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# Equazioni lineari matriciali proprietà, metodi numerici ed applicazioni

V. Simoncini

Dipartimento di Matematica, Università di Bologna (Italy)

`valeria.simoncini@unibo.it`

## Some matrix equations

- Sylvester matrix equation

$$A\mathbf{X} + \mathbf{X}B + D = 0$$

Eigenvalue problems, Control, Model Order Reduction, Assignment problems,  
Riccati equation

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- Lyapunov matrix equation

$$A\mathbf{X} + \mathbf{X}A^{\top} + D = 0, \quad D = D^{\top}$$

Stability analysis in Control and Dynamical systems, Signal processing, eigenvalue computations

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- Algebraic Riccati equation

$$AX + XA^T - XBB^T X + D = 0, \quad D = D^T$$

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- Multiterm linear matrix equation

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Elliptic PDEs, PDEs with stochastic inputs, bilinear dynamical systems, etc.

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Elliptic PDEs, PDEs with stochastic inputs, bilinear dynamical systems, etc.

**Focus: All or some of the matrices are large (and possibly sparse)**

The Lyapunov equation.

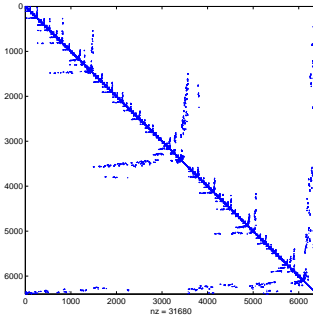
$$A\mathbf{X} + \mathbf{X}A^\top + D = 0, \quad A \text{ stable}$$

$$\boxed{A} \quad \boxed{\mathbf{X}} \quad + \quad \boxed{\mathbf{X}} \quad \boxed{A^\top} \quad + \quad \boxed{D} \quad = 0$$

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sparse, but ...

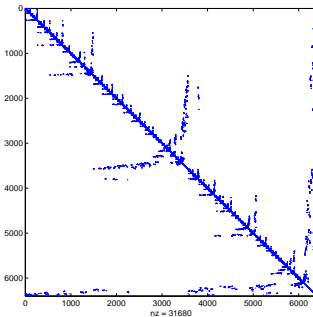
$\mathbf{X}$  dense



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$A =$  sparse, but ...  $\mathbf{X}$  dense

Example: For  $D = I$  and  $A$  symmetric, it holds that  $\mathbf{X} = -\frac{1}{2}A^{-1}$

## The Lyapunov equation. Some characterizations

$$AX + XA^\top + BB^\top = 0, \quad A \in \mathbb{R}^{n \times n} \text{ stable}$$

- **The Applied Mathematician perspective**

**X** holds stability information of time-invariant dynamical system:

$$\mathbf{x}'(t) = A\mathbf{x}(t) + B\mathbf{u}(t), \quad \mathbf{x}(0) = x_0$$

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- **The Analyst perspective.** Closed form solution:

$$X = -\frac{1}{2\pi} \int_{-\infty}^{\infty} (\omega I - A)^{-1} BB^\top (\omega I - A)^{-*} d\omega = \int_{-\infty}^0 e^{At} BB^\top e^{At} dt$$

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- **The Algebraist perspective.** Kronecker formulation:

$$(A \otimes I + I \otimes A)\mathbf{x} = b \quad \mathbf{x} = \text{vec}(\mathbf{X}), \quad b = \text{vec}(BB^\top)$$

with  $\mathcal{S} := A \otimes I + I \otimes A \in \mathbb{R}^{n^2 \times n^2}$

## Linear systems vs linear matrix equations

Large linear systems:

$$\mathcal{S}\mathbf{x} = b,$$

- Krylov subspace methods (CG, MINRES, GMRES, BiCGSTAB, etc.)
- Preconditioners: find  $P$  such that

$$\mathcal{S}P^{-1}\tilde{\mathbf{x}} = b \quad \mathbf{x} = P^{-1}\tilde{\mathbf{x}}$$

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### Large linear matrix equations:

$$A\mathbf{X} + \mathbf{X}A^{\top} + BB^{\top} = 0$$

- No preconditioning - to preserve symmetry
- $\mathbf{X}$  is a large, dense matrix  $\Rightarrow$  low rank approximation

$$\mathbf{X} \approx \tilde{\mathbf{X}} = ZZ^{\top}, \quad Z \text{ tall}$$

## The Kronecker sum matrix

$$\mathcal{S} := A \otimes I_n + I_n \otimes A,$$

with  $A$  symmetric and positive definite, banded with bandwidth  $b$

- Quantum Chemistry and Quantum dynamics
- Signal processing
- Numerical analysis
  - PDE discretizations: e.g., in Finite Differences, Finite Elements, Legendre Spectral Methods, Isogeometric Analysis, ...
- Multivariate Statistics

Sparsity and quasi-sparsity pattern properties of

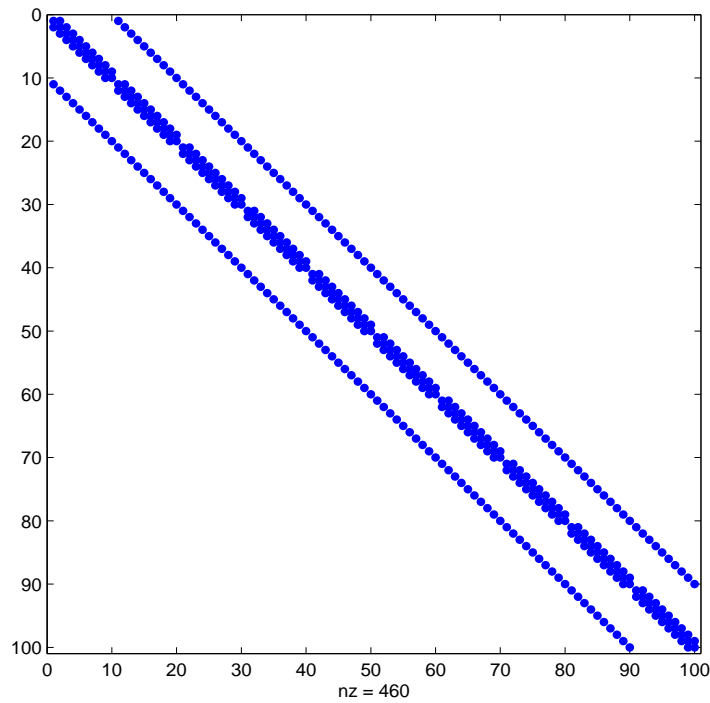
$$f(\mathcal{S})$$

$$f \in \{z^{-1}, e^z, z^{\frac{1}{2}}, \dots\}$$

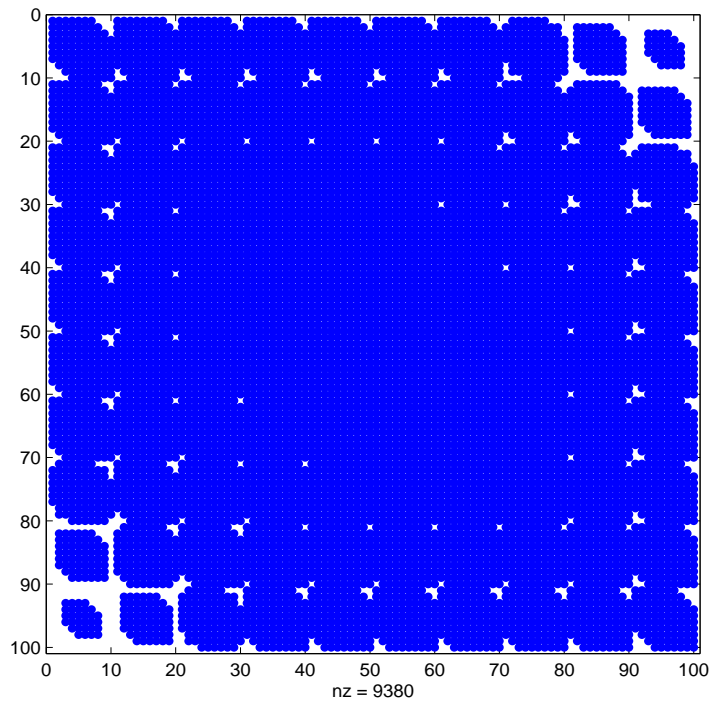
## Discretization of 2D Laplace operator on the unit square

$$\mathcal{S} := A \otimes I_n + I_n \otimes A, \quad A = \text{tridiag}(-1, 2, -1)$$

