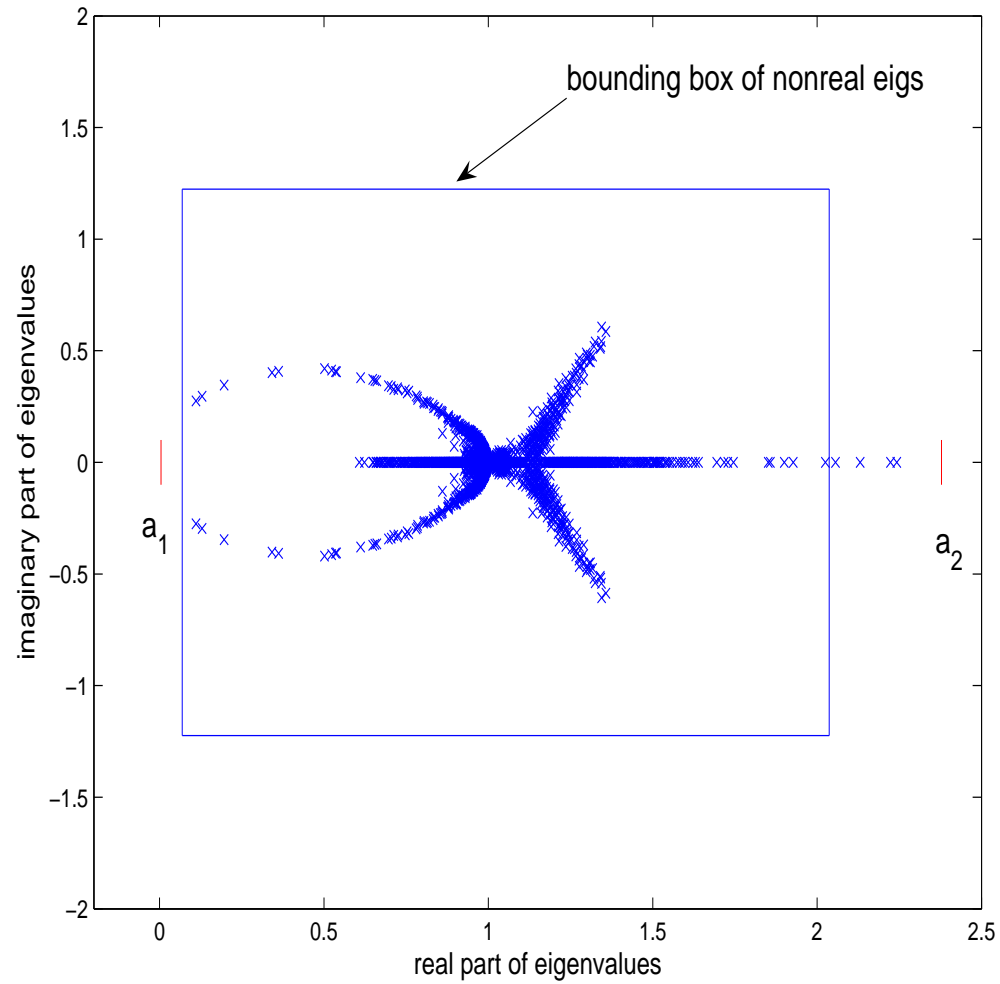
$$\begin{aligned} \frac{1}{2}(\lambda_{\min}(A) + \lambda_{\min}(\hat{S})) &\leq \Re(\lambda) \leq \frac{1}{2}(\lambda_{\max}(A) + \lambda_{\max}(\hat{S})) \\ |\Im(\lambda)| &\leq \sigma_{\max}((I - A)B^T H^{-\frac{1}{2}}). \end{aligned}$$

★ If $\Im(\lambda) = 0$ then

$$\min\{\lambda_{\min}(A), \lambda_{\min}(\hat{S})\} \leq \lambda \leq \max\{\lambda_{\max}(A), \lambda_{\max}(\hat{S})\}$$

Benzi Simoncini '06

Spectral bounds



$$H = \text{cholinc}(BB^T, 10^{-2})$$

Some algebraic details for $\mathcal{M}\hat{Q}^{-1}$

$$\begin{bmatrix} A & B^T \\ B & O \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \lambda \hat{Q} \begin{bmatrix} x \\ y \end{bmatrix} \quad \hat{Q} = \begin{bmatrix} I & O \\ B & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} I & B^T \\ O & I \end{bmatrix}$$

can be written as

$$\begin{bmatrix} I & O \\ -B & I \end{bmatrix} \begin{bmatrix} A & B^T \\ B & O \end{bmatrix} \begin{bmatrix} I & -B^T \\ O & I \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

$$\begin{bmatrix} A & (I - A)B^T \\ B(I - A) & -B(2I - A)B^T \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

Some algebraic details for $\mathcal{M}\hat{\mathcal{Q}}^{-1}$. cont'ed

$$\begin{bmatrix} A & (I - A)B^T \\ B(I - A) & -B(2I - A)B^T \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \lambda \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

Using $BB^T = H + E$, this can be written as

$$\left(\begin{bmatrix} I_n \\ B \end{bmatrix} (A - I_n) \begin{bmatrix} I_n & -B^T \end{bmatrix} + \begin{bmatrix} O & O \\ O & E \end{bmatrix} \right) \begin{bmatrix} u \\ v \end{bmatrix} = (\lambda - 1) \begin{bmatrix} I_n & O \\ O & H \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

- ★ For $E = 0$ (i.e. $H = BB^T$) we readily recover the known exact case
- ★ For $E \neq O$, all eigenvector blocks u with $Bu \neq 0$ may give rise to nonreal eigenvalues
- ★ $E \neq 0$ affects the null space of the low rank matrix ($\lambda = 1$)

More to show? A second open problem

$$\hat{Q} = \begin{bmatrix} I & O \\ B & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -H \end{bmatrix} \begin{bmatrix} I & B^T \\ O & I \end{bmatrix}$$

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