Sparsity pattern:



Matrix  $\mathcal{S}$



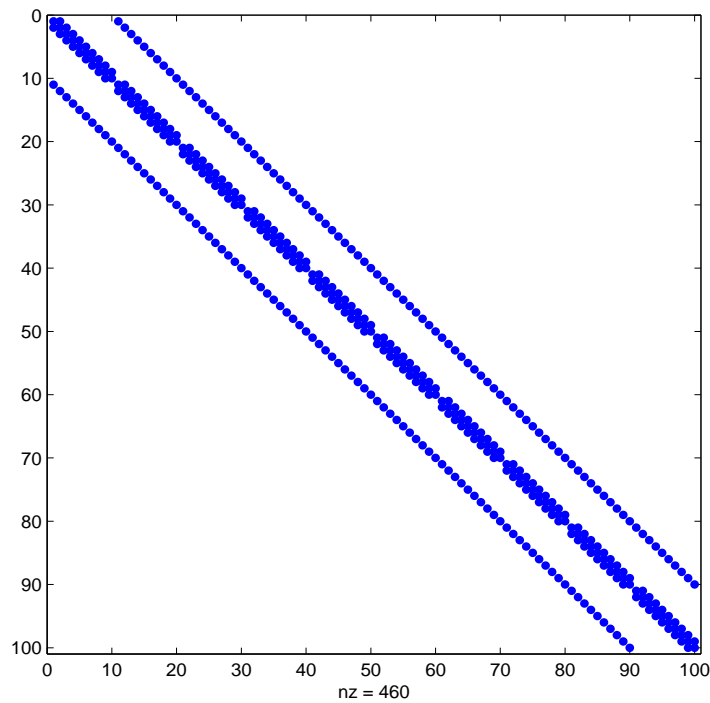
$\mathcal{S}^{-1}$



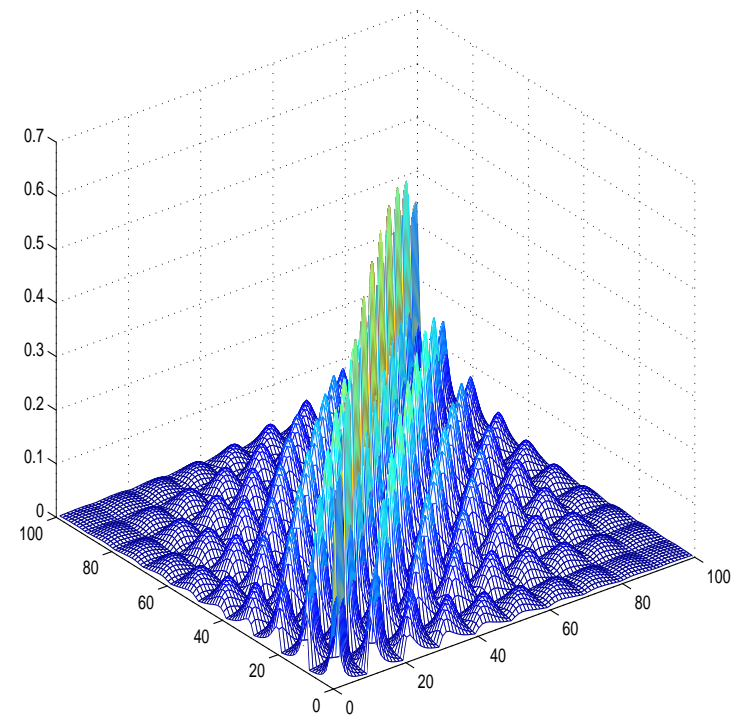
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Sparsity pattern:



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$|(\mathcal{S}^{-1})_{ij}|$

## The exponential decay of the entries of $\mathcal{S}^{-1}$

### The classical bound (Demko, Moss & Smith):

If  $\mathcal{S}$  spd is banded with bandwidth  $b$ , then

$$|(\mathcal{S}^{-1})_{ij}| \leq \gamma q^{\frac{|i-j|}{b}}$$

where

$$\kappa = \lambda_{\max}(\mathcal{S}) / \lambda_{\min}(\mathcal{S}) \text{ (cond. number of } \mathcal{S})$$

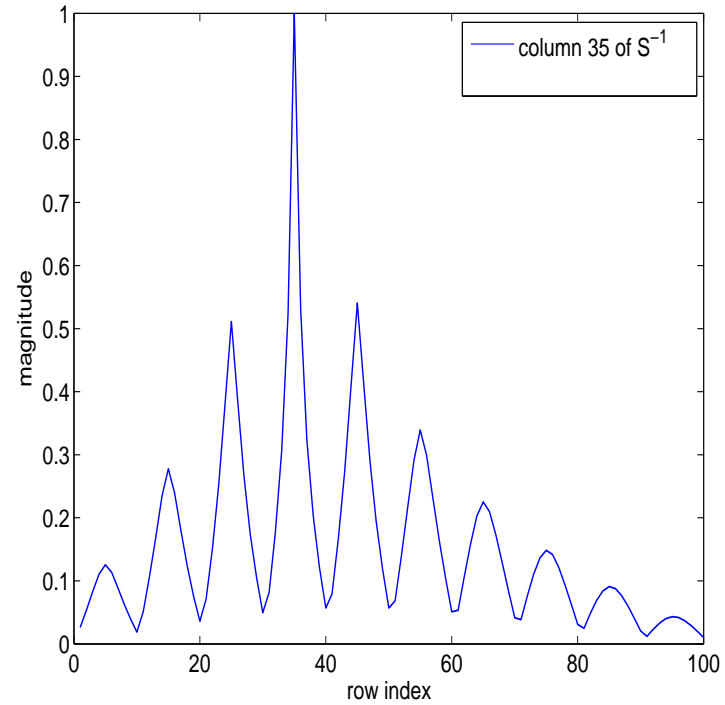
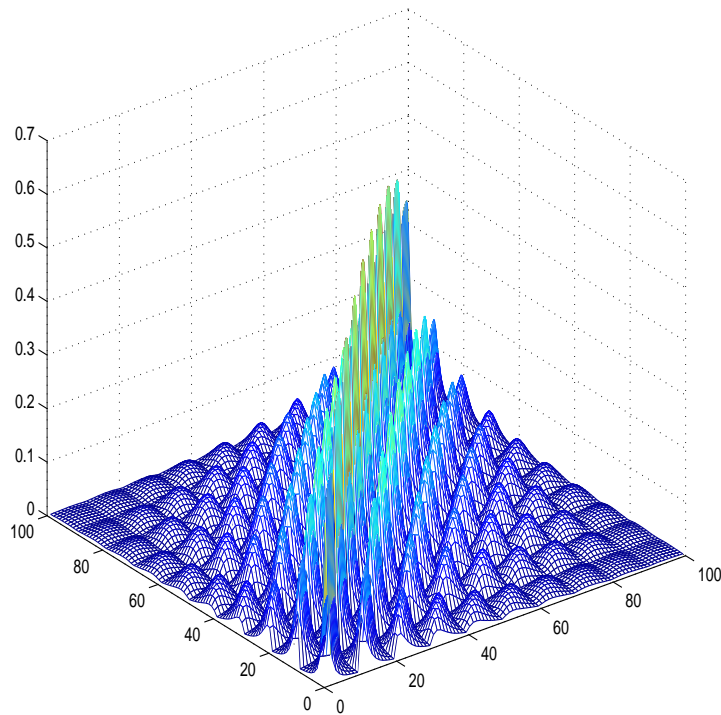
$$q := \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} < 1$$

$$\gamma := \max\{\lambda_{\min}(\mathcal{S})^{-1}, \hat{\gamma}\}, \text{ and } \hat{\gamma} = \frac{(1 + \sqrt{\kappa})^2}{2\lambda_{\max}(\mathcal{S})}$$

( $\lambda_{\min}(\mathcal{S})$ ,  $\lambda_{\max}(\mathcal{S})$  smallest and largest eigenvalues of  $\mathcal{S}$ )

**Many contributions:** Bebendorf, Hackbusch, Benzi, Boito, Razouk, Golub, Tuma, Concus, Meurant, Mastronardi, Ng, Tyrtshnikov, Nabben, ...

## The actual decay



... a very peculiar pattern

⇒ much higher sparsity

Where do the repeated peaks come from?

For  $\mathcal{S} = A \otimes I_n + I_n \otimes A \in \mathbb{R}^{n^2 \times n^2}$  :

$$x_t := (\mathcal{S}^{-1})_{:,t} = \mathcal{S}^{-1}e_t \quad \Leftrightarrow \quad \text{Solve : } \mathcal{S}\mathbf{x}_t = e_t$$

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Let

$\mathbf{X}_t \in \mathbb{R}^{n \times n}$  be such that  $\mathbf{x}_t = \text{vec}(\mathbf{X}_t)$

$E_t \in \mathbb{R}^{n \times n}$  be such that  $e_t = \text{vec}(E_t)$

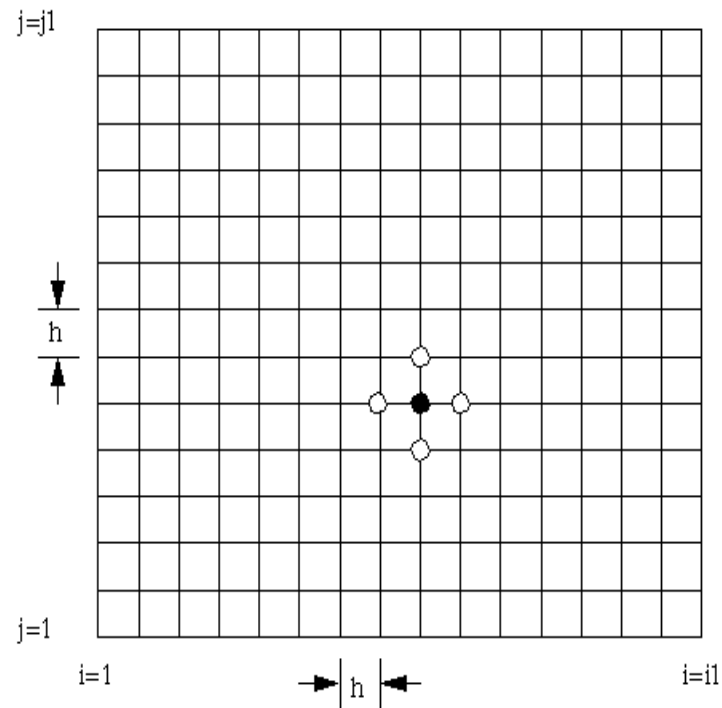
Then

$$\mathcal{S}\mathbf{x}_t = e_t \quad \Leftrightarrow \quad A\mathbf{X}_t + \mathbf{X}_tA = E_t$$

## The Poisson equation - revisited

$$-u_{xx} - u_{yy} = f, \quad \text{in } \Omega = (0, 1)^2$$

+ Dirichlet b.c. (zero b.c. for simplicity)



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**FD Discretization:**  $U_{i,j} \approx u_{x_i, y_j}$ , with  $(x_i, y_j)$  interior nodes, so that

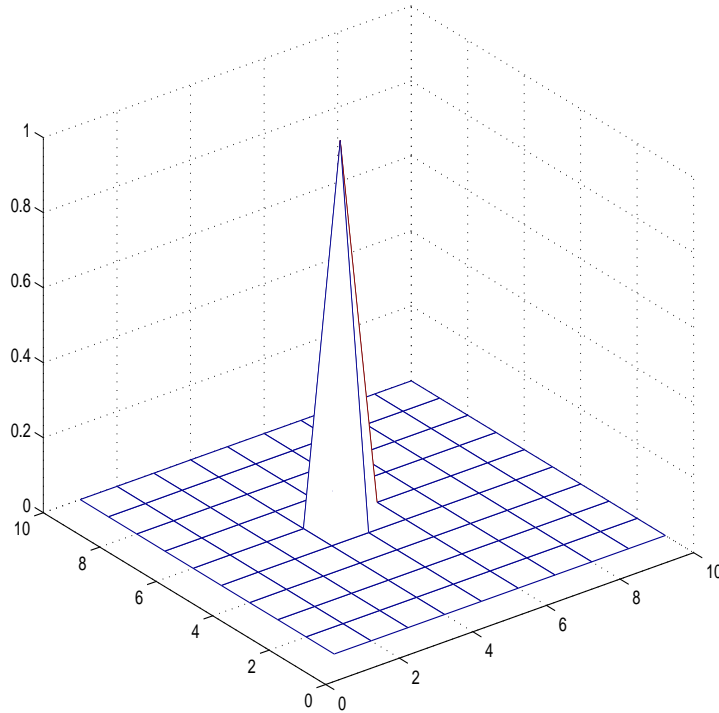
$$u_{xx}(x_i, y_j) \approx \frac{U_{i-1,j} - 2U_{i,j} + U_{i+1,j}}{h^2} = \frac{1}{h^2} [1, -2, 1] \begin{bmatrix} U_{i-1,j} \\ U_{i,j} \\ U_{i+1,j} \end{bmatrix}$$

$$u_{yy}(x_i, y_j) \approx \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{h^2} = \frac{1}{h^2} [U_{i,j-1}, U_{i,j}, U_{i,j+1}] \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$\mathbf{A}\mathbf{U} + \mathbf{U}\mathbf{A} = \mathbf{F}, \quad F_{ij} = f(x_i, y_j)$$

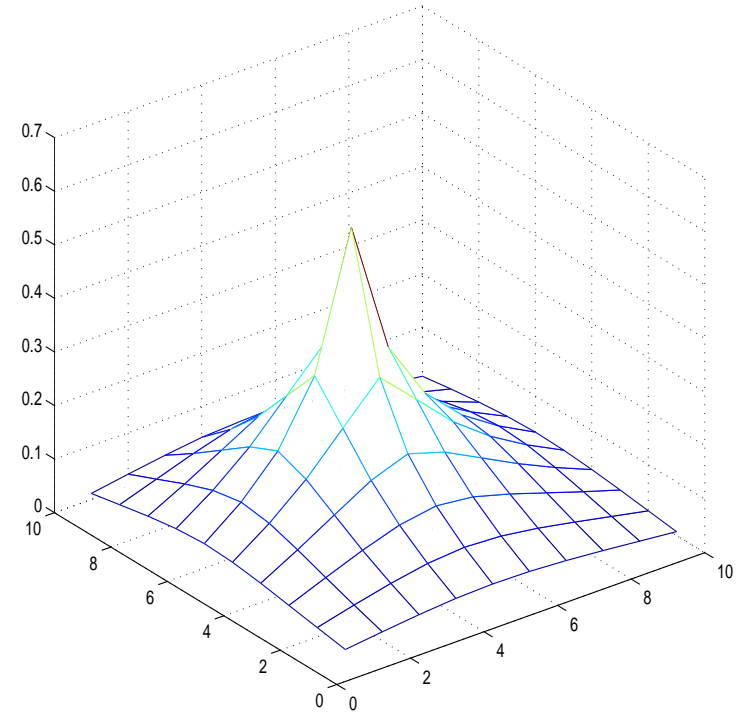
For  $\mathcal{S}$  the 2D Laplace operator,  $t = 1, \dots, n^2$

$$t = 35, \quad \mathcal{S}\mathbf{x}_t = e_t \quad \Leftrightarrow \quad A\mathbf{X}_t + \mathbf{X}_t A = E_t$$



matrix  $E_t$

and

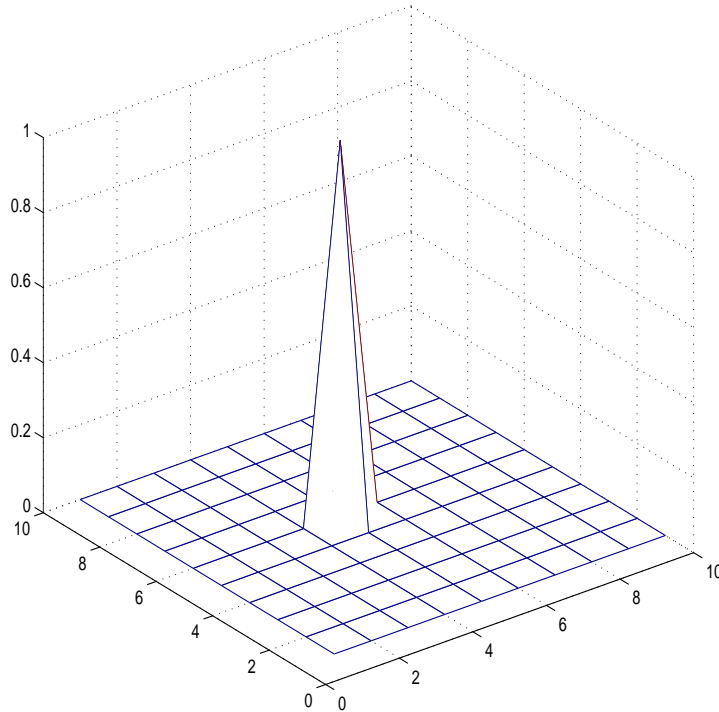


matrix  $\mathbf{X}_t$



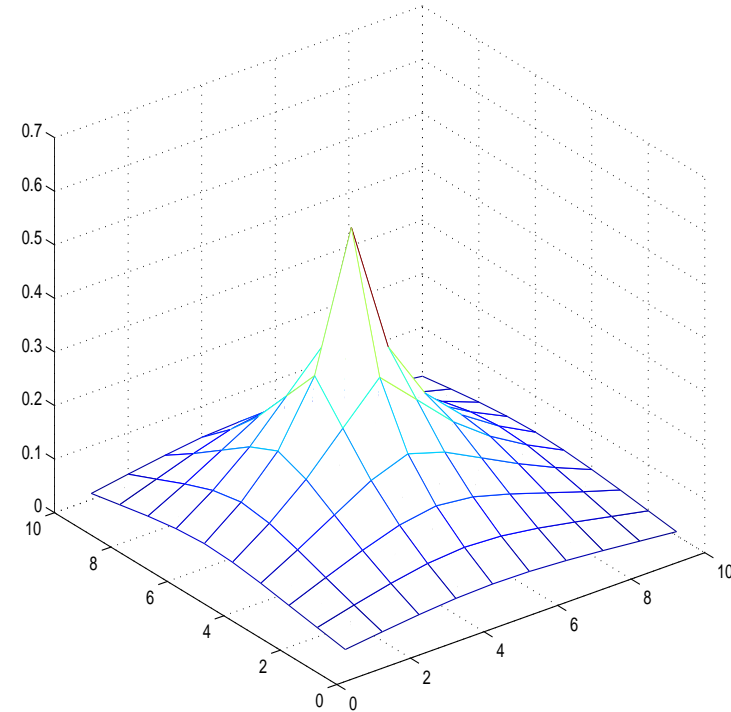
For  $S$  the 2D Laplace operator,  $t = 1, \dots, n^2$

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matrix  $E_t$

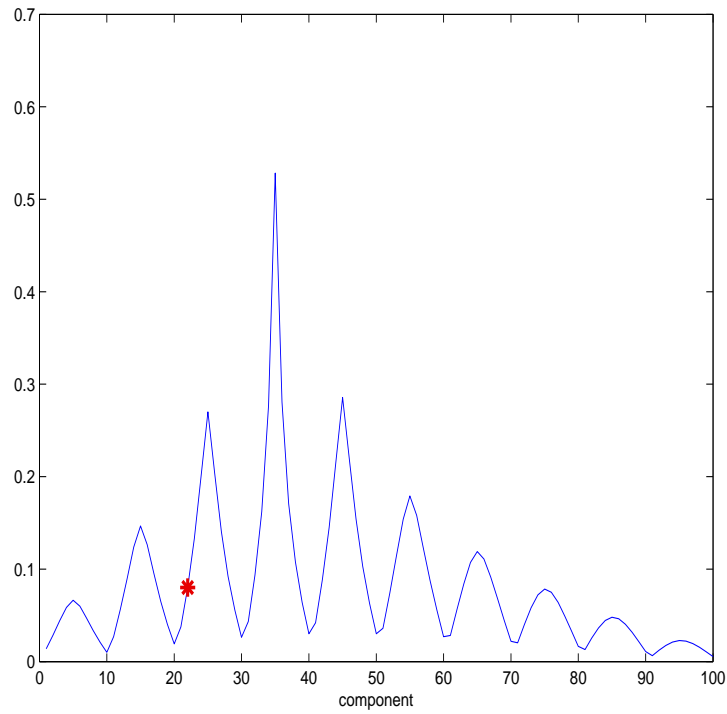
and



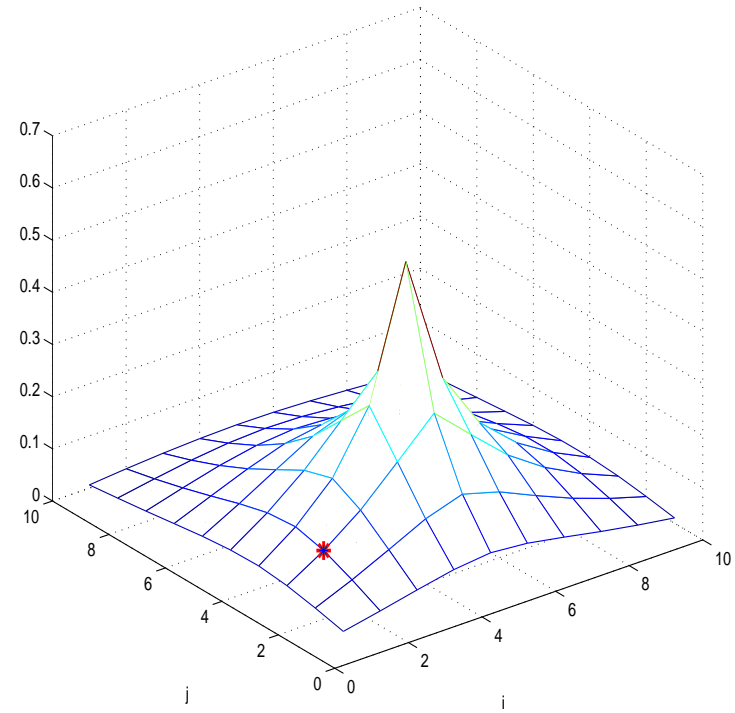
matrix  $\mathbf{X}_t$

$E_t$  has only one nonzero element

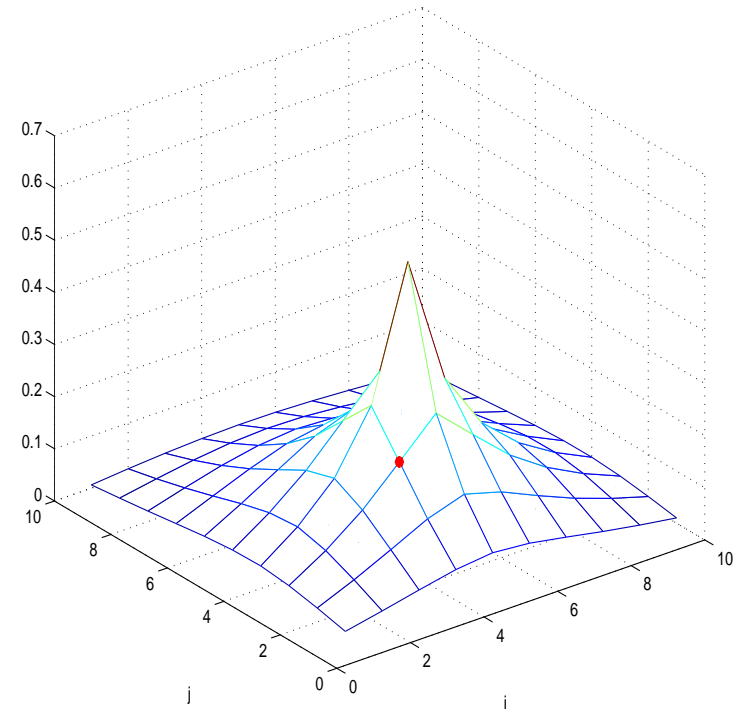
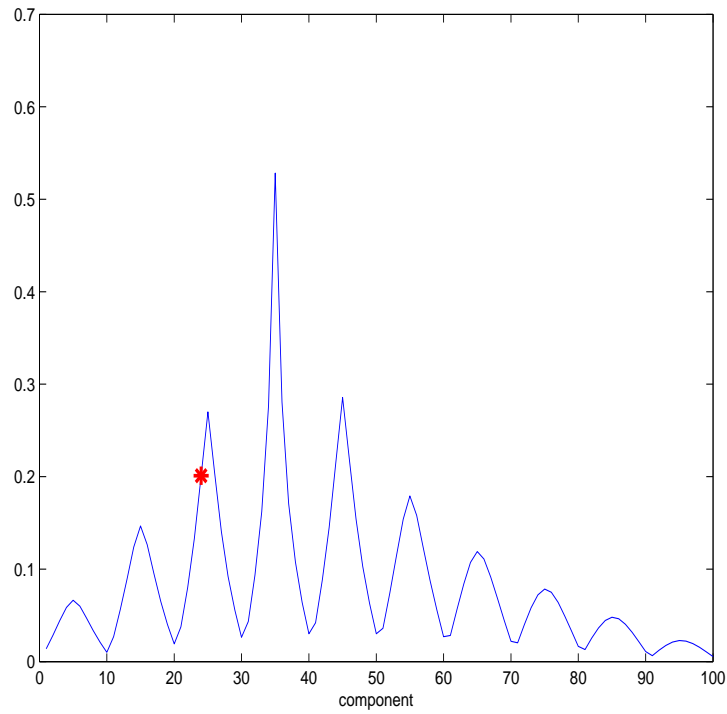
Lexicographic order:  $(E_t)_{ij}$ ,  $j = \lfloor (t-1)/n \rfloor + 1$ ,  $i = tn \lfloor (t-1)/n \rfloor$



Left: Row of  $\mathcal{S}^{-1}$

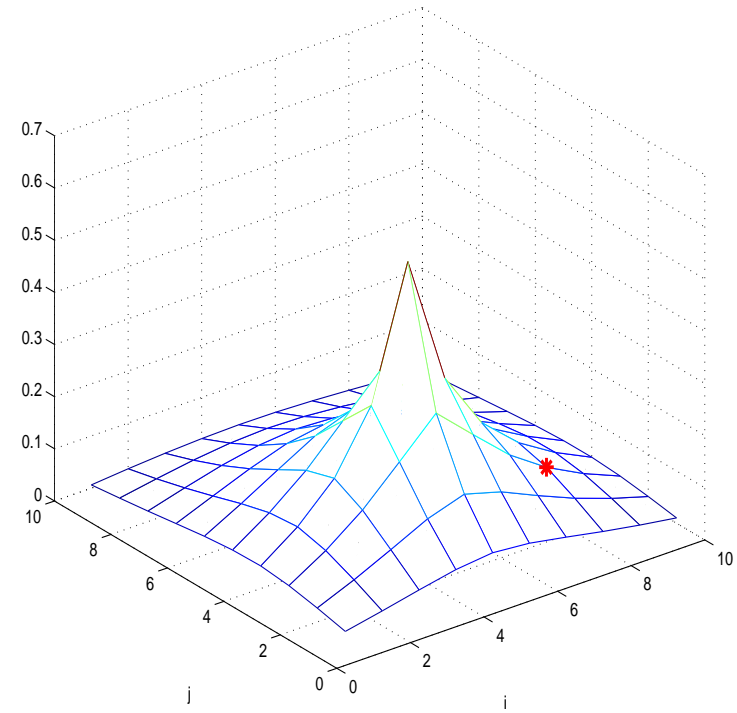
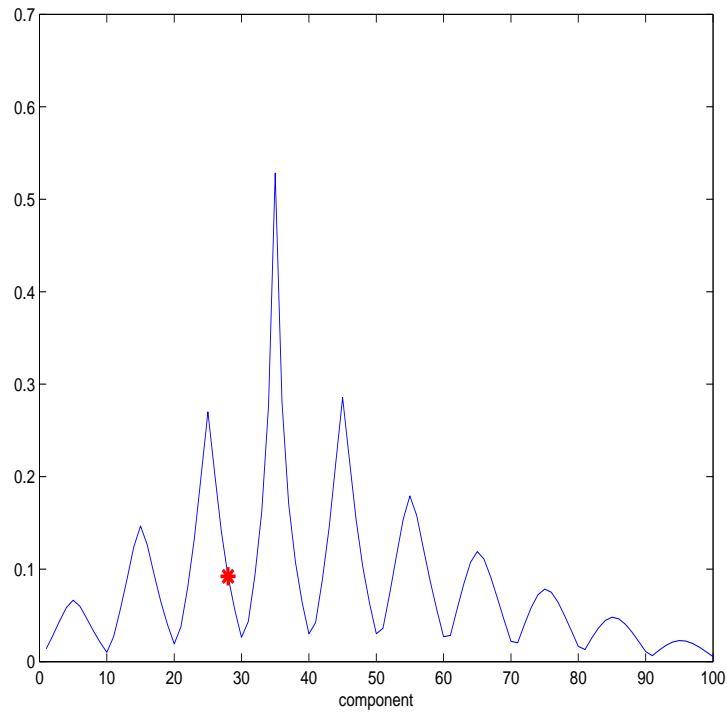


Right: same row on the grid



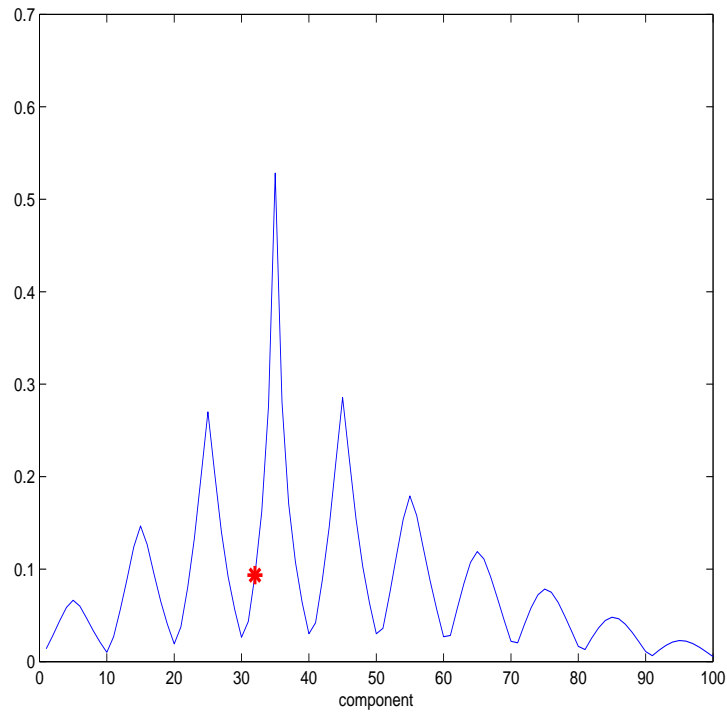
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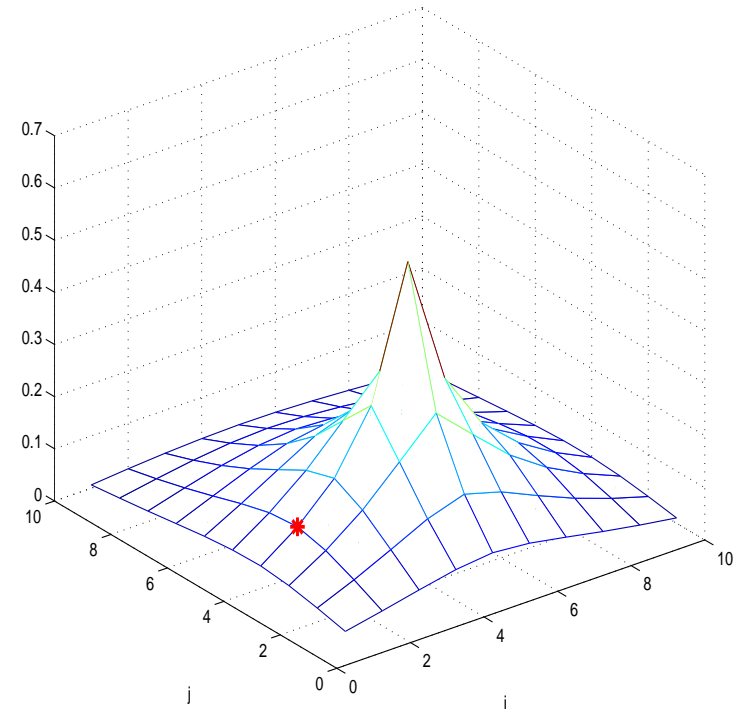


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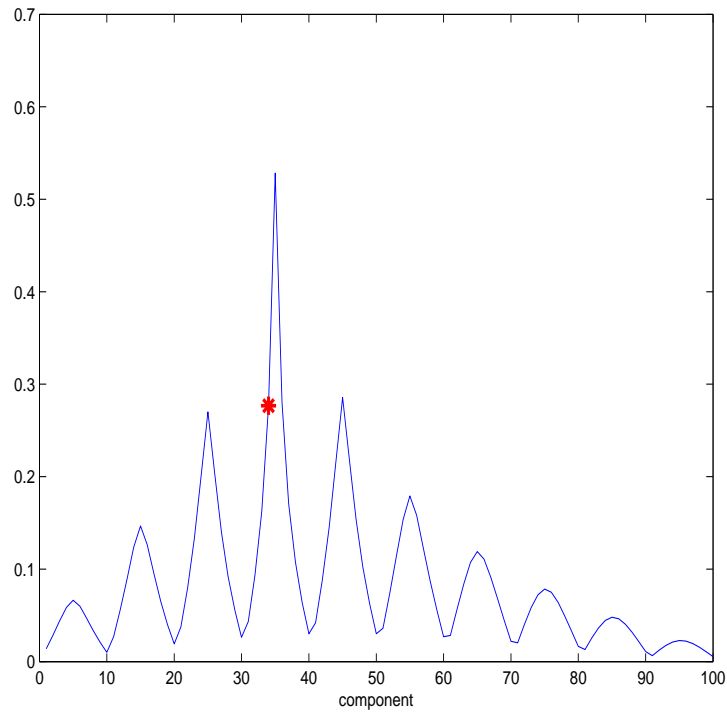
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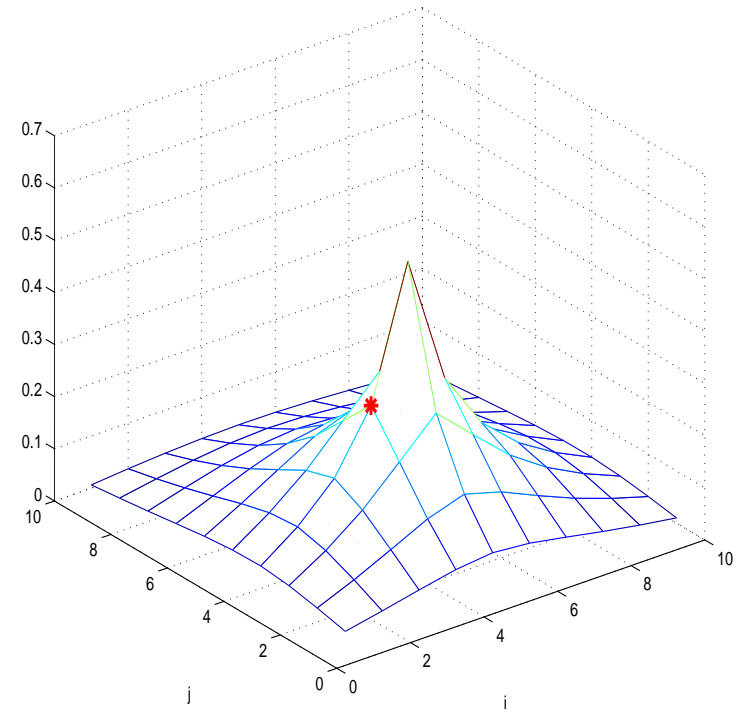
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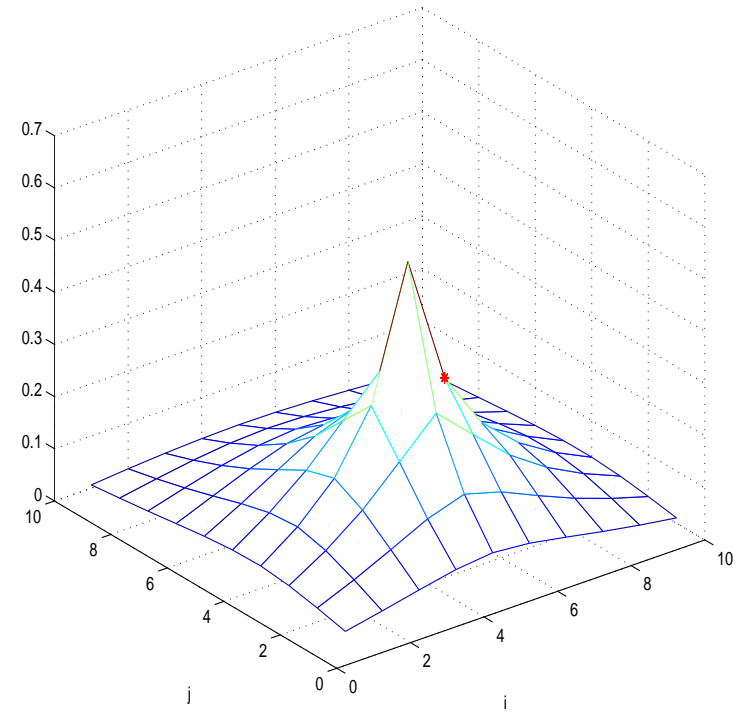
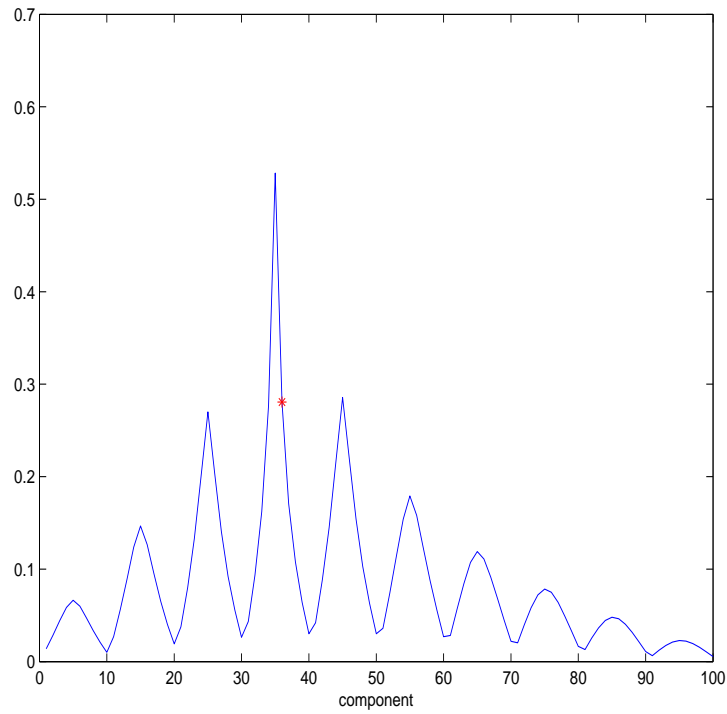
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## Qualitative bounds (more general than for the Laplacian!)

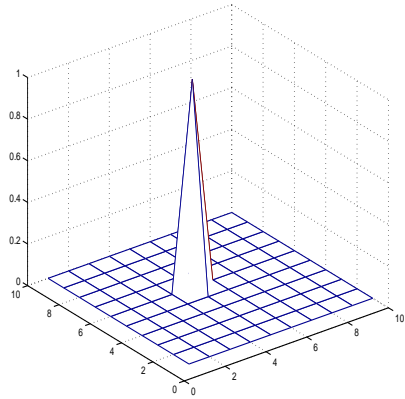
Let  $\kappa = \lambda_{\max}/\lambda_{\min} = \text{cond}(A)$

i) Assume  $\ell, i, m, j : \ell \neq i, m \neq j$ .  $\mathbf{n}_2 := |\ell - i| + |m - j| - 2 > 0$

$$|(\mathcal{S}^{-1})_{k,t}| \leq \frac{\sqrt{\kappa^2 + 1}}{2\lambda_{\min}} \frac{1}{\sqrt{\mathbf{n}_2}}.$$

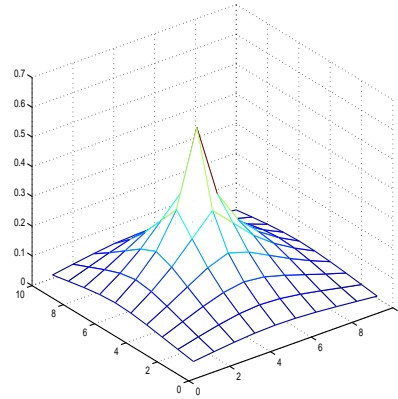
ii) Assume  $\ell, i, m, j : \ell = i$  or  $m = j$ .  $\mathbf{n}_1 := |\ell - i| + |m - j| - 1 > 0$

$$|(\mathcal{S}^{-1})_{k,t}| \leq \frac{\kappa\sqrt{\kappa^2 + 1}}{2} \frac{1}{\sqrt{\mathbf{n}_1}}.$$



$(i, j)$

and

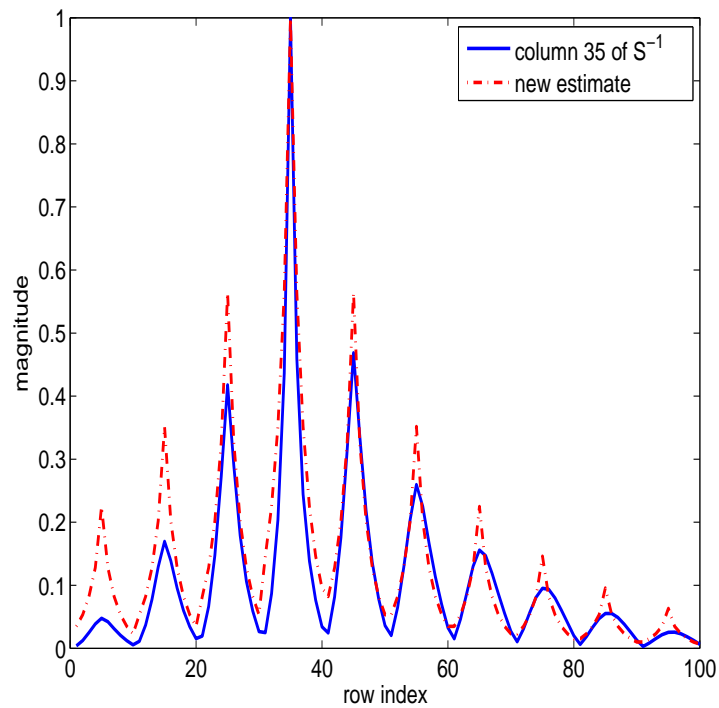


$(\ell, m)$



Example. Legendre stiffness matrix (scaled to have unit peak)

$$A = \text{tridiag}(\delta_k, \underline{\gamma_k}, \delta_k)$$



$$\gamma_k = \frac{2}{(4k - 3)(4k + 1)}$$

$$k = 1, \dots, n, \quad \text{and}$$

$$\delta_k = \frac{-1}{(4k + 1)\sqrt{(4k - 1)(4k + 3)}}$$

$$k = 1, \dots, n - 1$$

Canuto, Simoncini, Verani 2014

## Connections to point-wise estimates for discrete Laplacian

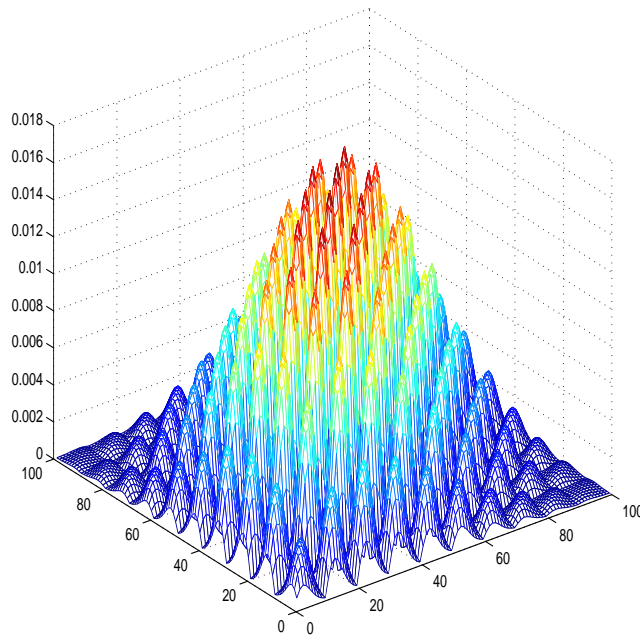
For the discrete Green function  $G_h$  on the discrete  $d$ -dimensional grid  $R_h$ , there exist constants  $h_0$  and  $C$  such that for  $h \leq h_0$ ,  $x, y \in R_h$ ,

$$G_h(x, y) \leq \begin{cases} C \log \frac{C}{|x-y|+h} & \text{if } d = 2 \\ \frac{C}{(|x-y|+h)^{d-2}} & \text{if } d \geq 3 \end{cases}$$

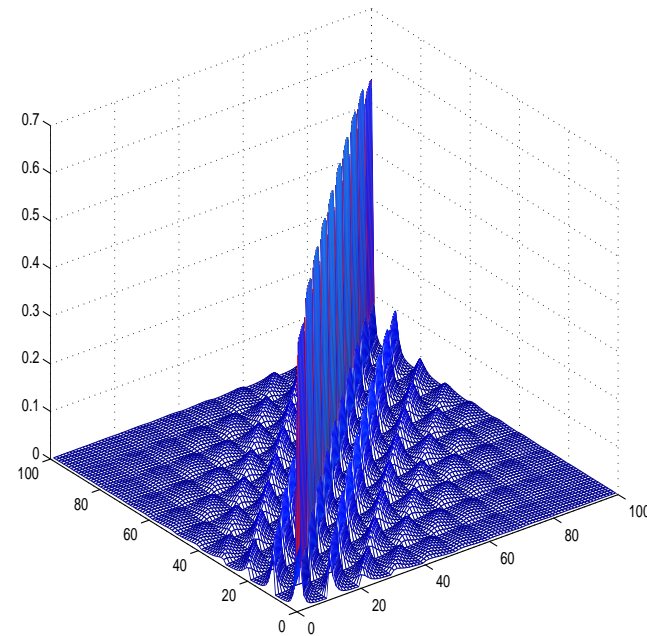
(Bramble & Thomee, '69)

Our estimate: entries depend on inverse square root of the distance!

Typical decay plot for  $f(\mathcal{S})$ , with  $\mathcal{S}$  Laplace operator as before



$$f(\mathcal{S}) = e^{-5\mathcal{S}}$$



$$f(\mathcal{S}) = \mathcal{S}^{-\frac{1}{2}}$$

(Bounds for Laplace or Stieltjes functions)

In general,  $\mathcal{S} = A_1 \oplus A_2 := A_1 \otimes I + I \otimes A_2$ ,  $A_1, A_2$  banded spd

Benzi, Simoncini 2015

## Generalizations

- Three-dimensional case
- (banded) Non-symmetric matrices
- “Quasi” Kronecker structure
- Numerical solution of PDEs on structured grids

$$-\Delta u = 1, \quad \Omega = (0, 1)^3 \quad \Rightarrow \quad \mathcal{S} = (A \otimes I \otimes I + I \otimes A \otimes I + I \otimes I \otimes A)$$

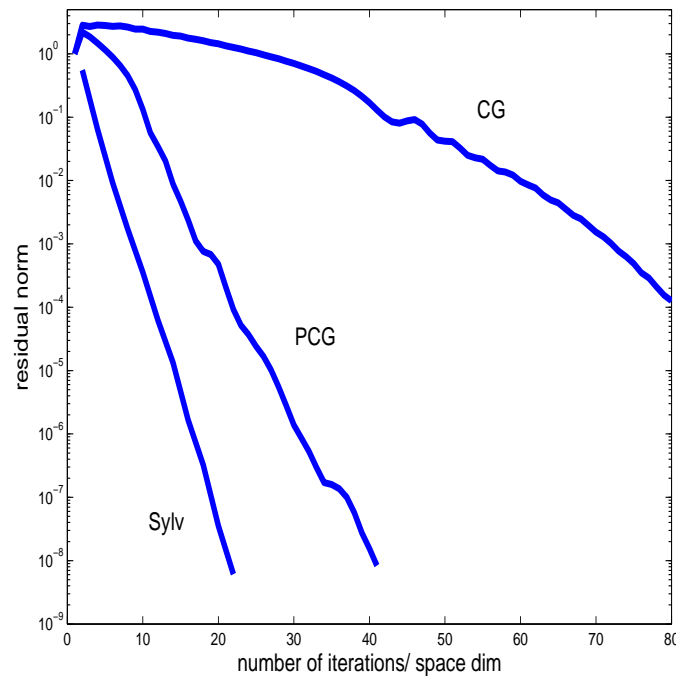
CG for  $\mathcal{S}x = b$  vs Iterative solver for  $(I \otimes A + A \otimes I)U + UA = F$

$$A \in \mathbb{R}^{n \times n}, \quad \mathcal{S} \in \mathbb{R}^{n^3 \times n^3}, \quad n = 50$$

$$-\Delta u = 1, \quad \Omega = (0, 1)^3 \quad \Rightarrow \quad \mathcal{S} = (A \otimes I \otimes I + I \otimes A \otimes I + I \otimes I \otimes A)$$

CG for  $\mathcal{S}x = b$  vs Iterative solver for  $(I \otimes A + A \otimes I)U + UA = F$

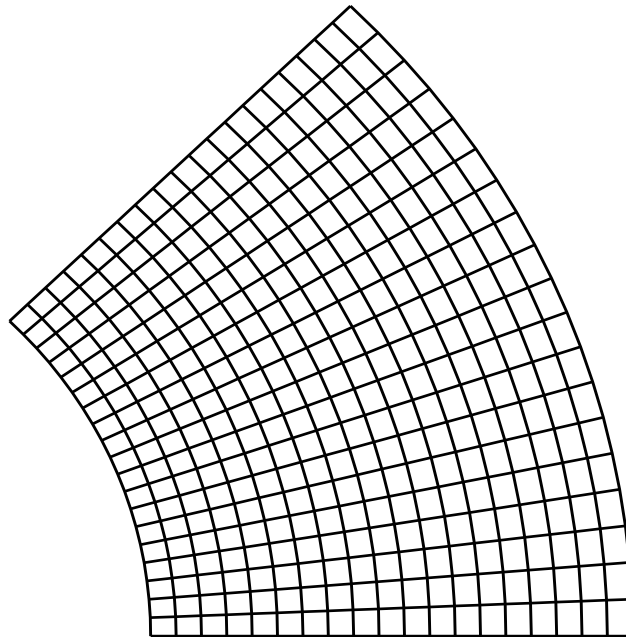
$$A \in \mathbb{R}^{n \times n}, \quad \mathcal{S} \in \mathbb{R}^{n^3 \times n^3}, \quad n = 50$$



	CG	PCG	Matrix Eqn solver
Comput. Time	2.91	0.56	0.08

## Generalizations. Solutions to PDEs

$$-u_{xx} - u_{yy} = f, \quad (x, y) \in \Omega$$

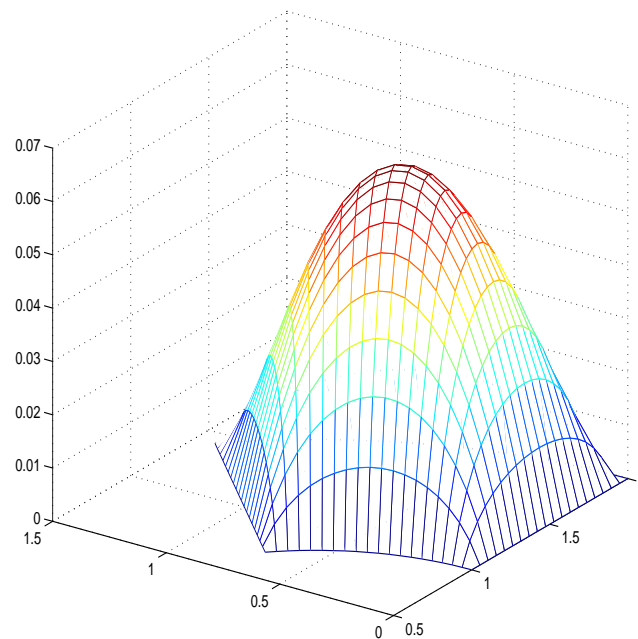


In polar coordinates  $(r, \theta)$ :  $-u_{rr} - \frac{1}{r}u_r - u_{\theta\theta} = \tilde{f}$

$$\Rightarrow A_1 \mathbf{X} + \mathbf{X} A_2 = F$$

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$$-u_{xx} - u_{yy} = f, \quad (x, y) \in \Omega$$



In polar coordinates  $(r, \theta)$ :  $-u_{rr} - \frac{1}{r}u_r - u_{\theta\theta} = \tilde{f}$

$$\Rightarrow \mathbf{A}_1 \mathbf{X} + \mathbf{X} \mathbf{A}_2 = F$$



# Structured grids

## Applications

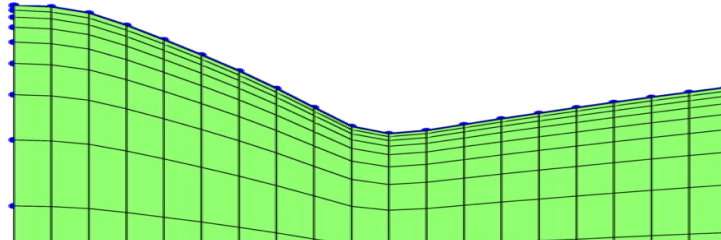
- Computational Aero- and Fluid-Dynamics
- Semiconductor devices
- Object modelling
- Parallel computation
- ...

## Classical strategies (building blocks)

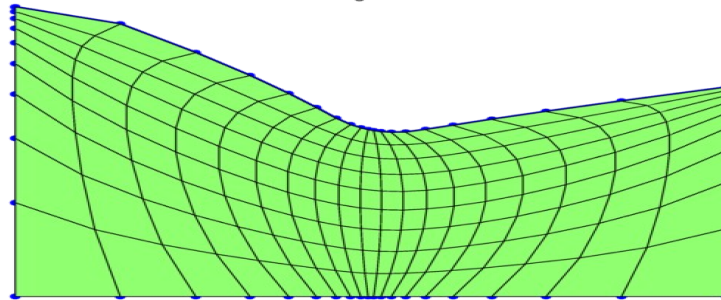
- Conformal mappings (Boundary-fitted curvilinear coord.)
- Algebraic grid generators (Transfinite interpolation)
- Elliptic, hyperbolic grids with controls
- Variational methods
- ...

## Grid generation. An example

Grid generated using transfinite interpolation  
top/bottom grid ratio=0.05



Grid generated using PDE method  
top/bottom grid ratio=0.05  
middle/left grid ratio=0.05



(grids from <http://www.math.fsu.edu/okhanmoh/research.html>)

## Conclusions

- Matrix equations have very broad applicability  
(structure recurrent in many application problems...)
- Recent appropriate computational devices
- Important tool for matrix sparsity analysis

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